

User Guide

Trimble® CFX-750™ Display

Version 5.0
Revision A
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Legal Notices

Agriculture Business Area

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Version 2.1, February 1999

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If such an object file uses only numerical parameters, data structure layouts and accessors, and small macros and small inline functions (ten lines or less in length), then the use of the object file is unrestricted, regardless of whether it is legally a derivative work. (Executables containing this object code plus portions of the Library will still fall under Section 6.)

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To receive information regarding updates and new products, please contact your local dealer or visit the Trimble website at www.trimble.com/register. Upon registration you may select the newsletter, upgrade, or new product information you desire.

Notices

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at his own expense.

Properly shielded and grounded cables and connectors must be used in order to meet FCC emission limits. TRIMBLE is not responsible for any radio or television interference caused by using other than recommended cables and connectors or by unauthorized changes or modifications to this equipment. Unauthorized changes or modifications could void the user's authority to operate the equipment.

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:

(1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Responsible Party:

Trimble Navigation
935 Stewart Drive
Sunnyvale CA 94085
Telephone: 1-408 481 8000

Canada

This Class B digital apparatus complies with Canadian ICES-003. Cet appareil numérique de la classe B est conforme à la norme NMB-003 du Canada.

This apparatus complies with Canadian RSS-GEN, RSS-310, RSS-210, and RSS-119.

Cet appareil est conforme à la norme CNR-GEN, CNR-310, CNR-210, et CNR-119 du Canada.

Australia and New Zealand Class A Statement

Attention: This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

Australia and New Zealand

This product conforms with the regulatory requirements of the Australian Communications Authority (ACA) EMC framework, thus satisfying the requirements for C-Tick Marking and sale within Australia and New Zealand.



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For product recycling instructions and more information, please go to www.trimble.com/ev.shtml.

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Trimble Europe BV
c/o Menlo Worldwide Logistics
Meerheide 45
5521 DZ Eersel, NL

Safety Information

Always follow the instructions that accompany a Warning or Caution. The information they provide is intended to minimize the risk of personal injury and/or damage to property. In particular, observe safety instructions that are presented in the following format:

 **WARNING** – This alert warns of a potential hazard which, if not avoided, can cause severe injury.

 **CAUTION** – This alert warns of a hazard or unsafe practice which, if not avoided, can cause injury or damage.

Note – An absence of specific alerts does not mean that there are no safety risks involved.

Warnings

 **WARNING** – Anhydrous ammonia (NH₃) can cause severe burning, blindness, or death. Before you begin to operate or service equipment that contains NH₃, carefully read and follow all safety instructions in [Working with anhydrous ammonia, page 7](#).

 **WARNING** – Incorrect adjustment of the Manual Override Sensitivity calibration setting could cause this critical safety feature to fail, resulting in personal injury or damage to the vehicle. Any adjustment to this setting should only be made by an experienced user.

 **WARNING** – During the Deadzone calibration, the system moves the vehicle's steering wheels. To avoid injury, be prepared for sudden vehicle movement.

 **WARNING** – When you tap the liquid flow calibration **Start** button, the machine will become operational. Take all necessary precautions to ensure user safety. Failure to do so may result in serious injury or death.

 **WARNING** – When you tap the control valve calibration **Start** button, the machine will become operational. Take all necessary precautions to ensure user safety. Failure to do so may result in serious injury or death.

 **WARNING** – When you tap the fill disk **Start** button, the machine becomes operational. Take all necessary precautions to ensure user safety. Failure to do so may result in serious injury or death.

 **WARNING** – When the implement is down and the master switch is in the On position, the machine is fully operational. Take all necessary precautions to ensure user safety. Failure to do so could result in injury or death.

-
-  **WARNING** – The display contains a single-use Lithium-sulfide LiSO^2 battery. Do not expose the battery to temperatures greater than 71 °C (160 °F) as the battery may explode.
-
-  **WARNING – MOVING PARTS DURING THIS TEST!** Please stay clear of the implement. Ensure the implement is raised, the transmission is in PARK, and the emergency brake is applied before continuing.
-
-  **WARNING** – Many large and sudden change in satellite geometry caused by blocked satellites can cause significant position shifts. If operating under these conditions, auto-guidance systems can react abruptly. To avoid possible injury or damage to property under these conditions, disable the auto-guidance system and take manual control of the vehicle until the conditions have cleared.
-
-  **WARNING** – Obstacles in the field can cause collisions, which may injure you and damage your vehicle. If an obstacle in the field makes it unsafe to continue a particular phase of the automated dead-zone calibration, stop the vehicle to abort the phase and turn the steering wheel to disengage the system. Reposition the vehicle and continue from the current test phase.
-
-  **WARNING** – The wheels can move abruptly during the Steering Proportional Gain procedure while the Autopilot system tests the hydraulic response to its steering commands. To avoid injury, be prepared for vehicle movement.
-

Working with anhydrous ammonia

- Contact your NH_3 supplier to review all safety requirements associated with anhydrous ammonia (NH_3).
- Always wear correct personal protective equipment. This includes, but is not limited to:
 - Goggles or face shield
 - Protective suit and gloves
 - Respirator
- **Do not** allow anyone to operate the system without proper instruction and training.
- Stand up-wind when working around NH_3 and related equipment.
- Always keep NH_3 equipment away from buildings, livestock, and other people.
- Never work on NH_3 equipment in confined spaces.
- Before you attempt to transport the implement, discharge the system of all NH_3 and completely shut down the system. See [Discharging the system, page 8](#).
- If symptoms of illness occur during or shortly after use of NH_3 products, seek immediate medical attention.

- Keep a source of clean water (at least five gallons) readily available. In case of exposure, flush exposed skin or eyes immediately with large quantities of water and seek immediate medical attention.
- NH₃ can be harmful to the environment if not used correctly. Follow all local, state, and federal regulations regarding proper handling of this chemical.

Servicing the equipment

1. Remove the system from operation before performing any maintenance.
2. Thoroughly bleed all system lines and disconnect the nurse tank hose. See [Discharging the system, page 8](#).
3. Make sure that the gauge pressure is at zero before you open the system.
4. Use extreme caution when opening a previously pressurized system.

Discharging the system

1. Turn off the console or vehicle master switch.
2. Completely close the main shut-off valve on the supply or nurse tank.
3. Resume field application until the pressure gauge shows zero pressure.
4. Check again that the console and/or vehicle master switch, and all section switches, are turned off.
5. Completely close the emergency shut-off valve the cooling tower.
6. Bleed and disconnect the nurse tank supply hose from the system.
7. Turn on the console master switch and all section switches.
8. Stand up-wind from the implement and then slowly open the bleed valve(s) until fully open.
9. Allow at least one (1) hour for the system to fully discharge.
10. Before you open the system, make sure that the pressure gauge on the manifold reads zero and that the cooling tower is not cold to the touch. This ensures that all liquid NH₃ has evaporated and that the pressure is discharged.

Note – Frost on any component is a positive indication of trapped NH₃ at low pressure. Lack of frost does not always indicate a lack of NH₃.

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Introduction

This manual describes how to install, configure, and use the Trimble® CFX-750™ display, version 5.0.

Even if you have used other Global Navigation Satellite Systems (GNSS) or application control products before, such as the United States' Global Positioning System (GPS) products, it is recommended that you spend some time reading this manual to learn about the special features of this product. If you are not familiar with GNSS, visit the Trimble website (www.trimble.com) for an interactive look at Trimble and GNSS.

About the CFX-750 display

The Trimble CFX-750 display is an in-cab touchscreen display that provides affordable guidance, steering and precision agriculture functionality.

The CFX-750 display includes a built-in GPS receiver that you can upgrade to receive GLONASS satellite signals. The display can also use an array of components to maximize efficiency when planting, spraying, spreading and strip tilling, including the Trimble Field-IQ™ crop input control system.

Related information

Sources of related information include the following:

- Release notes: The release notes describe new features of the product, information not included in the manuals, and any changes to the manuals. The release notes are available at www.trimble.com.
- Trimble training courses: Consider a training course to help you use your GPS system to its fullest potential. For more information, go to the Trimble website at www.trimble.com/training.html.

Technical assistance

Contact your Trimble Reseller for technical assistance.

Installing the Display and Antenna

In this chapter:

- [System components](#)
- [Installing the display](#)
- [Connecting the display](#)
- [Installing the antenna](#)

This chapter introduces the CFX-750 display and system components, and also describes how to install the display and antenna.

System components



Item	Description	Part number
❶	CFX-750 display	94110-00
❷	RAM mount and screws	61958
❸	Quick reference card	78838-00-ENG
❹	Compact disc	78821-02
❺	GPS antenna cable	50449
❻	Power bus/CAN cable	77282
❼	Power cable	67258-01
❽	AG-25 antenna	77038
❾	AG-25 antenna mount plate	62034

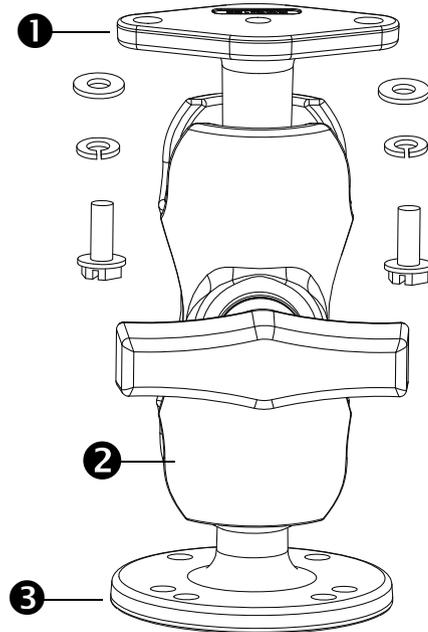
Installing the display

Mount the CFX-750 display in the vehicle cab. When you position the display, make sure that:

- it is within the driver’s reach so that the USB drive is easy to remove and replace.
- the touchscreen is easy to see, but the display does not block the driver’s view.
- it does not interfere with the driver getting in or out of the cab, or any other activities.

The image shows the mounting assembly for the display:

Item	Description
❶	Diamond-shaped mounting plate
❷	RAM mount
❸	Bar mount



To install the display:

1. Use the supplied screws to firmly attach the diamond-shaped mounting plate to the back of the display:



2. Attach the RAM mount to the ball on the diamond-shaped mounting plate:



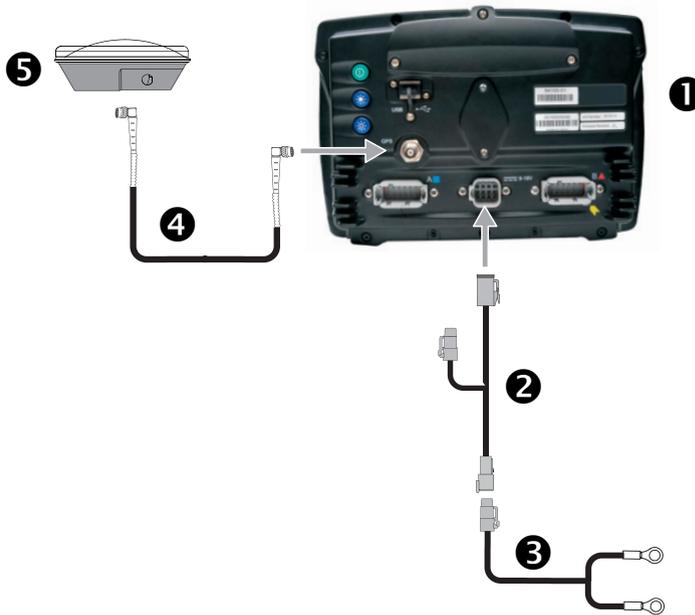
3. Select a position in the cab for the display. Hold the display in the selected location and check that it is easily accessible from the driver's seat.
4. Use the provided bolts to attach the bar mount to the cab.
5. Attach the other end of the RAM mount to the ball on the bar mount and then tighten the screw.

Connecting the display

The diagrams in this section show how to set up the CFX-750 display as a standalone system.

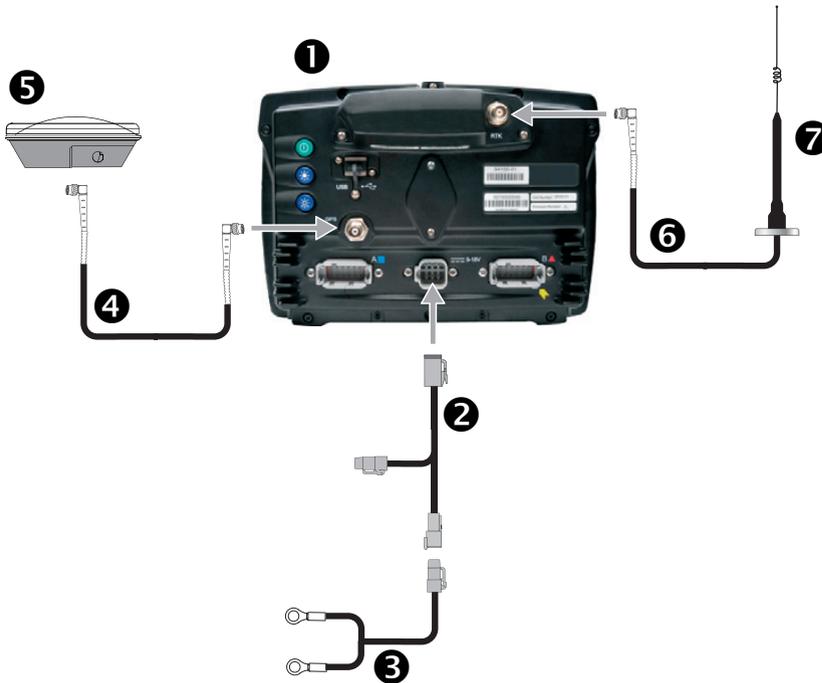
To learn how to connect the CFX-750 display to other the system components, see the *CFX-750 Display Cabling Guide*.

Connecting a standalone CFX-750 display for WAAS/EGNOS/OmniSTAR® XP/HP corrections



Item	Description	Trimble part number
1	CFX-750 display	94110-00
2	CFX-750 power cable	77282
3	CFX-750 basic power cable	67258-01
4	8 m GPS TNC/TNC RT angle cable	50449
5	AG-25 GNSS antenna	77038

Connecting a standalone CFX-750 display for RTK corrections



Item	Description	Trimble part number
1	CFX-750 display <i>Note – RTK password required.</i>	94110-00
2	CFX-750 power cable	77282
3	CFX-750 basic power cable	67258-01
4	8 m GPS TNC/TNC RT angle cable	50449
5	AG-25 GNSS antenna	77038
6	NMO-to-TNC 20 ft antenna cable and base	62120
7	900 MHz radio antenna kit	22882-10

Installing the antenna

Note – To minimize any interference to the GPS signal, make sure that the GPS antenna is at least 1 m (3 ft) from any other antenna (including a radio antenna). You may experience interference if you operate the vehicle within 100 m (300 ft) of any power line, radar dish, or cell phone tower.

Note – The AG-25 antenna has integrated magnets for easy installation. To attach the antenna to a non-metal surface, you must use the mounting plate.

1. Find the mounting location for the antenna at the front of the vehicle roof, centered from left to right.
2. On the mounting plate, remove the protective covers from the adhesive strips.
3. Attach the mounting plate to the vehicle roof with the adhesive strips. Ensure that the mounting plate is centered along the vehicle roof.
4. Connect the antenna cable to the antenna.
5. Place the antenna directly on the mounting plate. The three magnets embedded in the bottom of the antenna will hold it in place.
6. Route the other end of the antenna cable into the cab.

Getting Started

In this chapter:

- Display basics
- The Quick Start Wizard
- Using the setup wizards
- The guidance screen
- Using the EZ-Remote joystick
- Reading lightbar patterns
- On-screen icons

This chapter describes, in general terms, how to use the CFX-750 display.

Display basics

The CFX-750 display provides guidance, steering and precision agriculture functionality. The display has a touchscreen that you use to operate your system and to view guidance information. In addition, there is a USB port on the display for loading and saving field data.

Front view



Item	Description	Notes
❶	8" Touch-sensitive screen	To interact with the system, tap the screen with your finger. For more information, see Recalibrate touchscreen, page 244 .
❷	Speaker	You can adjust the speaker volume, or turn it off. For more information, see Touchscreen speaker volume, page 233 .
❸	Integrated lightbar with 27 LEDs	When lit, the LEDs show the position of your vehicle relative to your intended guidance line. For more information, see Reading lightbar patterns, page 37 .



CAUTION – Do not press on the screen with a sharp item, such as a pencil or screwdriver; you may damage the surface of the screen.

Back view



Item	Description	Notes
1	Power button	Turns the display on or off.
2 and 3	Brightness controls	<ul style="list-style-type: none"> To increase the brightness of the screen, press 2. To decrease the brightness, press 3. <p>Note – You can also use the <i>Color Scheme</i> and <i>Backlight</i> menu options to set the screen brightness. See <i>Color Scheme</i>, page 232, and <i>Backlight</i>, page 233.</p>
4	USB socket	You can connect a USB memory stick to the display to transfer data to and from the unit. For more information, see The USB socket , page 27.
5	GPS connector	Connects the GPS cable (P/N 50449) to the display.
6	Port A	Connects external devices to the display.
7	Power connection socket	Connects the power cable (P/N 67258) to the display.
8	Port B	Connects external devices to the display.
9	Radio access panel	If you purchase the optional RTK module, install the module here. For more information, see the installation instructions supplied with the radio module.

Cleaning the touchscreen

To clean the CFX-750 display use the following supplies:

- Ammonia-free glass cleaner

Note – Do not apply glass cleaner directly to the touchscreen.

- Soft, lint-free cotton cloth
 - 50% isopropyl alcohol
1. Apply a small amount of glass cleaner to the cloth and gently rub it against the touchscreen.
 2. To clean off any stains or smudges, use a cotton cloth dampened with 50% isopropyl alcohol.

 **Tip** – Clean the display while it is switched off. It is easier to see dirt and fingerprints when the touchscreen is dark.

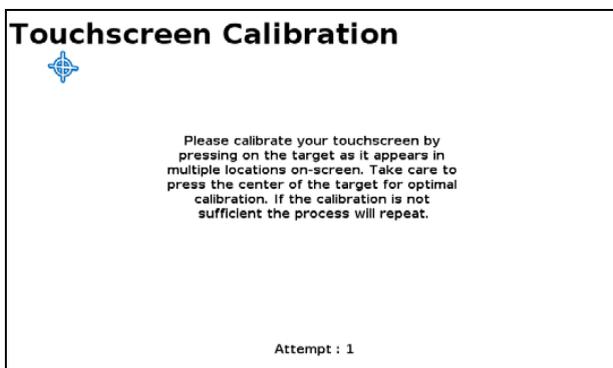
Power up

To turn on the display, press the power button on the rear of the display. After a short time, the *Welcome* screen appears:



The first time that you turn on the CFX-750 display, the following wizards appear in turn:

- Touchscreen calibration:

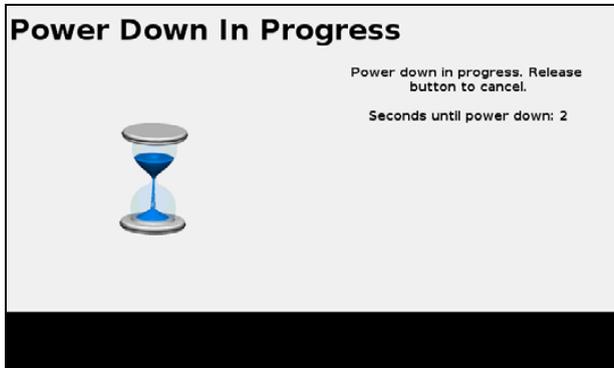


You must calibrate the touchscreen before you can use the display; to do this, follow the onscreen instructions.

- The Quick Start wizard. To configure your system properly, make sure that you run the entire wizard, see [page 29](#).

Power down

To turn off the CFX-750 display, hold down the power button for three seconds. While holding down the power button, the *Power Down In Progress* screen appears:



Note – To cancel the power down process, release the power button before the three second countdown is complete.

Resetting the display

Occasionally, you may want to reset the display settings. There are two ways to do this:

- **Soft reset:** This returns all settings to the factory defaults. All saved field data remains intact.
- **Hard reset:** This returns all settings to the factory defaults, **and** deletes all saved data including any field data.

Note – Do not perform a hard reset unless it is absolutely necessary or you are instructed to do so by Trimble Technical Support.

Soft reset

1. Power down the display and then power it on.
2. Wait until the status bar at the bottom of the second startup screen is over half full:



3. Press the power button and **top** brightness control button at the same time:



4. Hold the buttons down until the display beeps.

Hard reset

1. Power down the display and then power it on.
2. Wait until the status bar at the bottom of the second startup screen is over half full:



3. Press the power button and **both** brightness control buttons at the same time:



4. Hold the buttons down until the display beeps.

The USB socket

The USB socket is on the rear of the display. See [Back view, page 24](#). Use the USB socket to manage your data via a USB drive.

USB drive compatibility

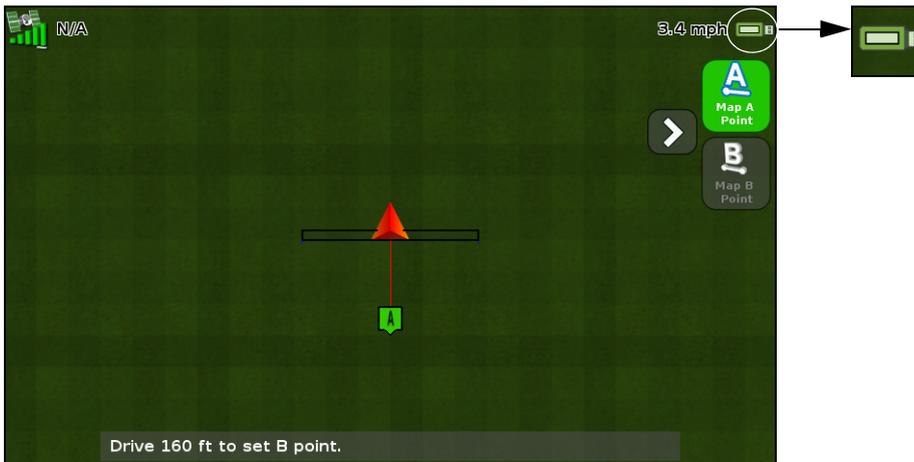
You can use the following USB drives with the CFX-750 display:

- A-Data micro SDHC/SD/USB adapter
- Digital Concepts USB to PC Reader
- Kingston Data Traveler 8 GB
- Lexar Firefly 1 GB
- Lexar Secure II Plus
- ADATA Classic C801 8 GB
- Generic USB - uDHC adapter with Transcend 8 GB microSDHC card
- Kingston Data Traveler 101
- Lexar JumpDrive TwistTurn
- PNY Attache

- PNY Micro Swivel Attache 4 GB
- PNY Mini Attache 8 GB
- SanDisk Cruzer Gator 4 GB
- Toshiba TransMemory U2M-004GTA 4 GB
- PNY Mini Attache 4 GB
- SanDisk Cruzer
- SanDisk Cruzer Micro 1 GB
- Transcend JetFlash

Inserting a USB drive

1. Rotate the display so you that can see the back of it.
2. Insert the USB drive into the USB socket. When the USB drive is inserted correctly, the USB icon appears on the guidance screen:



The color of the USB icon indicates the current state of the USB drive:

- Green: the USB drive is connected.
- Yellow: the USB drive is connecting.
- Red: the connection to the USB drive has been lost.

Removing a USB drive



CAUTION – Do not remove the USB drive from the socket while the display is writing to or from the drive. This will corrupt the data.

1. Rotate the display so that you can see the back of it.
2. Pull the USB drive out of the USB socket.

Taking a screenshot

Occasionally, you may want to save a screenshot of the touchscreen, for example to provide information for troubleshooting purposes. When you take a screenshot, the display saves a .png file to the root directory of the USB drive.

Note – Screenshot capability is available only when there is a USB drive inserted in the display.

To take a screenshot:

1. Press **both** brightness control buttons at the same time:



2. Hold the buttons down until the touchscreen flashes.



CAUTION – Do not remove the USB drive from the socket while the display is writing to or from the drive. This will corrupt the data.

The Quick Start Wizard

The Quick Start Wizard enables you to configure important settings before you begin driving. The first time that you turn on the display, the wizard starts automatically. Make sure that when you first turn on the display that you run the entire wizard.

When you run the wizard, you can choose whether or not it appears every time the display is turned on. If you choose to hide the wizard, the guidance screen will appear automatically when you turn the unit on again. However, you can still access the wizard at a later time, as follows:

1. Tap  and then tap .
2. Tap **Quick Start Wizard**. The *Welcome* screen appears.
3. Tap . The first page of the Quick Start Wizard appears:



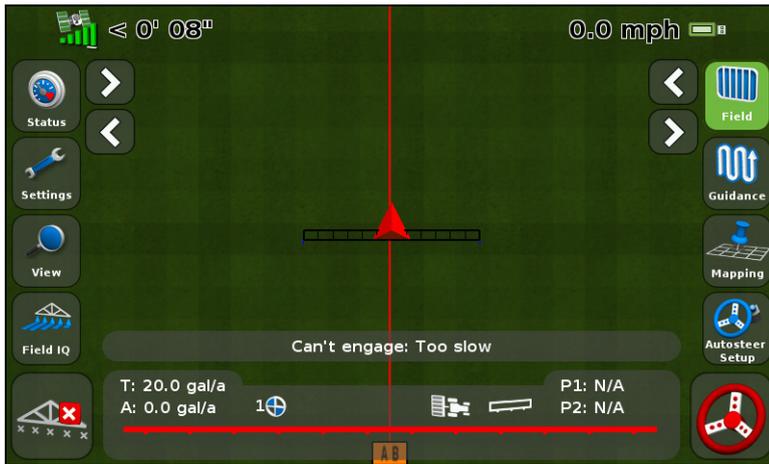
4. To set up your system, complete each page of the wizard. See the section below.

Using the setup wizards

The CFX-750 display contains various wizards that guide you through the task of configuring your system. The following table describes how to use the wizards to enter your system settings.

To ...	Tap ...
Select the setting you require	The field that displays the required value. When you make your selection, the field changes color from gray to green.
Enter the numbers that you require	
Enter text	
Accept the selection and go to the next screen	
Accept the selection and exit the screen	
Navigate the wizard	
Go back to the previous page	
Exit the wizard Note – When you exit the wizard, the system retains any settings you have already selected; for any settings that you have not yet entered, the system uses the settings from the previous configuration.	
Access the on-screen help	

The guidance screen



The guidance screen displays a mix of text and icons that provide operating information and access to various system functions. The availability of the text and icons depends on the set up of your system. For example, some icons are not available while you are using an auto steer system.

To activate an icon, tap it with your finger. If the display does not respond when you tap it, see [Recalibrate touchscreen, page 244](#).

The following sections describe the icons that can appear on the guidance screen.

Status

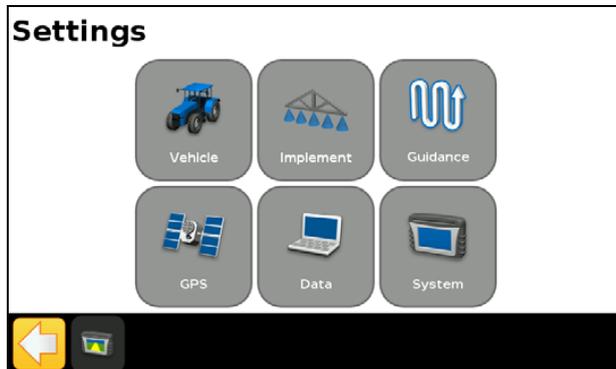
Tap  to scroll through several pop-up screens that describe various system settings:



To remove the pop-ups, continue to tap  until they disappear.

Settings

Tap  to open the *Settings* screen:



Use the *Settings* screen to adjust your system settings, and view the status of the following:

Setting	For more information, see ...
Vehicle	Chapter 4, Vehicle, page 42
Implement	Chapter 5, Implement Application Controller, page 91
Guidance	Chapter 9, Mapping and Guidance, page 189
GPS	Chapter 10, GPS, page 209
Data	Chapter 11, Data, page 217
System	Chapter 12, System, page 230

View

The options for viewing the guidance screen are:

- Zoom In
- Zoom Out
- Change View—this toggles between the Overhead view and Trailing view icons.

To:

- **change** the view, tap  and then select the option that you require.
- **exit** a view and return to the guidance screen, tap .

To learn how to change the View settings, see [View, page 232](#).

Zooming

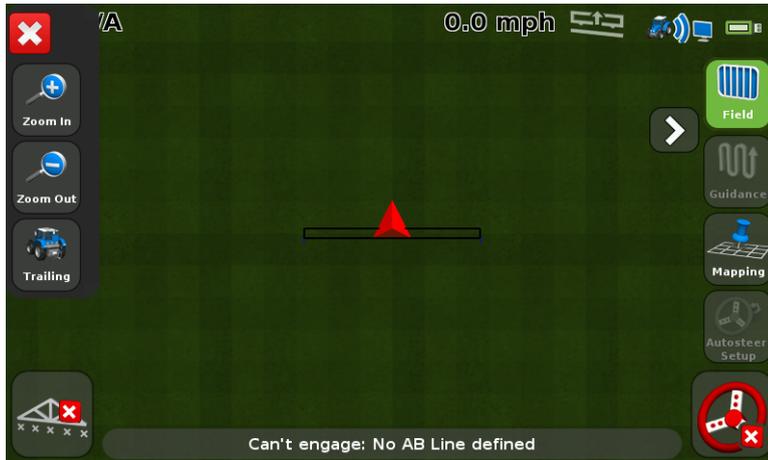
To zoom in or out on the guidance screen, tap  or .

Viewing modes

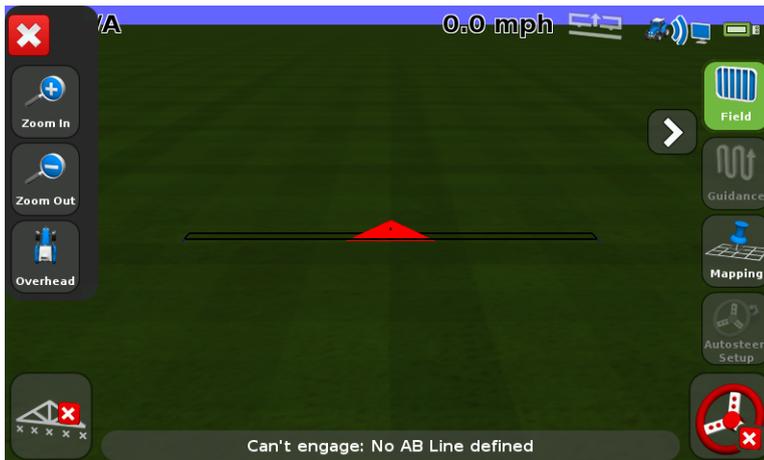
There are two viewing modes, Overhead and Trailing.

By default, the view switches from Overhead to Trailing when you approach the AB line.

To access the Overhead view, tap  .



To access the Trailing view, tap  .



Extended icons

The guidance screen features several extended icons that are hidden in the default view.

To view or hide the extended icons, tap  or .

The following images show how the extended icons appear on the guidance screen when they are expanded and collapsed:



Expanded



Collapsed

Quick Access icon

You can use the Quick Access icon to quickly adjust common settings.

The items that appear in the Quick Access menu will vary depending on the applications that you are currently running.

The following sections describe the items that may appear.

Note – The Quick Access icon appears only when you are running Field-IQ or a variable rate controller.



Boom setup

Use this option to view and adjust the following settings:

Value ...	Notes ...
Implement width	Enter the width of the current implement. The display uses this value to automatically calculated the swath spacing. Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Boundaries	See Boundary setup, page 193 .
Number of sections	Enter the number of sections you want to control on the implement. Enter a number between 1 - 10.

Refill

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Current volume	Set the current volume of the tank or bin.
Refill method	Select from one of the following options: <ul style="list-style-type: none"> • Refill: To fill the tank or bin to the top • Partial Refill: To add a specified amount to the tank or bin when you select Partial Refill Now from the <i>Refill</i> screen.
Refill Now / Partial Refill Now	Use this option to refill the tank or bin.

Section Switching Setup

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Coverage switching overlap	Control the amount of boom switching overlap allowed before the system switches that section. Enter a percentage between 1-99%. For: <ul style="list-style-type: none"> • Less skip: Set a high percentage when total coverage is essential. The system will turn off sections when they cover a larger percentage of any fully covered areas. This may cause some double-coverage. Sections will turn on as soon as they move from a covered to an uncovered area. • Less overlap: Set a low percentage when you need to save product. The system will turn off sections as soon as you reach any covered area. This may leave some skips. Sections will turn on when the entire section has moved from a covered to an uncovered area.
Refill method	Choose from one of the following options: <ul style="list-style-type: none"> • Refill: to fill the tank or bin to the top • Partial Refill: to add a specified amount to the tank or bin when you select Partial Refill Now from the <i>Refill</i> screen.
Refill Now / Partial Refill Now	Use this option to refill the tank or bin.

Boundary switching overlap

Use this option to control the amount of overlap on a boundary before the system switches off the boom section. Enter a percentage between 1-99%.

Note – *This setting operates only when the boom is overlapping a headland, pivot boundary, or exclusion zone.*

For:

- **Less skip:** Set a high percentage when it is acceptable to apply outside the boundary.

- **Less overlap:** Set a low percentage when you do not want to apply outside the boundary. A very low setting may cause some skip at the boundary.

On/off valve latency

This option allows for hardware delays by adjusting the amount of time needed before turning the valves on or off. To use this option:

1. Measure the amount of time it takes (in seconds) for the system to reach the correct rate after you have switched it on or off.
2. Enter a time between 0.0 - 10.0 seconds.

Intentional overlap

You can use this option to make sure that when applying, there are no gaps in coverage if you move into an uncovered area or out of a covered area.

Use this option ...	To set the distance that you want to travel before...
On overlap distance	Exiting a covered area and switching the implement on
Off overlap distance	Entering a covered area and switching the implement off

Target rate

Use this option to set the target application rate (the amount of product you want to apply). Enter a number between 1333 - 41333.

Valve aggressiveness

If you use an auto-steer system, such as an EZ-Steer® or Autopilot™ system, you can use this option to adjust how the system responds to steering changes.

Note the following:

- A higher setting brings the vehicle back on line quickly, but may cause tight oscillations.
- A lower setting gives a more moderate response to bringing the vehicle back on line, but can avoid overshoot.

Enter a setting between 50 - 150%.

The Field icon

From the guidance screen, tap  to create a new field or select an existing field. See [Chapter 9, Mapping and Guidance](#).

The Guidance icon

From the guidance screen, tap  to quickly nudge, shift, or resume a guidance line:



The Mapping icon

From the guidance screen, tap  to quickly add or delete the following features:

- rock
- line
- tree
- area
- weed
- exclusion



The auto-steer icon

From the guidance screen, tap  to quickly adjust the aggressiveness setting for the EZ-Steer or Autopilot system:



Reading lightbar patterns

When lit, the LEDs show the position of your vehicle relative to your intended guidance line. As your vehicle position changes in relation to the guidance line, the LEDs move left or right.

Use the lightbar to obtain accurate guidance when:

- you have set an implement offset or implement draft

- fine-tuning guidance on straight swaths

The LEDs in the integrated lightbar show the position of your vehicle relative to the guidance line:

- When your vehicle is on the guidance line, the three central green LEDs are lit.
- As your vehicle moves off the guidance line, the lit LEDs move left or right, and change to red. Note that the LED pattern that appears has a different meaning for each Main Lightbar LED Mode. For more information, see the table below, and [Lightbar Setup, page 233](#).

This LED pattern ...	Indicates that the vehicle is ...
	Directly on the guidance line.
	Off the guidance line. For this pattern, if the Main Lightbar LED Mode is set to: <ul style="list-style-type: none"> • Chase, the vehicle is offline to the <i>left</i>. • Pull, the vehicle is offline to the <i>right</i>.
	Off the guidance line. For this pattern, if the Main Lightbar LED Mode is set to: <ul style="list-style-type: none"> • Chase, the vehicle is offline to the <i>right</i>. • Pull, the vehicle is offline to the <i>left</i>.

Using the EZ-Remote joystick

Optionally, you can use an EZ-Remote™ joystick to control the CFX-750 display. The joystick has ten LED buttons: six have preset functions; you can assign one of the following functions to each of the other four:

- Map a rock, tree, or weed
- Start or finish a line
- Start or finish an area
- Start or finish an exclusion zone
- Turn coverage on or off
- Camera A or Camera B control
- Show trailing map view
- Show overhead map view
- Zoom
- Show status

To learn how to assign a function to a programmable button, see [EZ-Remote joystick, page 235](#).

On-screen icons

The tables in this section describe all of the icons available on the CFX-750 display.

Note – Icons appear only when they are appropriate. They are not visible at all times.

To activate an icon, tap it with your finger. If the display does not respond when you tap it, see [Recalibrate touchscreen, page 244](#).

System icons

Icon	Description
	System and display setup
	Autopilot setup
	GPS/GLONASS setup
	Data configuration
	Help
	Settings / Configuration
	Next page
	Back page

Icon	Description
	Menu
	Configure
	Status
	Setup wizard
	Edit item
	Delete
	Cancel changes
	Accept / save changes

Information icons

Icon	Description
	Setup complete
	Critical warning

Icon	Description
	General alert
	Information

View icons

Icon	Description
	Activate external video input
	Full screen external video
	Run screen trailing view

Icon	Description
	Zoom in
	Zoom out
	Run screen overhead view

Application icons

Icon	Description
	Manual section control
	Automatic section control
	Target rate

Icon	Description
	Section control off
	Coverage logging on
	Coverage logging off

Guidance icons

Icon	Description
	Guidance pattern select
	Pause guidance
	Nudge left
	Nudge right
	Record FreeForm guidance pattern
	Set A point

Icon	Description
	Start recording headland
	Pause recording headland
	End headland recording
	Cannot engage auto guidance
	Ready to engage auto guidance
	Auto guidance engaged

Icon	Description
	Set B point
	Shift AB line
	Next AB line

Icon	Description
	Increase auto guidance aggressiveness
	Decrease auto guidance aggressiveness

Mapping icons

Icon	Description
	Map line feature
	Map tree (point feature)
	Map rock (point feature)

Icon	Description
	Mapping configuration
	Area feature

Vehicle

In this chapter:

- [Introduction](#)
- [The EZ-Steer assisted steering system](#)
- [The EZ-Pilot steering system](#)
- [The Autopilot automated steering system](#)

This chapter describes how to configure your auto steer system for use with the CFX-750 display.

Introduction

To ensure the correct performance of your auto steer system, you must calibrate it correctly. Before you calibrate your auto steer option, do the following:

- Ensure that the vehicle’s hydraulic oil is up to operating temperature. Refer to the vehicle documentation.
- Ensure that the tire pressure is correct.
- Complete the GPS Setup on the CFX-750 display. For more information, see [Chapter 10, GPS](#).

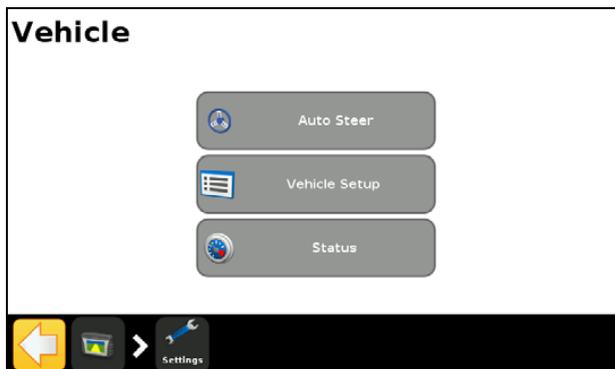
When you calibrate your auto steer option, pay attention to the following:

- Choose a field with the smoothest possible surface and perform the calibration at the normal operating speed for the vehicle.
- For a high-clearance sprayer, perform the initial calibration without an implement or with the booms folded in. After the initial calibration is completed, you can fine tune the settings with the implement or booms folded out.

The calibration process requires a straight AB line. If you do not create an AB line before you begin the calibration, the system prompts you to open a field and create one.

To access the auto steer options:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer**:



The EZ-Steer assisted steering system

The EZ-Steer assisted steering system works with the CFX-750 display's internal GPS receiver to provide vehicle guidance. As such, you must complete the GPS setup before you calibrate, set up, or run your EZ-Steer system. See [Chapter 10, GPS](#).

Setup

To view and adjust the settings for the EZ-Steer system:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer** and then **EZ-Steer Setup**:



Note – If the EZ-Steer Setup button does not appear, tap Auto Steer System Type and then select EZ-Steer for your controller.

The EZ-Steer Setup screen contains the following options:

- Engage Options
- Vehicle Setup
- Aggressiveness
- EZ-Steer Demo
- EZ-Steer Calibration Wizard

The following sections describe each option.

Engage Options

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Minimum/Maximum speed	Enter the minimum and maximum speeds at which the EZ-Steer system will disengage: <ul style="list-style-type: none"> • Minimum: between 1.0 and 15.9 mph (1.6 and 25.5 kph). • Maximum: between 1.0 and 18.0 mph (1.6 and 28.8 kph).

Setting ...	Notes ...
Maximum Angle	The EZ-Steer system will not engage when the vehicle is heading toward the guidance line at an angle greater than the Maximum Angle. Enter an angle between 5 and 45 degrees.
Engage/Disengage Offline	<ul style="list-style-type: none"> Engage offline: The system will not engage when the vehicle is offline further than the Engage Offline distance. Enter a distance between 0' 5" and 27' 0" (0.2 and 8.2 m). Disengage offline: The system will automatically disengage when the vehicle is offline further than the Disengage Offline distance. Enter a distance between 0' 6" and 27' 00" (0.2 m and 8.2 m).
Override sensitivity	Control how much force is required to disengage the system. Enter an increment between 1-100%.
EZ-Steer external switch	Enable or disable additional safety features.
EZ-Steer operator timeout	Enter a time between 1-60 minutes.

Vehicle Setup

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Vehicle type	Enter the type of vehicle on which the EZ-Steer system will be installed.
Wheelbase	See Entering vehicle measurements, page 47 .
Antenna height	See Entering vehicle measurements, page 47 .
Antenna to axle offset	See Entering vehicle measurements, page 47 .
Angle per turn	Adjust the angle that the wheels turn during one full rotation of the steering wheel. Enter an angle between 2-149 degrees.
Freeplay left/right	Adjust this setting if the vehicle is consistently off to the right or left of the guidance line. Enter a measurement of 0-12" (0-30.48 cm).
Motor speed	Control the speed of the EZ-Steer drive wheel motor.
Motor direction is reversed	Select yes or no.
Sprayer steering delay	Account for time lags with vehicle steering. Enter a value between 0.1-1.5.
Swather steering delay	Account for time lags with vehicle steering. Enter a value between 0.1-1.5.

Aggressiveness

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Online aggressiveness	Control how aggressively the EZ-Steer system corrects deviations from the guidance line. Enter a value between 50-150%.
Approach aggressiveness	Control how fast the EZ-Steer system steers the vehicle onto the guidance line. Enter a value between 50-150%

EZ-Steer Demo

Use this option to access the EZ-Steer Demo Mode.

EZ-Steer Demo Mode is useful for practice with defining fields, coverage logging, and assisted steering. EZ-Steer Demo Mode requires an EZ-Steer controller, motor, and EZ-Steer simulator stand (P/N 54836-00).

EZ-Steer Calibration Wizard

The EZ-Steer Calibration Wizard guides you through the process of calibrating your EZ-Steer system.

Calibration

Before you begin to use the display you must calibrate the EZ-Steer system. To do this, complete the Quick Start Wizard (see [The Quick Start Wizard, page 29](#)) that appears the first time that you use the display.

Note – *You must have GPS connected.*

To calibrate the EZ-Steer system at a later time, complete the following process:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer** and then tap **EZ-Steer Setup**:



Note – If the EZ-Steer Setup button does not appear, tap Auto Steer System Type and then select EZ-Steer for your controller.

3. In the EZ-Steer Setup screen, tap **EZ-Steer Calibration Wizard**.

- The wizard guides you through the following processes:
- Entering your vehicle measurements
- T2[®] roll calibration
- EZ-Steer calibration

Entering vehicle measurements

For optimum guidance, you must take accurate vehicle measurements and enter them into the display.

Note – Do not enter calibration numbers from EZ-Guide[®] Plus or EZ-Steer[®] T2 systems. This may cause very poor vehicle control, including swerves and/or large oscillations.

To streamline the calibration process, you may want to take the vehicle measurements and record them for entry later on.

The techniques for taking vehicle measurements are described below; to learn about implement measurements, see [Implement Setup options, page 194](#).

Before you take the measurements, position your vehicle as follows:

1. Park the vehicle on level ground.
2. Make sure that the vehicle is straight, with the centerline of the body parallel to the wheels.
3. Take the vehicle measurements:

To take this measurement ...	Measure from the ...	
Wheelbase	Center (the axle) of the front wheel to the center of the back wheel. Note that the wheelbase measurement for: <ul style="list-style-type: none"> • Tracked vehicles, is exactly half of the length of the track • Articulated 4WD vehicles, is half of the distance between the center of the front and rear wheels. 	
Antenna height	Ground to the top of the GPS antenna.	

To take this measurement ...	Measure from the ...
Antenna to axle offset	<p>Center (the axle) of the front or rear wheel to the top of the GPS antenna.</p> <p>Note – Make sure that you take this measurement to within 7.6 cm (3 in.) as an incorrect distance may result in poor steering performance.</p> <p>Take the measurement from the antenna to the correct point of your vehicle, as follows:</p> <ul style="list-style-type: none"> • Rear axle: <ul style="list-style-type: none"> - MFWD - Sprayer - Floater - Truck • Front axle: <ul style="list-style-type: none"> - 4wd tractor - Combine • Track center: <ul style="list-style-type: none"> - Tracked tractor <p>If the antenna is:</p> <ul style="list-style-type: none"> • in front of the axle, enter a Forward distance • behind the axle, enter a Behind distance



T2 roll calibration

Calibrating the T2 roll sensor enables the display to calibrate terrain compensation in the EZ-Steer controller. This step requires you to:

- Enter an accurate value for controller orientation.
- Park the vehicle and mark the inside of both sets of wheels.
- Remain stationary while the system calculates the roll offset. This takes approximately 20 seconds.
- Turn the vehicle around and ensure the wheels are over the positions marked in the previous step.
- Remain stationary while the system calculates the roll offset. This takes approximately 20 seconds.

EZ-Steer calibration

In this step you must drive and engage on a straight AB line in a clear field:

1. Begin driving and then tap .
2. Drive 160 feet and then tap .

A series of calibration screens will allow you to adjust any settings as necessary.

Operation

You must calibrate and set up the EZ-Steer system before operation.

Engaging the system

Before you can engage the EZ-Steer system, you must:

- open a field in the guidance screen
- define an AB line
- position the vehicle within the configured engage limits

To engage the system:

1. Point the nose of the vehicle toward the guidance line and drive at operational speed.
2. Do one of the following:
 - From the guidance screen, tap  .
 - Press the optional remote engage foot pedal.

Disengaging the system

The EZ-Steer system automatically disengages when one of the following happens:

- The vehicle is outside the configured engage limits.
- You pause the system.
- GPS positions are lost.
- You tap the **Engage** button on the guidance screen.

You can manually disengage the EZ-Steer system by turning the steering wheel (this overrides the electric motor). Check this setting before you start using the system by engaging on a line and then turning the wheel until the system disengages. To adjust the amount of force required to disengage the system, change the *Override Sensitivity* in the *Engage Options* screen.

Engage status indicators

Engage status	Icon color
Ready to engage	
Engaged	
Cannot engage	

Curve Auto steering Accuracy in Headlands

It is possible to engage the EZ-Steer system on headlands with sharp corners at the edge of the field. However, the EZ-Steer system may be unable to drive around these sharp bends. Use one of the following methods to compensate:

- Manually steer the vehicle around the corner. Once you have rounded the corner, re-engage the EZ-Steer system.
- In the Engage Options screen, increase the Disengage Offline distance.

Vehicle-specific performance

Before you use the EZ-Steer system, consider the following performance suggestions.

Vehicle type	Performance hint
2WD tractor	<p>With tractors that have SuperSteer (for example, New Holland TG), if the tractor has a SuperSteer front axle, for best performance:</p> <ul style="list-style-type: none"> • Reduce the Online Aggressiveness value. • Line up close to the swath and make certain that the front wheels are straight before engaging the EZ-Steer system. • To get smoother performance when the vehicle is pulling an implement over tilled ground, enable the Diff-Lock. This prevents the machine from pulling sharply to the left or right. If you are calibrating on a hard surface, turn off Diff-Lock.
4WD tractor	<p>The EZ-Steer system can be installed on Case IH STX tractors with Accusteer. For optimal performance, disable Accusteer using the switch in the cab (if possible).</p>
Sprayer	<ul style="list-style-type: none"> • It is common for these vehicles to have slow steering. To compensate for this, use high aggressiveness. • If you experience large, slow oscillations, increase the aggressiveness. • When you configure the system on a sprayer, the Sprayer steering delay setting is available on the <i>Vehicle Setup</i> screen. • Some sprayers have steering that is slow to react after you turn the steering wheel. The system uses the steering delay setting to compensate for this slowness and ensure that steering corrections occur at the correct point.

Vehicle type	Performance hint
Swather	<ul style="list-style-type: none"> • When you configure the system on a swather, the Swather steering delay setting is available on the Vehicle Setup screen. • Some swathers have steering that is slow to react after the steering wheel is turned. The system uses the steering delay setting to compensate for this slowness and ensure that steering corrections occur at the correct point. • To improve the performance of your swather, adjust the Swather steering delay setting by a small amount (0.1 seconds) at a time. Test the result between each adjustment

After using the EZ-Steer system

- Any time that you are not using the EZ-Steer system, pivot the EZ-Steer motor away from the steering wheel.
- **Before** you leave the vehicle turn off the EZ-Steer system power switch or remove the power plug.

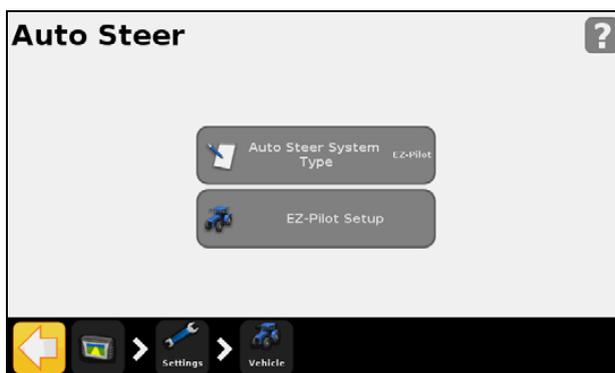
The EZ-Pilot steering system

The EZ-Pilot® steering system works with the CFX-750 display's internal GPS receiver to provide vehicle guidance. You must therefore complete the GPS setup before you calibrate, set up, or run your EZ-Pilot system. See [Chapter 10, GPS](#).

Setup

To view and adjust the settings for the EZ-Pilot system:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer** and then **EZ-Pilot Setup**:



Note – If the EZ-Pilot Setup button does not appear, tap Auto Steer System Type and then select EZ-Pilot for your controller.

The EZ-Pilot Setup screen contains the following options:

- Engage Options
- Vehicle Setup
- Aggressiveness
- Vehicle Calibration menu

The following sections describe each option.

Engage Options

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Minimum/Maximum speed	Enter the minimum and maximum speeds at which the EZ-Pilot system will disengage: <ul style="list-style-type: none"> • Minimum: between 1.0 and 15.9 mph (1.6 and 25.5 kph). • Maximum: between 1.0 and 18.0 mph (1.6 and 28.8 kph).

Setting ...	Notes ...
Maximum Angle	The EZ-Pilot system will not engage when the vehicle is heading toward the guidance line at an angle greater than the Maximum Angle. Enter an angle between 5 and 45 degrees.
Engage/Disengage Offline	Engage offline: The system will not engage when the vehicle is offline further than the Engage Offline distance. Enter a distance between 0' 5" and 27' 0" (0.2 and 8.2 m). Disengage offline: The system will automatically disengage when the vehicle is offline further than the Disengage Offline distance. Enter a distance between 0' 6" and 27' 00" (0.2 m and 8.2 m).
Override sensitivity	Control how much force is required to disengage the system. Enter an increment between 1-100%.
Operator timeout	Enter a time between 1-60 minutes.

Vehicle Setup

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Vehicle type	Enter the type of vehicle on which the EZ-Pilot system will be installed.
Wheelbase	See Entering vehicle measurements, page 54 .
Antenna height	
Antenna to axle offset	
Freeplay left / right	Drives consistently to one side of the line. <ul style="list-style-type: none"> • If the vehicle is offline to the left, increase the Freeplay offset to the right. • If the vehicle is offline to the right, increase the Freeplay offset to the left.
Motor speed	Control the speed of the EZ-Pilot drive wheel motor.

Aggressiveness

Use this option to view and adjust the settings described below:

Setting ...	Notes ...
Online aggressiveness	Control how aggressively the EZ-Pilot system corrects deviations from the guidance line. Enter a value between 50-150%.
Approach aggressiveness	Control how fast the EZ-Pilot system steers the vehicle onto the guidance line. Enter a value between 50-150%

Vehicle Calibration Menu

See [Angle Per Turn calibration, page 56](#)

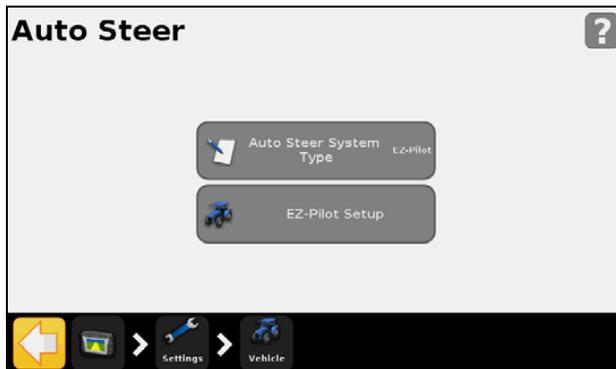
Calibration

Before you begin to use the display, you must calibrate the EZ-Pilot system. To do this, complete the Quick Start Wizard (see [The Quick Start Wizard, page 29](#)), that appears the first time that you use the display.

Note – You must have GPS connected.

To calibrate the EZ-Pilot system at a later time, complete the following process:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer** and then **EZ-Pilot Setup**:



Note – If the EZ-Pilot Setup button does not appear, tap Auto Steer System Type and then select EZ-Pilot for your controller.

3. In the EZ-Pilot Setup screen, tap **EZ-Pilot Calibration Wizard**.

The wizard guides you through the following processes:

- Entering your vehicle measurements
- T3™ roll calibration
- EZ-Pilot calibration

Entering vehicle measurements

For optimum guidance, you must take accurate vehicle measurements and enter them into the display.

Note – Do not enter calibration numbers from EZ-Guide® Plus or EZ-Steer systems. This may cause very poor vehicle control, including swerves and/or large oscillations.

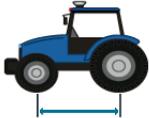
To streamline the calibration process, you may want to take the vehicle measurements and record them for entry later on.

The techniques for taking vehicle measurements are described below; to learn about implement measurements, see [Implement Setup options, page 194](#).

Before you take the measurements, position your vehicle as follows:

1. Park the vehicle on level ground.
2. Make sure that the vehicle is straight, with the centerline of the body parallel to the wheels.

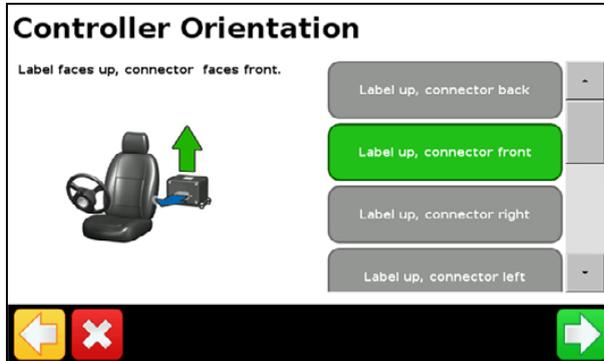
Take the vehicle measurements:

To take this measurement ...	Measure from the ...	
Wheelbase	Center (the axle) of the front wheel to the center of the back wheel. Note that the wheelbase measurement for tracked vehicles is exactly half of the length of the track.	
Antenna height	Ground to the top of the GNSS antenna.	
Antenna to axle offset	Center (the axle) of the front or rear wheel to the top of the GPS antenna. Note – Make sure that you take this measurement to within 7.6 cm (3 in.) as an incorrect distance may result in poor steering performance. Take the measurement from the antenna to the correct point of your vehicle, as follows: <ul style="list-style-type: none"> • Rear axle: <ul style="list-style-type: none"> - MFWD - Sprayer - Floater - Truck • Front axle: <ul style="list-style-type: none"> - 4wd tractor - Combine - Swathers Note – For swathers, it is recommended that you put the antenna directly above the front axle or slight ahead. <ul style="list-style-type: none"> • Track center: <ul style="list-style-type: none"> - Tracked tractor If the antenna is: <ul style="list-style-type: none"> • in front of the axle, enter a Forward distance • behind the axle, enter a Behind distance 	

T3 roll calibration

Calibrating the T3 roll sensor enables the display to calibrate terrain compensation in the IMD-600 unit. This step requires you to:

1. Enter an accurate value for the IMD-600 orientation:



2. Park the vehicle and mark the inside of both sets of wheels.
3. Remain stationary while the system calculates the roll offset. This takes approximately 20 seconds.
4. Turn the vehicle around and ensure the wheels are over the positions marked in the previous step.
5. Remain stationary while the system calculates the roll offset. This takes approximately 20 seconds.

Angle Per Turn calibration

You must first set the IMD-600 orientation and perform the T3 terrain compensation calibration.

You must operate the vehicle in an open field with ample area for the vehicle to make right and left turns.

1. Tap **Right Angle-Per-Turn Calibration**.
2. Drive forward until  appears and then tap the icon.

Note – For the best results drive the vehicle between 2 and 4 mph.

3. Allow the system to operate for 20 seconds until you receive a message that the calibration is complete.
4. Repeat [Step 1](#) through [Step 3](#) for left angle-per-turn calibration.

EZ-Pilot system calibration

In this step you must drive and engage on a straight AB line in a clear field:

1. Begin driving and tap .
2. Drive 160 feet and then tap .

A series of calibration screens will allow you to adjust any settings as necessary.

Operation

You must calibrate and set up the EZ-Pilot system before operation.



CAUTION – Do not operate the EZ-Pilot system while driving in reverse gear.

Engaging the system

Before you can engage the EZ-Pilot system, you must:

- Open a field in the guidance screen
- Define an AB line
- Position the vehicle within the configured engage limits

To engage the system:

1. Point the nose of the vehicle toward the guidance line and drive at operational speed.
2. From the guidance screen or the optional remote control, tap .



CAUTION – If you use the vehicle on a public roadway, you **must** put the red EZ-Pilot system override switch in the off position.

To engage the EZ-Pilot system, do one of the following:

- Tap **Engage** on the Run screen
- Press the **Engage** button on the EZ-Remote joystick, see [EZ-Remote joystick, page 235](#)
- Use an external foot or rocker switch, see [Engaging the EZ-Pilot system using an external foot or rocker switch, page 58](#)

Engaging the EZ-Pilot system using an external foot or rocker switch

To install a foot or rocker switch:

1. Locate the foot or momentary rocker switch and the remote engage adapter cable (P/N 88506 - included with the foot switch kit, P/N 78150-00, or purchased separately).
2. Remove the wedge from a receptacle 3-pin Deutsch DTM:



3. Do one of the following:
 - For a foot switch, hold the receptacle with the lock facing upward with the black wire on the right-hand side, the white wire in the middle, and the green wire on the left-hand side:



Note – If you purchased P/N 78150-00, the correct connector is already attached.

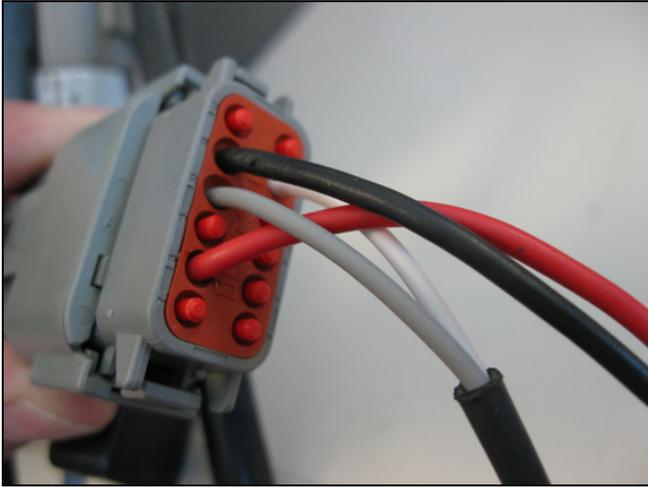
5. Connect the attached receptacle to the 3-pin DTM plug on the remote engage adapter cable:



6. Plug the other end of the remote engage adapter cable into the port replicator (pin 10 and pin 11) on the EZ-Pilot cable that is connected to Port B on the CFX-750 display:



Note – If you are using a sonalert, you must remove engage pin 10 and move it to pin 8 so that the remote engage functions run between pin 8 and pin 11 and the sonalert functions between pin 2 and pin 10.

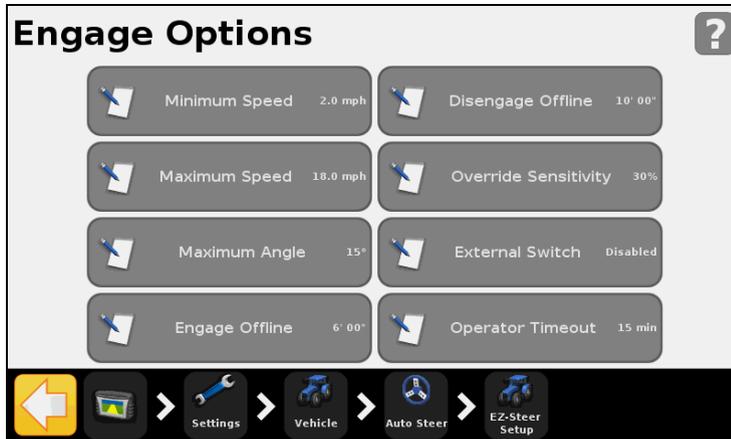


7. Route the cables of the footswitch or rocker switch to the required location:

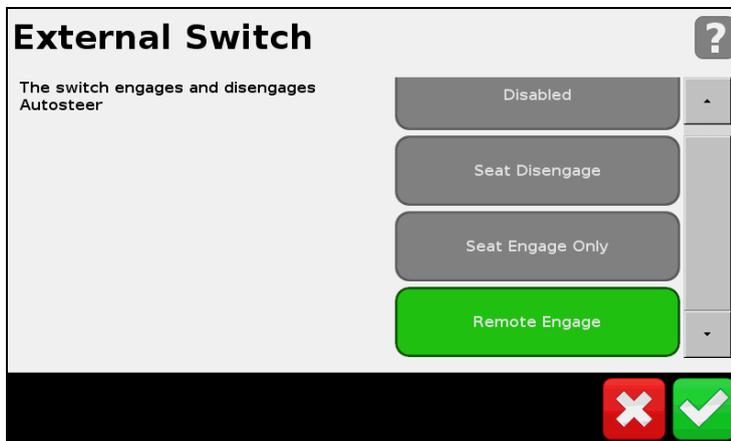


Setting up the display when using a foot or rocket switch

1. Select *Settings / Vehicle / Auto Steer / EZ-Pilot Setup*.
2. Tap **EZ-Pilot External Switch**:



3. Tap **Remote Engage** and then tap :



The Switch functionality now shows *Remote Engage* and is ready to be used:



Disengaging the system

The EZ-Pilot system automatically disengages when one of the following happens:

- The vehicle is outside the configured engage limits.
- You pause the system.
- GPS positions are lost.
- You tap the **Engage** button on the guidance screen.
- You press the **Engage** button on the optional EZ-Remote joystick.

You can manually disengage the EZ-Pilot system by turning the steering wheel (this overrides the electric motor). Check this setting before you start using the system by engaging on a line and then turning the wheel until the system disengages. To adjust the amount of force required to disengage the system, change the *Override Sensitivity* in the *Engage Options* screen.

Engage status indicators

Engage status	Icon color
Ready to engage	
Engaged	
Cannot engage	

Curve auto steering accuracy in headlands

It is possible to engage the EZ-Pilot system on headlands with sharp corners at the edge of the field. However, the EZ-Pilot system may be unable to drive around these sharp bends. Use one of the following methods to compensate:

- Manually steer the vehicle around the corner and then re-engage the EZ-Pilot system.
- In the *Engage Options* screen, increase the Disengage Offline distance.

Vehicle-specific performance

Before you use the EZ-Pilot system, consider the following performance suggestions.

Vehicle type	Performance hint
2WD tractor	<p>With tractors that have SuperSteer (for example, New Holland TG), if the tractor has a SuperSteer front axle, for best performance:</p> <ul style="list-style-type: none"> • Reduce the Online Aggressiveness value. • Line up close to the swath and make certain that the front wheels are straight before engaging the EZ-Pilot system. • To get smoother performance when the vehicle is pulling an implement over tilled ground, enable the Diff-Lock. This prevents the machine from pulling sharply to the left or right. If you are calibrating on a hard surface, turn off Diff-Lock.
4WD tractor	<p>The EZ-Pilot system can be installed on Case IH STX tractors with Accusteer. For optimal performance, disable Accusteer using the switch in the cab (if possible).</p>
Sprayer	<ul style="list-style-type: none"> • It is common for these vehicles to have slow steering. To compensate for this, use high aggressiveness. • If you experience large, slow oscillations, increase the aggressiveness. • When you configure the system on a sprayer, the Sprayer steering delay setting is available on the <i>Vehicle Setup</i> screen. • Some sprayers have steering that is slow to react after you turn the steering wheel. The system uses the steering delay setting to compensate for this slowness and ensure that steering corrections occur at the correct point.

Vehicle type	Performance hint
Swather	<ul style="list-style-type: none"> • When you configure the system on a swather, the Swather steering delay setting is available on the Vehicle Setup screen. • Some swathers have steering that is slow to react after the steering wheel is turned. The system uses the steering delay setting to compensate for this slowness and ensure that steering corrections occur at the correct point. • To improve the performance of your swather, adjust the Swather steering delay setting by a small amount (0.1 seconds) at a time. Test the result between each adjustment

After using the EZ-Pilot system



CAUTION – *Before* you leave the vehicle, turn off the power to the display which will turn off the EZ-Pilot system power.



CAUTION – If you use the vehicle on a public roadway, you **must** put the red EZ-Pilot system override switch in the off position.

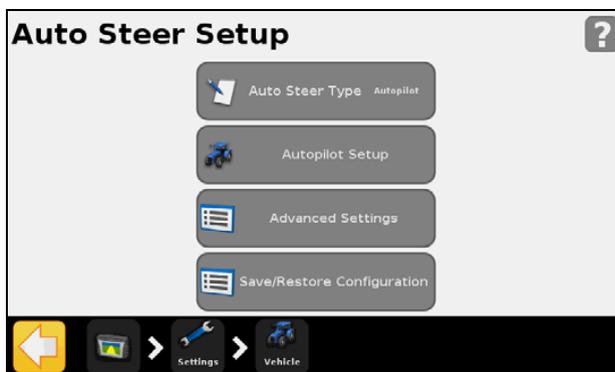
The Autopilot automated steering system

Note – For advanced setup options contact your Trimble reseller.

Setup - overview

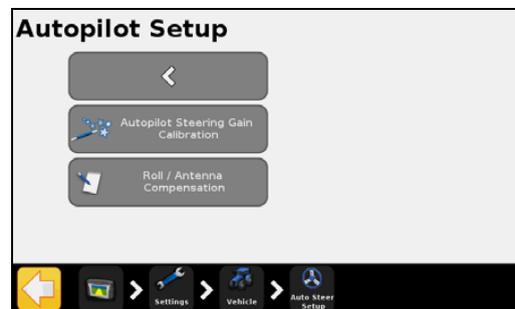
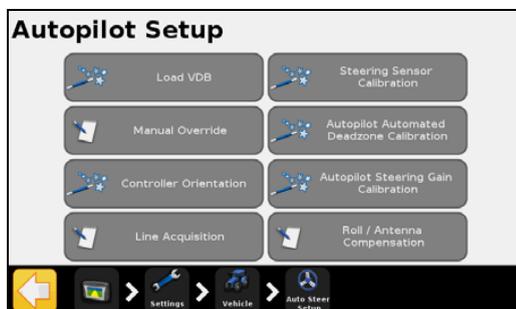
To view, set up, and adjust settings for the Autopilot system:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer**
3. Set the Auto Steer type to *Autopilot*
4. Tap **Autopilot Setup**.



Autopilot Setup screen

From the *Autopilot Setup* screen, you will view, set up, and adjust settings for the following:



Note – The buttons that appear depend on the vehicle loaded from the vehicle database (VDB) or from a restored vehicle configuration. The following is a complete list of what may appear—some or all may be relevant to your selected vehicle type.

Setup Category	Explanation
Load VDB	Allows you to access the Trimble Vehicle Database through a USB drive for basic setup.
Manual Override	Adjusts how much force is required to disengage the system when the driver turns the steering wheel for pressure transducer and some quadrature encoder systems. Depending on the manual override method, this option may not be available.
Controller Orientation	Determines the position/orientation of the controller as it is currently installed in the vehicle.
Line Acquisition	Controls how aggressively the Autopilot system commands the vehicle to steer to the current guidance line. Note – If Line Acquisition is set higher than the steering capabilities of the vehicle hydraulic system, instability may occur. You must check the stability at the indicated speed.
Steering Sensor Calibration	Converts the reported steering potentiometer voltage output into an equivalent steering angle measurement. Note – To set up AutoSense™ sensors, go to Auto Steer Setup / Advanced Settings / Autopilot Operations / Autopilot Steering Sensor.
Autopilot Automated Deadzone Calibration	Determines the minimum valve command required for steering movement.
Autopilot Steering Gain Calibration	Sets the proportional gain value, PGain, to control vehicle steering overshoot and responsiveness.
Roll / Antenna Compensation	Sets the offsets to compensate for variations in the position of the NavController II and the mounting of the GNSS receiver.
Performance Settings	Adjusts controller responsiveness to favor high accuracy or high stability in steering calculations (for supported sprayers and some swathers only).

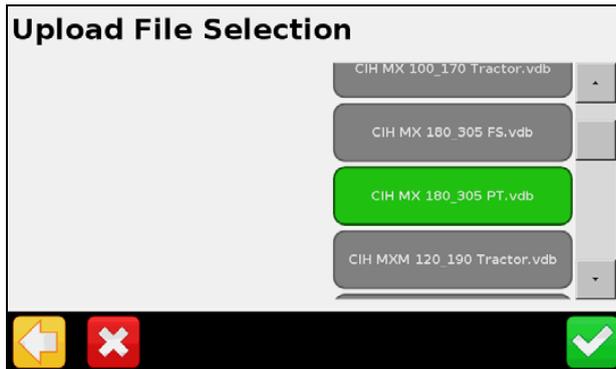
Loading a VDB

Note – Before loading a vehicle database into the CFX-750 display, go to Partners or contact your local reseller to obtain the most current Trimble VDB files and to determine which vehicle model is recommended for your installation.

To load a vehicle profile file from the Trimble Vehicle Database file:

1. Copy the vdb file to the following location on a USB memory stick:
Root / AgGPS / Autopilot/ VDB.
2. Insert the USB memory stick into the back port of the CFX-750 display.
3. In the *Autopilot Setup* screen, tap **Load VDB**. A number of upload warning messages appear.

4. Select the appropriate vehicle file for your vehicle based on recommendations from Partners or your Trimble Reseller and then tap .



A number of upload warning messages appear. Communication with the NavController II restart.

Manual Override

Note – *The manual override sensitivity calibration is only valid for those platforms employing a pressure transducer for the manual override function.*

It is strongly recommended that you perform this calibration only if it is determined that the default sensitivity is unacceptable under all operating conditions. The default sensitivity setting provides a balance between rapid activation of the override function and rejection of steering wheel motion due to incidental contact (for example, due to travel in a rough field).

Adjust the setting by incrementing the voltage setting up or down in increments of 0.10 V. Maximum and minimum voltage is established by vehicle and operational parameters.

The *Current Sensor Value* voltage or sensitivity is displayed along with the *Override* status that is based on comparing the setting value to the reported sensor value.

- **Increasing** the threshold value makes the manual override function less sensitive to steering movements.
- **Decreasing** the threshold value makes the manual override function more sensitive to steering wheel movements and will disengage Autopilot function sooner.

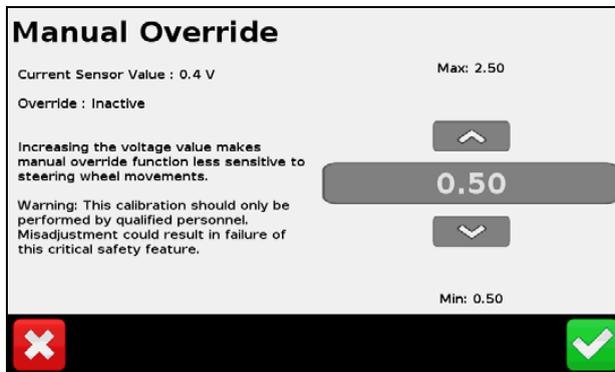
Calibration procedure

With the vehicle at a standstill, do the following:

1. Turn the steering wheel and evaluate the effort required to activate the *Override* status on the display.
2. Adjust the sensitivity level up or down by increasing or decreasing it in increments of 0.20 units.
3. Turn the steering wheel and assess whether the manual override feature is at an acceptable sensitivity level by evaluating the effort required against the *Override* status on the display.
4. Repeat [Step 1](#) through [Step 3](#) until the *Calibration* screen shows a suitable response.

It is recommended that you evaluate the performance of the manual override feature under loading conditions and / or during activities that may affect the pressure of the hydraulic system.

5. Tap  when Manual Override responds optimally:



Controller Orientation

Note – NavController II images represent the mounting orientation when viewed from the top looking down, and with the front of the tractor pointing at the top of the screen.



Controller Orientation is set by using Orthogonal Entry or Direct Entry—tap  when you have made your selection in this screen and then follow the procedures described below.

Orthogonal Entry

Use this option if the mounting position of the control was completed in 90° increments around the X, Y, Z axis. To achieve the correct NavController II orthogonal orientation, do the following:

1. In the *Connector Orientation* screen, orient the controller image in reference to the mounting direction of the NavController II wiring connectors when viewed from above and with the front of the tractor pointing to the top of the display. **Ignore the reference direction of the NavController II labeling during this step.** When the correct connector orientation has been achieved, tap .



- In the *Label Orientation* screen, orient the controller image in reference to the mounting direction of the NavController II Labeling Panel when this is viewed from above, and with the front of the tractor pointing to the top of the display. **Ignore the reference direction of the Nav II wiring connectors during this step.** When the correct connector orientation has been achieved, tap .

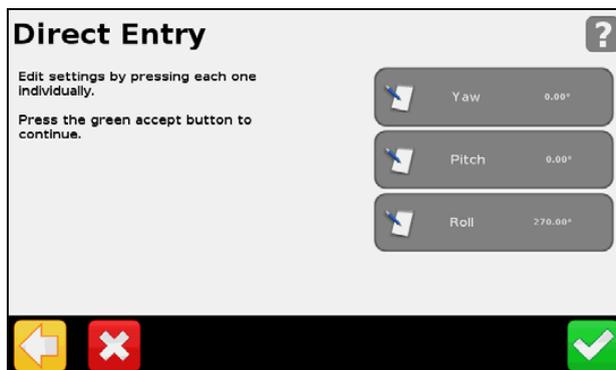


Direct Entry

Use this option if the mounting position was done in known Roll, Pitch, Yaw degrees.

To achieve the NavController II direct orientation, enter the mounting angles of the controller in relation to the Roll = 0, Pitch = 0, Yaw = 0 state of the controller.

The 0,0,0 state of the controller is defined with the wiring connectors facing the rear of the tractor, and the label panel facing up when viewed from above.



When the controller begins in the (0,0,0) orientation, increasing degrees of orientation are indicated by the following:

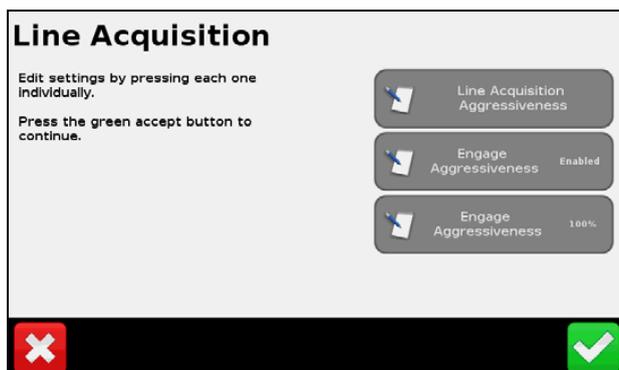
Direct Entry Axis	Explanation
Yaw	Rotation around the z-axis; initially the front edge of the controller moves right and the back edge of the controller moves left.
Pitch	Rotation around the x-axis; initially the front edge of the controller moves up, and the back edge of the controller moves down.
Roll	Rotation around the y-axis; initially the left edge of the controller moves up and the right edge of the controlled moves down.

When the correct connector orientation has been achieved, tap .

Line Acquisition

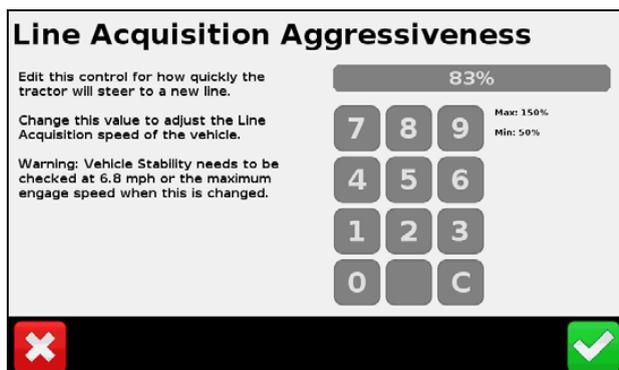
The *Line Acquisition* screen enables you to fine-tune how the Autopilot system commands the steering hydraulics to approach the line.

Line acquisition parameters are set using one of the following attributes—tap  when you have entered the *Line Acquisition* parameters:



Line Acquisition Aggressiveness

This controls how fast the guidance system commands the vehicle to steer onto the current guidance line. The value can be adjusted to between 50% and 150% of the calculated value:



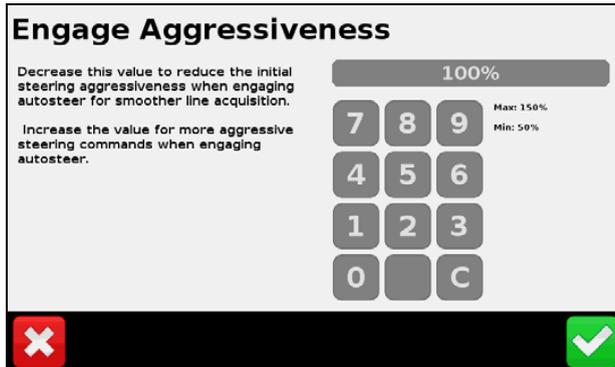
- With a higher setting, the vehicle approaches the line quickly, but may overshoot the line due to greater approach angles.
- With a lower setting, the vehicle steers onto the line more slowly, but is less likely to overshoot the line due to lower approach angles.

Note – Ensure that you test the line acquisition performance at, below, and above the speed specified in the Vehicle Stability Warning message on the Acquisition screen. Depending on the capabilities of the machine, higher line acquisition may cause instability due to the vehicle steering not being able to respond quick enough. This indicated speed value changes depending on the Line Acquisition Aggressiveness setting selected.

Tap  when you have entered the required *Line Acquisition Aggressiveness*.

Engage Aggressiveness

This controls how aggressive the vehicle initially reacts when you press the engage button.



- With a higher setting, the vehicle will react faster and more aggressively when you press the engage button.
- With a lower setting, the vehicle will react slower and smoother when you first press the engage button.

Note – *The Engage Aggressiveness calibration option is not shown unless the function is enabled.*

After adjusting the Steering Acquisition settings, re-evaluate the performance at, below, and above the normal operation speed of the Vehicle and Implement and make further adjustments as required.

Tap  when you have entered the required *Engage Aggressiveness*.

Steering Sensor Calibration

The *Steering Sensor Calibration* is required to convert the voltage output of the steering potentiometer into an equivalent steering angle measure.

Note – *Steering sensor calibration is only performed if a rotatory potentiometer or hall-effect sensor is installed on the vehicle. If the steering angle sensor is set to AutoSense, the Steering Sensor Calibration screen does not appear.*

Note – *To view or edit AutoSense settings, select Settings / Vehicle / Auto Steer Setup / Autopilot Operations / Autopilot Steering Sensor.*

Note – *Complete this calibration before attempting to calibrate the Steering Deadzone or Roll Corrections procedures.*

Pre-calibration

- Carry out this calibration on a hard, level surface that is free of obstructions.
- Follow the instructions that appear on each screen of the display.
- Make sure that the tractor speed exceeds 1.6 kph (1 mph) during the test phases.

Calibration procedure

Note – *To minimize the amount of open area space required for the complete calibration, you may reposition the vehicle between the phases of the test.*

1. Drive the vehicle to a large field that is without hazards or obstructions. The field should have smooth soil that is loose, but firm.
2. Enter the *Steering Sensor Calibration* wizard and then write down the *Sensor Voltage* and the *Steering Angle* when the wheels are straight, full left, and full right. This will be used for comparison purposes after you have run the test.
3. Run the Calibration wizard, reading and following all on-screen instructions.

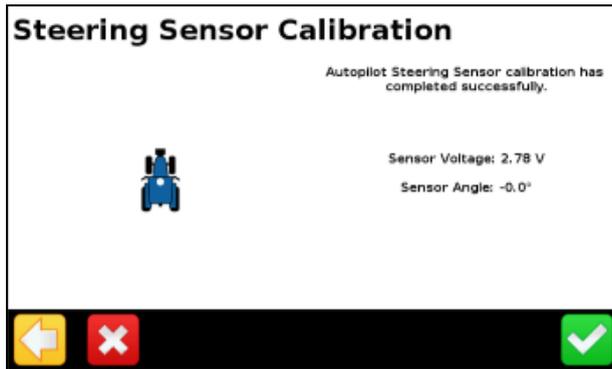
Note – *If the steering wheel is not turned completely to either left or right positions when required, or if the steering sensor requires adjustment or replacement, you must adjust the sensor and then repeat the calibration.*



CAUTION – Failure to be in motion and in a straight path will cause performance problems after calibration.

4. With the wheels *Straight*—move the vehicle slowly forward and then tap .
5. Steer the wheels full *Left* while continuing to move slowly forward and then tap .
6. Steer the wheels full *Right* while continuing to move slowly forward and then tap .
7. Steer the wheels *Straight* while continuing to move slowly forward and then tap .

8. Once the calibration is complete the *Sensor Voltage* and *Steering Angle* results appear. Tap  once you have verified that the voltage and angle are both acceptable.



- Watch the *Sensor Angle* to ensure a systematic angle reading at the steering extremes when you manually steer the wheels full right and full left.
 - Watch the *Sensor Angle* field to ensure that the angle reading is near zero when you manually steer the wheels straight ahead.
9. If required, repeat the calibration procedure.

Autopilot Automated Deadzone Calibration

 **WARNING** – Many large and sudden changes in satellite geometry caused by blocked satellites can cause significant position shifts. If operating under these conditions, auto-guidance systems can react abruptly. To avoid possible injury or damage to property under these conditions, disable the auto-guidance system and take manual control of the vehicle until the conditions have cleared.

 **WARNING** – Obstacles in the field can cause collisions, which may injure you and damage your vehicle. If an obstacle in the field makes it unsafe to continue a particular phase of the automated dead-zone calibration, stop the vehicle to abort the phase and turn the steering wheel to disengage the system. Reposition the vehicle and continue from the current test phase.

Note – *The Steering Sensor Setup and calibration must be performed before you run this procedure, and the vehicles hydraulic fluid must be at operation temperature.*

The *Autopilot Automated Deadzone Calibration* runs a series of tests on the valve and steering hydraulics to determine the point at which steering movement occurs. It determines the minimum valve command required for steering movement by turning the vehicle to the right and to the left.

In this test, the system gradually actuates the steering system while determining the independent left and right point at which wheel movement occurs for each direction.

Run the *Deadzone* calibration till the *Deadzone* value displays for each side a change of less than 0.5 units.

The calibration is run multiple times and a progress indicator appears on the display during each phase of the calibration. Once each phase is completed, the display will prompt the user to steer the vehicle in a particular direction.

Pre-calibration

- Warm up the vehicle. The hydraulic fluid must be at normal operating temperature for Deadzone calibration.
- If you perform the Deadzone calibration while the system is cold, repeat the Automated Deadzone calibration again when the system is at operating temperature.
- Prepare the steering sensor by doing the following:
 - If the vehicle has an AutoSense device, drive the vehicle in a straight line for at least one minute.
 - If the vehicle has a Potentiometer, first complete the Steering Sensor calibration.

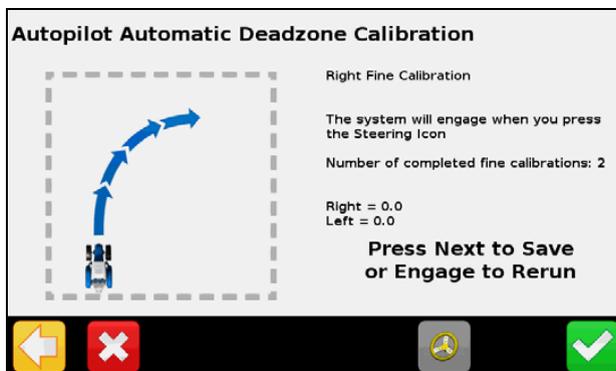
Calibration procedure

Note – To minimize the amount of open area required for the complete calibration, you may reposition the vehicle between the phases of the test.



WARNING – During Calibration the vehicle will turn slowly either to the right or to the left. The vehicle may move in an unpredictable manner. To avoid injury, be prepared for vehicle movements.

1. Drive the vehicle to a large field that is without hazards or obstructions. The field should have smooth soil conditions.
2. Enter the *Deadzone Calibration* wizard and then write down the and write down the *Right Deadzone Value* and the *Left Deadzone Value*. This will be used for comparison purposes after you have run the test.
3. Run the Calibration wizard, reading and following all on-screen instructions and taking note of all warning messages.
4. Move the vehicle straight forward in first gear at a maximum operation RPM and at a speed of approximately 1.6 kph (1 mph) and then tap .
5. Engage Autoguidance on the display. The calibration will turn the vehicle one direction. When it has completed the first test for a coarse deadzone value, straighten the wheels and push engage again. The system will then turn in the opposite direction to determine the coarse deadzone value for that direction. After this, you are instructed to repeat this process for the fine value determinations for each side.
 - If the difference between the deadzone values for the second and third trial **is greater than** 0.5 units, repeat the calibration procedure
 - If the difference between the deadzone values for the second and third trial **is less than** 0.5 units, tap  to complete the calibration.



Autopilot Steering Gain Calibration



WARNING – The wheels can move abruptly during the Steering Proportional Gain procedure while the Autopilot system tests the hydraulic response to its steering commands. To avoid injury, be prepared for vehicle movement.

Note – The Steering Sensor Setup and calibration must be performed before you run this procedure. Run this procedure only if the Autopilot system performance is less than satisfactory.

Note – Close fields on the display before performing the calibration.

The Autopilot Steering Gain, *PGain*, sets the proportional gain to control steering overshoot and responsiveness. The *PGain* setting is a compromise between fast steering response and stability. Modifications to *PGain* affect two steering characteristics:

- *Slew Time*: The amount of time the front wheels take to move from the far left to the far right position and vice versa.
- *Overshoot*: The percentage by which the front wheels exceed the commanded angle before they settle on the correct value.

Altering these settings may correct slight variations in your vehicle due to valve response and tire to soil interaction.

High *PGain* values decrease the slew time and increases the overshoot. This provides rapid responses, but excessive *PGain* can cause the steering to exhibit signs of instability, like a tendency to excessively overshoot and excessive wheel movement when the vehicle is online.

Low *PGain* values increase the slew time and decreases the overshoot. This improves the stability, but can introduce significant delays in the steering responses and can cause the vehicle to wander from side to side.

The proportional gain should be increased to the point just before any one of the following occurs:

- Slew times no longer decrease (low values are preferred).
- Overshoot exceeds 5–8% (depending on the vehicle).
- Wheels noticeably shake during online performance.

Pre-calibration

- Carry out this calibration on a hard, level surface that is free of obstructions.
- Make sure that the tractor speed is approximately 1.6 kph (1 mph) during the test.
- Calibrate the Steering Gain following a Steering Sensor calibration.
- Warm up the vehicle. The hydraulic fluid must be at normal operating temperature for Deadzone calibration.

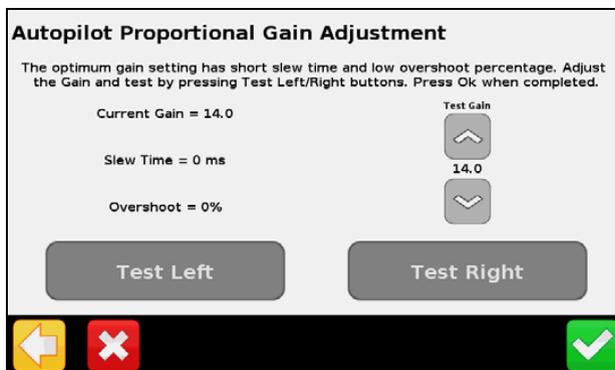
Calibration procedure

Note – To minimize the amount of open area required for completing the calibration, you may reposition the vehicle between the phases of the test.



WARNING – During this procedure the wheels will move abruptly. To avoid injury, be prepared for vehicle movements.

1. Drive the vehicle to a large field that is without hazards or obstructions. The field should have smooth soil conditions.
2. Run the Calibration wizard, reading and following all on-screen instructions and taking note of all warning messages.
3. In the *Autopilot Proportional Gain Adjustment* screen, while moving, turn the wheels to full left or full right and tap the opposite **Test** direction steering command:
 - The wheels will automatically turn to the opposing full turn position.
 - The *Slew* and *Overshoot* percentages will be reported once the test has been completed for the turn.
4. Once the *Slew* and *Overshoot* percentages appear on the screen, keep moving and select the opposing test direction to the one you selected in [Step 3](#):
 - The wheels will automatically turn to the opposing full turn position.
 - The *Slew* and *Overshoot* percentages will be reported once you have completed the turn.
5. Once you have run the slew test in both directions, adjust the *P Gain* if required by an increment of 1 unit in the direction that provides the required vehicle response—higher for a more reactive system, lower for a less reactive system.
6. Repeat the calibration procedure until the appropriate vehicle response is achieved and then tap  to complete the calibration.



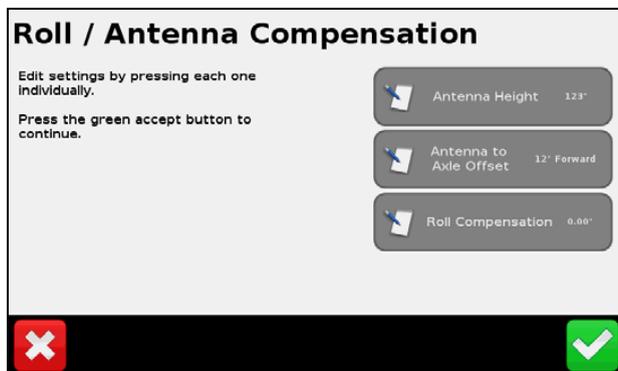
Roll / Antenna Compensation

The following antenna measurements will help the system to steer the vehicle more accurately.

Before taking measurements do the following:

- Park the vehicle on level, solid ground.
- Make sure the vehicle is straight, with the center line of the body parallel to the wheels.

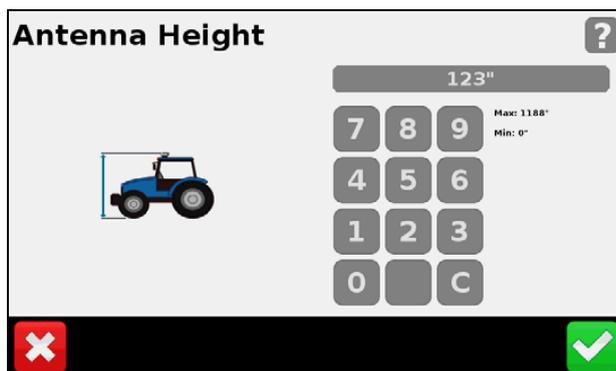
Follow each selection's directions carefully and provide measurements that are within 2.5 cm (1 inch) for the best results after calibration. Help text information appears on the screen to help you understand each measurement and process.



Tap  once you have adjusted all three measurements correctly.

Antenna Height

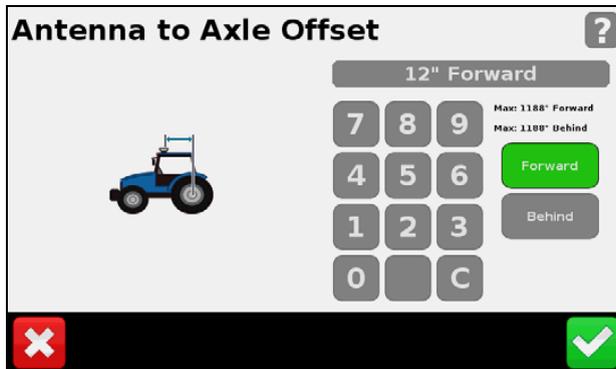
1. Measure vertically from the ground to the top of the GPS receiver. Enter the measurement in the appropriate units of the display:



2. Tap  when you have entered the correct height.

Antenna to Axle Offset

1. Measure horizontally from the center of the fixed axle to the center of the GPS receiver. Enter the measurement in the appropriate units of the display.



2. Do one of the following:
 - Tap **Forward** when the GPS receiver is located in front of the measurement axle.
 - Tap **Behind** when the GPS receiver is located behind the measurement axle.

The following table lists the appropriate measurement point for each vehicle type:

Vehicle type	Measure from the center of ...
MFWD vehicles	the rear axle
4WD articulating vehicles	the front axle
Tracked vehicles	the track assembly
Combines	the front axle
Swather vehicles	the front axle
Sprayer vehicles	the rear axle

3. Tap  when you have entered the correct offset.

Roll Compensation

 **Tip** – Trimble recommends that you use a highly-repeatable GPS correction mode for roll correction. For best results, use a RTK mode or OmniSTAR® HP signal that has been converged for at least 20 minutes. If you do a roll calibration with less accurate GPS correction modes, repeat the measurements **at least four times** to ensure a more consistent result.

Note – Before proceeding with Roll Calibration, do the following calibrations: Manual Override, Automated Deadzone, and Steering Gain.

You must carry out Roll Compensation in the Run screen with an open field and an established AB line. The results of this procedure must then be entered in the *Roll Compensation* screen. Repeat the calibration process as often as required to achieve the required accuracy.

Note – For best results, complete the following procedure using the Drop Flag Method for roll compensation.

Pre-calibration

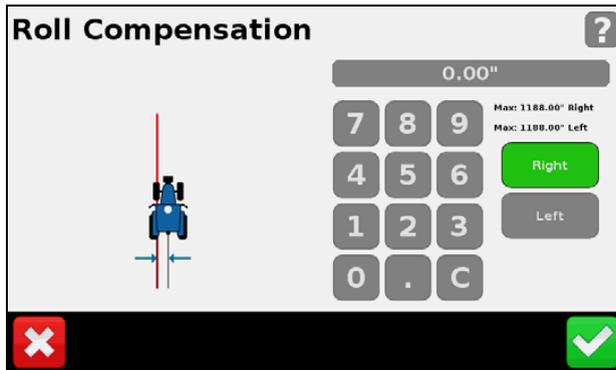
- Remove any implement(s) from the vehicle and drive to a flat, smooth area where you can complete passes of at least 125 m (400 feet) in length.
- On the display create an open field profile and an active AB line.
- Run the below calibration procedure till the correct response has been achieved.

Calibration procedure

It is recommended that you drop a flag marker from the center of the draw bar hitch for this test to create a point of origin and reference center line.

1. Drive to the created AB line.
2. Engage on the Line for a short distance. When the vehicle's direction stabilizes on the AB line and when the displayed cross track error is below 2 cm (1 inch), stop the vehicle.
3. Mark the vehicle's position by placing a flag below the center of the drawbar pin hole or another repeatable reference point.
4. Continue to drive the vehicle down the AB line and at the end of the line, turn the vehicle around.
5. Re-engage on the AB line, travelling in the opposite direction towards the original dropped flag marker.
6. Stop the vehicle on the same point as the original dropped flag marker.
7. Measure the offset distance between the original marker point and the current vehicle location.

8. Open the *Roll Calibration* screen and then do the following:



- a. Enter the appropriate distance and offset direction resulting from the test; use the following table for reference:

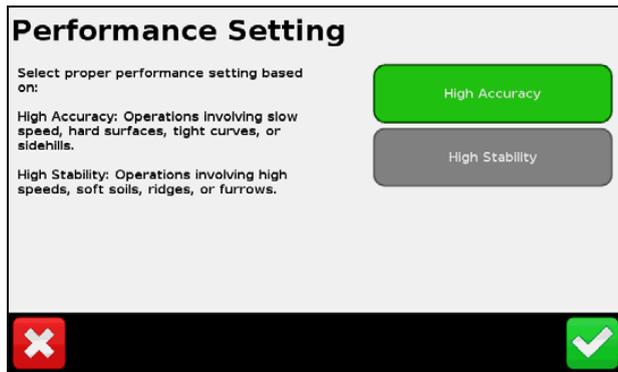
Vehicle position with reference to Flag 1	Cross Track Error says the vehicle is _____ of the line	Roll Cal. Calculation Equation	Direction to enter for Offset Direction
Right	Right	Flag Measure - XTE = Roll Cal Value	Right, unless XTE is larger than the flag measurement
Left	Left	Flag Measure - XTE = Roll Cal Value	Left, unless XTE is larger than the flag measurement
Right	Left	Flag Measure + XTE = Roll Cal Value	Right
Left	Right	Flag Measure + XTE = Roll Cal Value	Left

- b. Tap  when you have entered the correct offset.
9. Exit the *Autopilot Calibration* menu so that the offsets can be applied to the NavController II.
10. Open the Run screen and then repeat this calibration procedure till the *Roll Compensation* achieves the required accuracy:
11. Tap  when the correct *Engage Aggressiveness* has been entered.

Performance Settings

Note – Currently the Performance Setting calibration is available for supported sprayers and swathers only.

Select the correct performance setting for your sprayer based on the following required responsiveness:



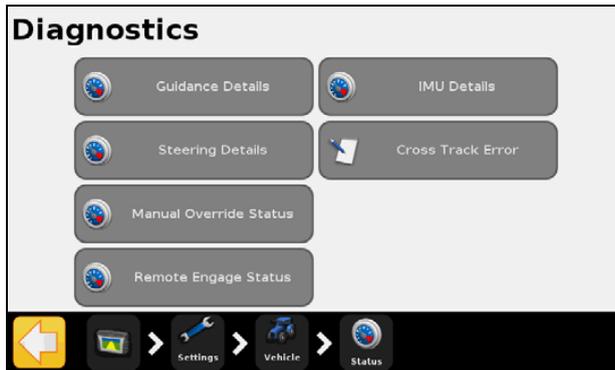
Performance Settings	Explanation
High Accuracy	Creates high accuracy in all conditions. This mode is best for high-accuracy operations at slower speeds, on hard surfaces, tight curves, and side hills.
High Stability	Creates smooth and stable corrections. This mode is best for soft soils, ridges, deep furrows, and high speed operations.

Tap  when the correct *Performance Setting* has been selected.

Status/Diagnostics

To view the system and sensor status settings for the Autopilot system:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Status** and then tap **Diagnostics**:



In the *Diagnostics* screen you can view the main sensor inputs for the selected vehicle type. The raw and scaled sensor data values will appear on each page. Data in the *Diagnostics* screen is updated continuously to allow for real-time evaluation of the connection.

Note – An engage button appears in menus that require the Autopilot system to be engaged in order to get real-time data from the sensors.

Note – The buttons that appear depend on the vehicle loaded from the vehicle database (VDB) or from a restored vehicle configuration. The following is a complete list of what may appear—some or all may be relevant to your selected vehicle type.

Diagnostics category	Description
Guidance Details	Displays guidance sensor details: Requested Steering Angle, Heading, PMW values, Corrections, and PPS value.
Steering Details	Displays the raw and scaled values for the Steering Angle sensor.
Manual Override Status	Displays the sensor override voltage as well as the vehicle voltage and status of override setting.
Remote Engage Status	Displays the remote engage voltage, the reported vehicle voltage, and current status of Steering Override setting.
IMU Details	Displays the accelerometer raw and scaled values by axis as well as the gyro axis values of the IMU (Inertial Measurement Unit).
Cross Track Error	Displays the cross track error histogram showing offline distance and average.

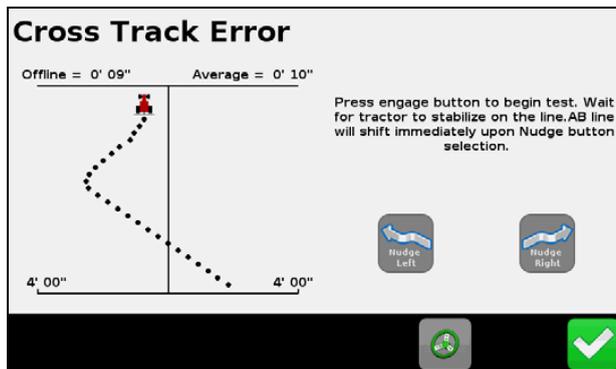
Cross Track Error (for advanced users)

Note – The field must be open and there must be an active AB line.

Note – “Nudge” shifts the AB line 91.4 cm (36 inches) to either side when the you select the nudge direction.

The Cross Track Error histogram shows the vehicle’s progression and acquisition of an AB guidance line.

After opening a field and setting an active AB line, this *Diagnostics* page allows the operator to watch how the vehicle responds to line acquisition commands in order to evaluate performance of the Autopilot parameters.



Evaluation



WARNING – During Calibration the vehicle will turn slowly either to the right or to the left. The vehicle may move in an unpredictable manner. To avoid injury, be prepared for vehicle movements.

1. Drive near the AB line and engage the Autopilot system using the display or Remote Engage buttons.
2. Evaluate the vehicles response using the *Offline* and the *Average* distance indicators.
3. Tap the **Nudge** buttons to nudge the guidance line in either direction.

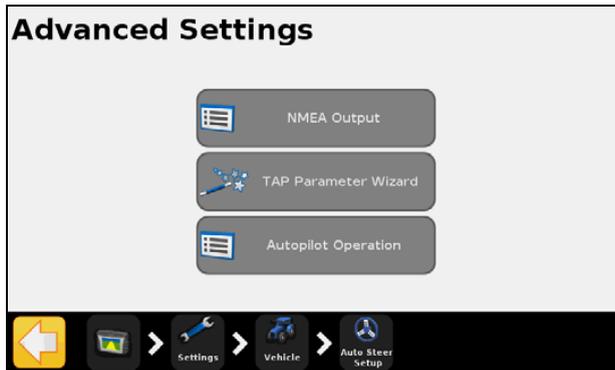
The vehicle will begin moving left or right depending on which direction you chose. Verify that the path is free of obstacles and that the vehicle is under full operator awareness before selecting **Nudge** directions.

4. Evaluate the response again using the *Offline* and the *Average* distance indicators.
5. Repeat the evaluation as required to understand the responsiveness of the vehicle profile.
6. Tap  when the *Cross Track Error Behavior* evaluation is complete.

Advanced Settings

To view and set the advanced configuration settings of the Autopilot system:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer Setup** and then tap **Advanced Settings**:



From the *Advanced Settings* menu you can now adjust and set operational parameters to further tune the Autopilot configuration and to define NMEA broadcasting protocols.

Advanced Setting	Explanation
NMEA Output	Establishes broadcast output protocols for GNSS positioning.
TAP Parameter Wizard	Allow manual entry of specific TAPs and the entry of their required value.
Autopilot Operation	Establishes operational parameters involving guidance aggressiveness, operator warnings, and a selection of steering sensor types.

Autopilot Operation

This enables you to further establish operational parameters using the following settings and sensors:

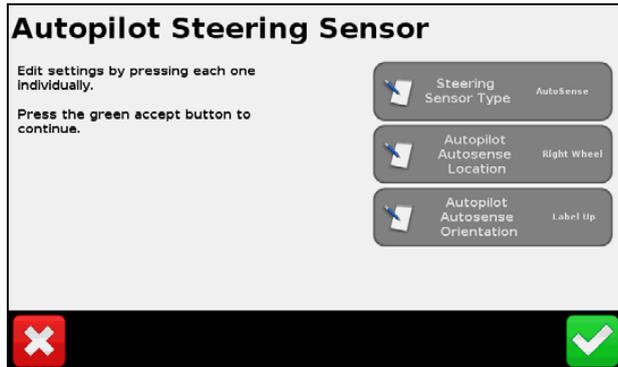
Operation category	Explanation
Online Aggressiveness	Sets how quickly the guidance system steers onto an active guidance line.
Operator Alert Timeout	Sets the maximum time interval that the operator can operate without the guidance system asking for operator presence.
End of Row Warning	Sets the distance from the end of the row at which the audible warning sounds to alert the operator of the upcoming event.
Autopilot Steering Sensor	Allows the selection of AutoDense steering sensors or Potentiometer sensors based on the selected Autopilot profile and allows you to set up an AutoSense steering sensor. Note – To calibrate a potentiometer, select <i>Auto Steer Setup / Autopilot Setup / Steering Sensor Calibration</i> .

Autopilot Steering Sensor

Note – The Autopilot Steering Sensor type is established through the selection of a .vdb profile or through the activation of TAP parameters.

Note – Potentiometer Steering Sensors are calibrated in Autopilot Setup.

This options allows you to select the type of Autopilot Sensor installed on the vehicle and set up Autosense Sensors:



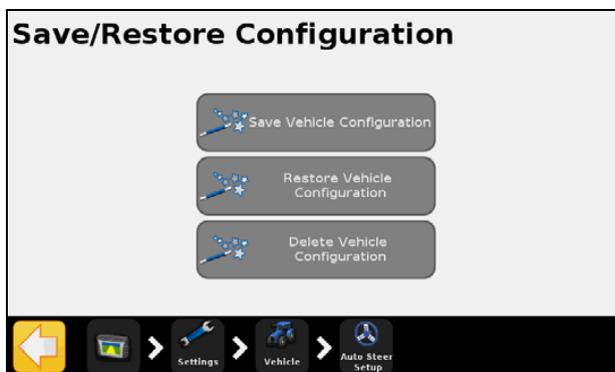
To set up Autosense Steering sensors, do the following:

1. Tap **AutoPilot AutoSense Location**. Determine which axle and side of the vehicle the sensor is mounted upon when viewed from the operator's seat.
2. Tap **AutoPilot AutoSense Orientation**. Determine which way the sensor label is facing when viewed from the perspective of looking down on the sensor.
3. Tap  when you have selected and set up the steering sensor.

Save/Restore Configurations

To save or restore a completed vehicle configuration file:

1. In the guidance screen, tap  and then tap **Vehicle**.
2. Tap **Auto Steer Setup** and then tap **Save / Restore Configuration**:



From the *Save/Restore Configuration* menu you can select any of the following options:

- **Save Vehicle Configuration**—save a vehicle configuration to the external memory or internal memory of the display.
- **Restore Vehicle Configuration**—restore a previously saved configuration file.
- **Delete Vehicle Configuration**—delete a configuration profiles from external memory or internal memory.

Display wizards will take you through each of the vehicle configuration options.

Note – *The internal memory of the display can only store a maximum of 10 unique vehicle configurations.*

Note – *External memory options are only available if a USB device is present in the rear port of the display.*

Note – *Configuration profiles will be recognized if they are copied from a FmX integrated display and are within the original content folder created by the FmX display.*

Operation

You must calibrate and set up the Autopilot automated steering system before operation.

Engaging the system

Before you can engage the Autopilot automated steering system, you must:

- Open a field in the guidance screen
- Define an AB line
- Position the vehicle within the configured engage limits

To engage the system:

1. Point the nose of the vehicle toward the guidance line and drive at operational speed.
2. Do one of the following:
 - From the guidance screen, tap  .
 - Press the optional remote engage foot pedal.

Disengaging the system

The Autopilot automated steering system automatically disengages when one of the following happens:

- The vehicle is manually steered, causing a manual override.
- The vehicle is outside the configured engage limits.
- You pause the system.
- GPS positions are lost.

- You tap the **Engage** button on the guidance screen.

Check the manual override setting before you start using the system by engaging on a line and then turning the wheel until the system disengages. To adjust the amount of force required to disengage the system, change the *Manual Override* sensitivity in the *Autopilot Setup* screen.

Engage status indicators

Engage status	Icon color
Ready to engage	
Engaged	
Cannot engage	

After using the Autopilot automated steering system

Before you leave the vehicle turn off the system power switch or remove the power plug.

Implement Application Controller

In this chapter:

- Introduction
- HARDI 5500 controller
- Raven controllers
- Rawson controller
- Amazone controller
- LH 5000 controller
- Vaderstad controller
- Bogballe controller
- Checking the implement connection

This chapter describes how to configure the CFX-750 display to use an implement application controller.

Introduction

The options in the *Implement* screen enable you to configure an implement application controller, such as the Field-IQ crop input control system.

To access the *Implement* screen:

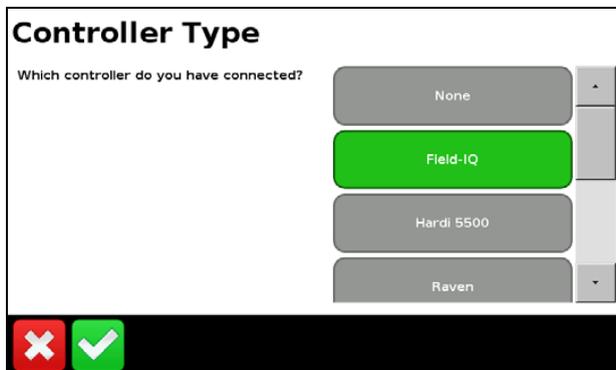
1. From the guidance screen, tap .
2. From the *Settings* screen, tap **Implement**:



The *Implement* screen contains two options, *Advanced* and *Initial Setup*. The *Advanced* option appears only after you have set up your controller using the *Initial Setup* option.

To set up your controller:

1. From the *Implement* screen, tap **Initial Setup**. The *Controller Type* screen appears.



Note – To access all of the available *Controller Type* options (apart from *None* and *Field-IQ*) you must have a VRA unlock code. To obtain a VRA unlock code, contact your Trimble reseller.

2. Select the controller that you are using.

Note – When you change the controller type, any open field will close.

3. Configure your controller. For more information, see:

- [HARDI 5500 controller, page 95](#)
- [Raven controllers, page 98](#)

- Rawson controller, page 102
- Amazone controller, page 106
- LH 5000 controller, page 109

Prescriptions

The CFX-750 display can use a prescription file to determine the rate of application in different areas of the field.

The prescription file consists of three separate ESRI files: .shp, .dbf and .shx. Each of these files contain different attribute information that the display uses.

You must load a prescription from the USB drive to the internal memory of the CFX-750 display. The display cannot read prescriptions directly from a USB drive. For more information, see the section below.

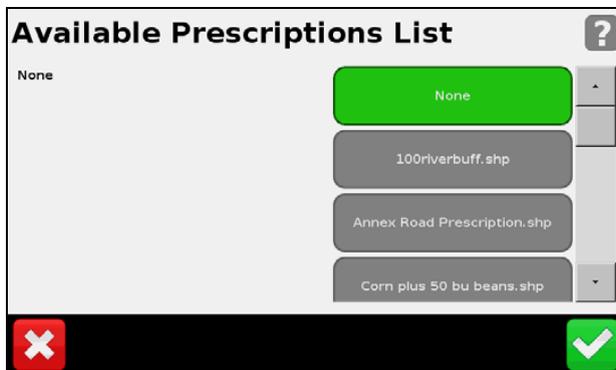
Loading a prescription

1. Copy the prescription file from your computer to the *AgGPS/Prescriptions* folder on your USB drive.

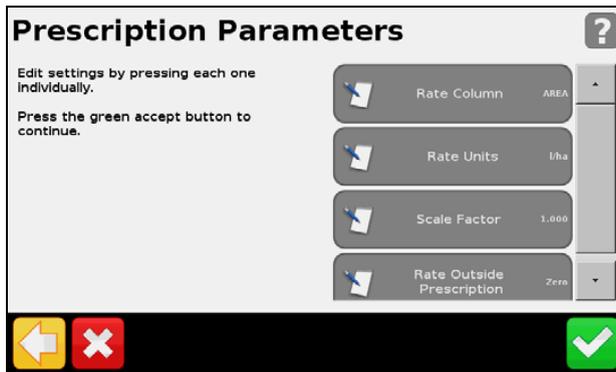
Note – If you do not have an AgGPS® directory on your USB, create one by exporting field data to the USB. For more information, see [Sending data to the USB drive, page 228](#).

2. Insert the USB drive into the USB socket, and then copy the prescription file to the display's internal memory. See [Retrieving data from the USB drive, page 228](#).
3. From the guidance screen, tap  to create a new field or select an existing field.

The CFX-750 display searches the internal memory for prescription files, and after you define or select a field, the following screen appears in the wizard:



4. Select the prescription file that you require and then tap . The following screen appears:



5. Configure each of the items in the *Prescription Parameters* screen.



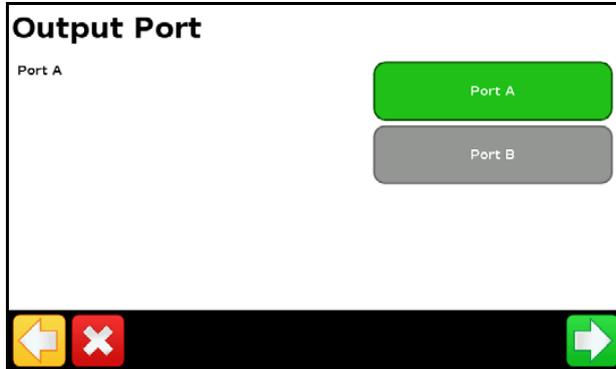
CAUTION – For the system to work correctly, you **must** select the correct Rate Column setting. If you do not, then the applied rate will be incorrect.

HARDI 5500 controller

Note – For the HARDI 5500 controller to work correctly with the CFX-750 display, you must install firmware version 3.16 or greater on the HARDI controller and connect a JOBCOM control box.

Setup

1. Once you select the HARDI 5500 as your controller, the following screen appears on the display:



Note – Do not configure the display to output NMEA messages on the same port that your controller is connected to.

2. On the HARDI 5500 controller, go to the *Settings* menu.
3. Change Remote to Enable.

For more information on setting up the HARDI 5500 controller, refer to the HARDI instruction manual.

Advanced

Use the *Advanced* option in the *Implement* screen to configure the following:

- Boom Setup
- Swath Control
- Rate Control
- Off When Stopped
- Rate Snapping

Boom Setup

Note – The boom setup on the CFX-750 display must match the setup on the HARDI controller. If the boom setup differs between the display and the HARDI controller, a warning message appears on the display.

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Fence Nozzles	Enter the locations of any fence nozzles.
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Rate control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
On	Application rates are sent from a prescription loaded in the display or the target rate manually configured on the display.
Off	The target rate must be set on the HARDI controller. The CFX-750 display does not send target rates to the controller. This is the default setting.

Note – When sending a target rate to the HARDI 5500 controller that is higher than 99.9, the display rounds to the nearest whole number. For example, 0-99.9 is not rounded. 101.4 is rounded to 101.

Off When Stopped

You can use this option to control whether the system allows the vehicle to continue operating when it is not moving.

If the vehicle is a clutch-operated planter, select No so you can continue planting even when stopped.

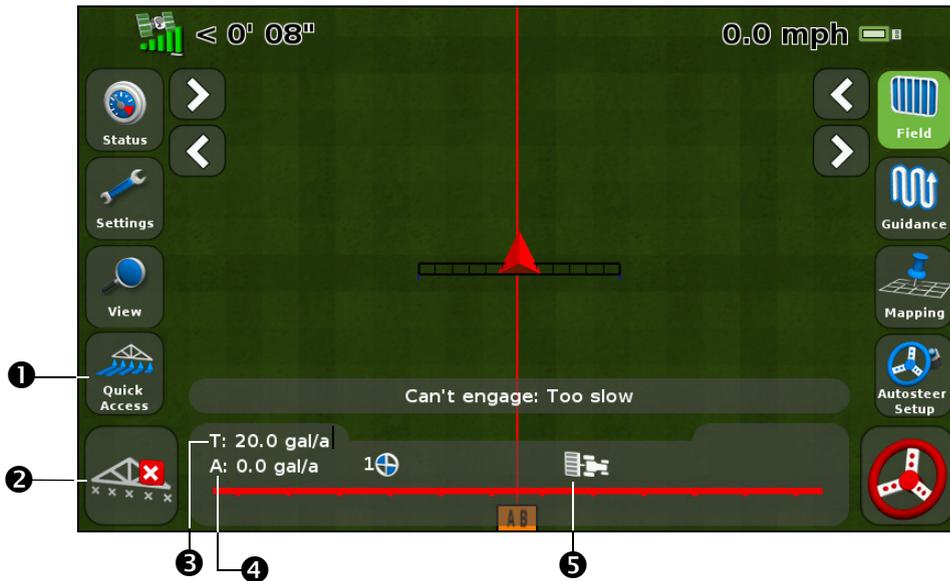
Rate Snapping

Due to pump constraints, liquid flow is generally inconsistent. To control how these inconsistencies appear on your display, turn rate snapping on or off.

Value ...	Notes ...
On	Matches the applied rate to the target rate when within 10% of the value.
Off	Shows all fluctuations in the actual applied rate.

Operation

When you connect the HARDI 5500 controller to the CFX-750 display, the following items appear on the guidance screen:



Item	Description	Notes
1	Quick Access icon	See, Quick Access icon , page 34.

Item	Description	Notes
②	Boom section status indicators	Shows the current state of each boom section: <ul style="list-style-type: none"> Green: Enabled and spraying Gray: Enabled but not currently spraying Red: The section is off (the switch is off)
③	Target rate	If a prescription is loaded, P displays to indicate that the prescription rate is being used rather than the target rate.
④	Actual rate	As the HARDI controller does not report the actual applied rate to the display, this item always appears as N/A.
⑤	Section control	Shows the current mode for the controller.
	Fence nozzle indicator	This indicator appears only when a fence nozzle is enabled. Fence nozzle status is represented with the same colors as the boom sections (see below). Note – The CFX-750 display cannot automatically turn fence nozzles on or off. It only displays the current status.
	Application indicator	The wheel on the display spins when the HARDI master switch is on and the booms are on.

Raven controllers

When using the Raven SCS 400 and 600 series controller with the CFX-750 display, note the following:

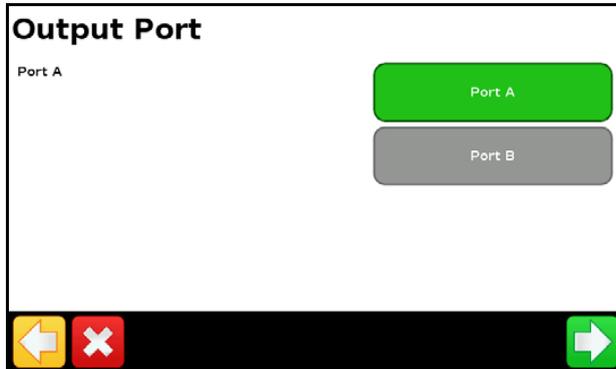
- The CFX-750 display cannot control the status of the Raven controller master or boom switches. This means that the operator must remain in complete control of the sprayer at all times.
- The CFX-750 display cannot automatically turn off the sprayer when going outside headlands, across exclusion zones, or previously sprayed areas.
- The sprayer may not always switch off completely when the CFX-750 sends a zero rate. This means the operator may need to manually turn off the master switch to ensure that spray is not applied.

Note – The only time the CFX-750 display sends a zero rate is when the sprayer is outside a prescription boundary and the "Rate outside polygon" option is zero.

- The operator must ensure that the master switch is off when there is no field open so that no spray is accidentally applied to areas that shouldn't be sprayed, for example, roads, paths, and neighboring fields.

Setup

1. Once you select Raven as your controller, the following screen appears on the display:



Note – Do not configure the display to output NMEA messages on the same port that your controller is connected to.

2. On the Raven controller, configure the following Data Menu settings:

Item	Setting
Baud or Baud Rate	9600
GPS	Inac
DLOG or Data Log	On
TRIG or Data Log Trigger Value	1
UNITor Data Log Trigger Units	sec

Note – In the GPS group, if ‘Send time’, ‘Time acknowledge’ or ‘Close file’ appear, change them to GPS Inac. Otherwise, the DLOG or DATA LOG option will not appear.

For more information on configuring and calibrating the Raven controller, refer to the Raven instruction manual.

Advanced

Use the *Advanced* option in the *Implement* screen to configure the following:

- Boom Setup
- Target Rate
- Rate Snapping

Boom Setup

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Number of sections	Enter a number between 1 - 10.

Target Rate

Set the target application rate that will be sent to the Raven controller. Enter a rate between 0.0 - 11000.0.

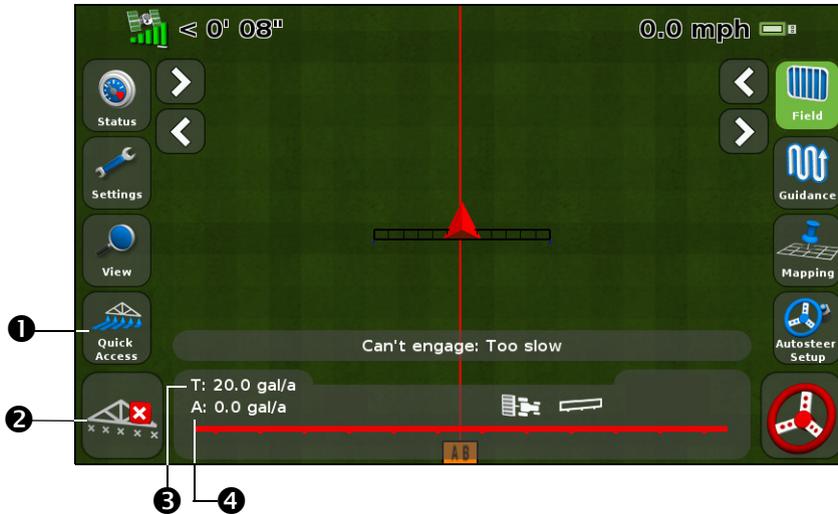
Rate Snapping

Due to pump constraints, liquid flow is generally inconsistent. To control how these inconsistencies appear on your display, turn rate snapping on or off.

Setting ...	Notes ...
On	Matches the applied rate to the target rate when within 10% of the value.
Off	Shows all fluctuations in the actual applied rate.

Operation

When you connect the Raven controller to the CFX-750 display, the following items appear on the guidance screen:



Item	Description	Notes
1	Quick Access icon	See Quick Access icon , page 34.
2	Boom section status indicators	Shows the current state of each boom section: <ul style="list-style-type: none"> Green: Enabled and spraying Gray: Enabled but not currently spraying Red: The section is off (the switch is off)
3	Target rate	If a prescription is loaded, P displays to indicate that the prescription rate is being used rather than the target rate.
4	Actual rate	The actual application rate. This is the amount of product that is currently being applied.
	Application indicator	The wheel on the display spins when the Raven master switch is on and the booms are on.

Target Rate

To manually enter a rate to send to the controller:

1. In the *Settings* screen, tap **Implement** and then **Advanced**.
2. Tap **Target Rate** and then adjust the rate that is sent to the controller.

Automatic Boom Switching

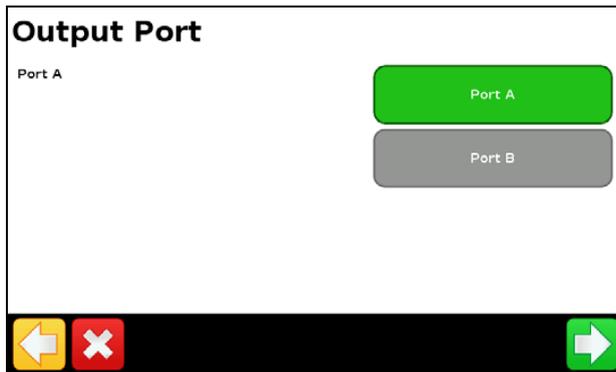
The CFX-750 display will not do automatic boom switching for the Raven controller.

Note – To ensure that areas outside the headland, in exclusion zones, or previously sprayed areas are not sprayed, you will need to manually turn off the Raven controller master switch.

Rawson controller

Setup

1. Once you select Rawson as your controller, a warning message appears. Make sure that you read the message carefully, and then tap  to continue:



2. Change the Output Port to COM or AUX to match the port on the display that the controller is connected to.
3. On the Rawson controller:
 - Verify the default target rate and step size and then enter these values into the CFX-750 display. To learn how to change these settings on the CFX-750 display, see [Advanced](#), below.
 - Set the baud rate to 9600.

To enable the CFX-750 display to change the rates on the controller, you must also set the Rawson controller to GPS mode:

1. Turn the Rawson controller on.
2. Press the MODE button twice.
3. Press the SET button to switch the controller between GPS and non-GPS modes.

Note – If you do not set the Rawson controller to use GPS mode, the CFX-750 display will only log the rates being used.

For more information on configuring the Rawson controller, refer to the *ACCU-RATE Controller 9.2A User Guide*.

Advanced

Use the *Advanced* option in the *Implement* screen to configure the following:

- Boom Setup
- Swath Control
- Target Rate
- Default Rate
- Step Size
- Rate Snapping

Boom Setup

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Target Rate

Set the target application rate that will be sent to the Rawson controller. Enter a rate between 0.0 - 11000.0.

Alternatively, you can load a prescription so the CFX-750 display will automatically send target rates to the Rawson controller.

Note – When the CFX-750 display is sending target rates to the Rawson controller, the Rawson controller will only display the Target Rate screen. To change or view any other screen on the Rawson controller, you must unplug the CFX-750 display cable.

Note – When using a prescription with the Rawson controller, the target rates in the prescription must match the step sizes in the Rawson controller. For example, if the default is 25000 and the step size is 4%, then the target rate values accepted by the Rawson controller are 26000, 27000, 28000...40000. Otherwise, the Rawson controller may not be able to apply the correct rate.

Default Rate

On the CFX-750 display, set the same target rate that appears on the Rawson controller when you first power up it up. Enter a number between 0 - 9999000.

Step Size

The step size increases or decreases the actual applied rate by the percentage that you select. You can choose from one of the following settings:

- 2%
- 4%
- 6 ²/₃%

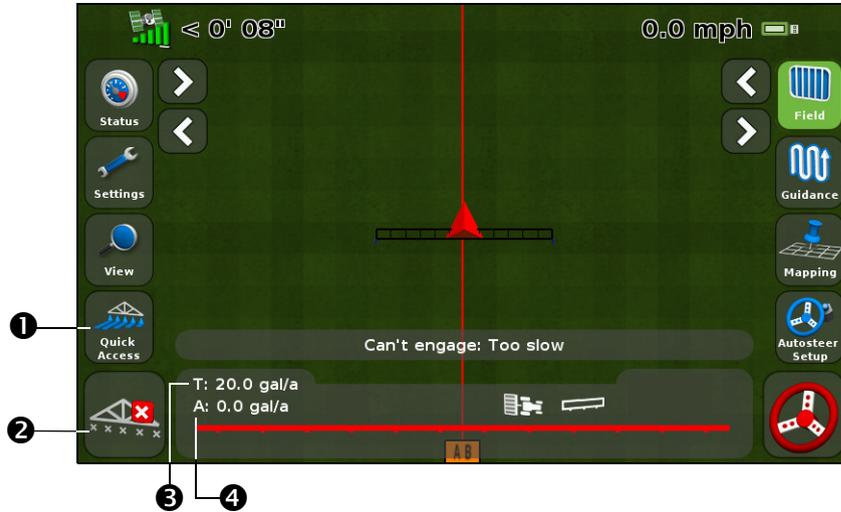
Rate Snapping

Due to pump constraints, liquid flow is generally inconsistent. To control how these inconsistencies appear on your display, turn rate snapping on or off.

Setting ...	Notes ...
On	Matches the actual applied rate to the target rate when within 10% of the value.
Off	Shows all fluctuations in the actual applied rate.

Operation

When you connect the Rawson controller to the display, the following items appear on the CFX-750 guidance screen:

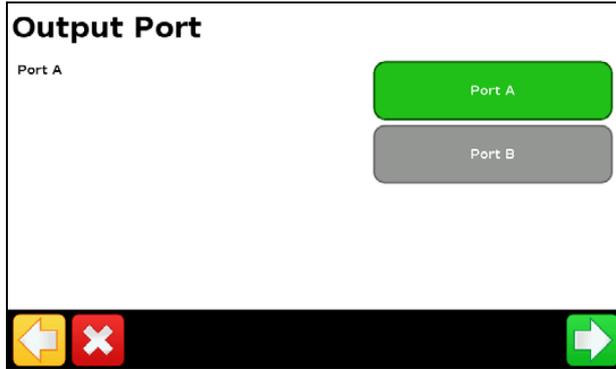


Item	Description	Notes
1	Quick Access icon	See Quick Access icon , page 34.
2	Boom section status indicators	Shows the current state of each boom section: <ul style="list-style-type: none"> Green: Enabled and spraying Gray: Enabled but not currently spraying Red: The section is off (the switch is off)
3	Target rate	If a prescription is loaded, P displays to indicate that the prescription rate is being used rather than the target rate.
4	Actual rate	The actual application rate. This is the amount of product that is currently being applied.
	Application indicator	The wheel on the display spins when the Rawson master switch is on and the lightbar receives flow messages from the controller.

Amazone controller

Setup

1. Once you select Amazone as your controller, the following screen appears on the display:



Note – Do not configure the display to output NMEA messages on the same port that your controller is connected to.

2. On the Amazone controller, go to the *Settings* menu.
3. Change Remote to Enable.

For more information on setting up the Amazone controller, refer to the Amazone instruction manual.

Advanced

Use the *Advanced* option in the *Implement* screen to configure the following:

- Boom Setup
- Swath Control
- Rate Control
- Target Rate
- Turn Off Rate on Overlap
- Rate Snapping

Boom Setup

Note – The boom setup on the CFX-750 display must match the setup on the Amazone controller. If the boom setup differs between the display and the Amazone controller, a warning message appears on the display.

Use this option to view and adjust the following settings:

Settings ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Fence Nozzles	Enter the locations of any fence nozzles.
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Settings ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Rate control

Use this option to view and adjust the following settings:

Settings ...	Notes ...
On	Application rates are sent from a prescription loaded in the display or the target rate manually configured on the display.
Off	The target rate must be set on the Amazone controller. The CFX-750 display does not send target rates to the controller. This is the default setting.

Note – When sending a target rate to the Amazone controller that is higher than 99.9, the display rounds to the nearest whole number. For example, 0-99.9 is not rounded. 101.4 is rounded to 101.

Target Rate

Set the target application rate that will be sent to the Amazone controller. Enter a rate between 0.0 - 11000.0.

Turn Off Rate on Overlap

Use this option to view and adjust the following settings:

Settings ...	Notes ...
Yes	Does not spray over an area that has been previously sprayed.
No	Sprays over an area that has been previously sprayed.

Operation

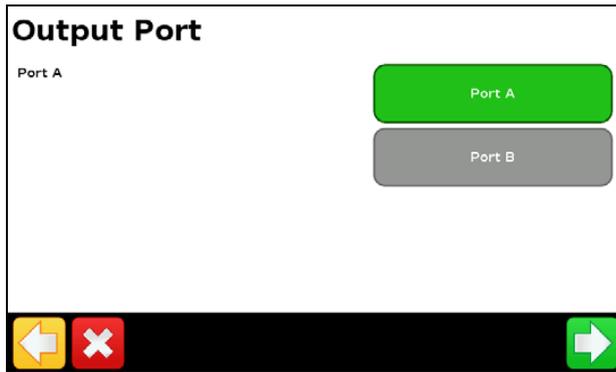
When you connect the Amazone controller to the display, the following items appear on the display's guidance screen:

Item	Notes
Actual rate	
Target rate	If a prescription is loaded, P displays to indicate that the prescription rate is being used rather than the target rate.
Boom section status indicators	Shows the current state of each boom section: <ul style="list-style-type: none"> • Green: Enabled and spraying • Gray: Enabled but not currently spraying • Red: The section is off (the switch is off)
Application indicator	The wheel on the display spins when the Amazone master switch is on and the lightbar receives flow messages from the controller.
Quick Access icon	See Quick Access icon , page 34.

LH 5000 controller

Setup

1. Once you select the LH5000 as your controller, the following screen appears on the display:



2. On the CFX-750 display, make sure that Output Port matches the port on the display that the controller is connected to (COM or AUX).
3. Do not configure the display to output NMEA messages on the same port that your controller is connected to.

For more information on configuring the LH 5000 controller, refer to the LH 5000 instruction manual.

Advanced

Use the *Advanced* option in the *Implement* screen to configure the following:

- Boom Setup
- Swath Control
- Rate Control
- Target Rate
- Turn Off Rate on Overlap
- Rate Snapping

Boom Setup

Note – The boom setup on the CFX-750 display must match the setup on the LH 5000 controller. If the boom setup differs between the display and the LH 5000 controller, a warning message appears on the display.

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Fence Nozzles	Enter the locations of any fence nozzles.
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Rate control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
On	Application rates are sent from a prescription loaded in the display or the target rate manually configured on the display.
Off	The target rate must be set on the LH 5000 controller. The CFX-750 display does not send target rates to the controller. This is the default setting.

Note – When sending a target rate to the LH 5000 controller that is higher than 99.9, the display rounds to the nearest whole number. For example, 0-99.9 is not rounded. 101.4 is rounded to 101.

Target Rate

Set the target application rate that will be sent to the LH 5000 controller. Enter a rate between 0.0 - 11000.0.

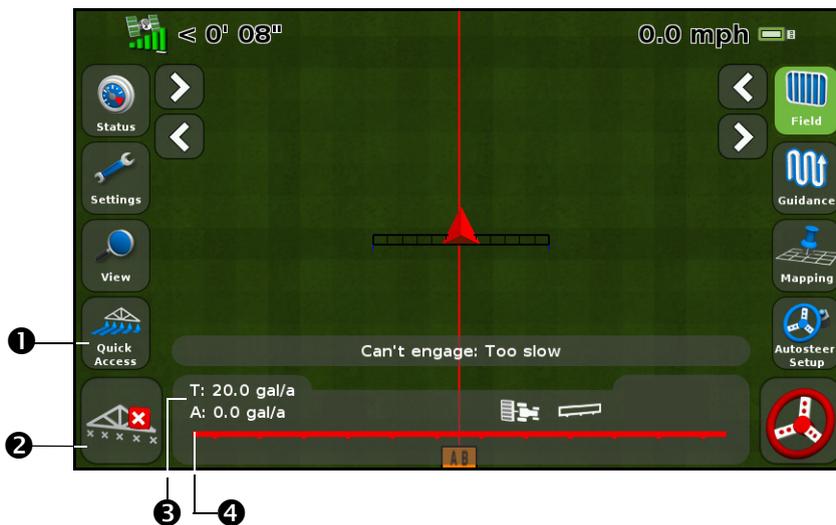
Turn Off Rate on Overlap

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Yes	Does not spray over an area that has been previously sprayed.
No	Sprays over an area that has been previously sprayed.

Operation

When the LH 5000 variable rate controller is connected to the display, the following items appear on the CFX-750 display's guidance screen:

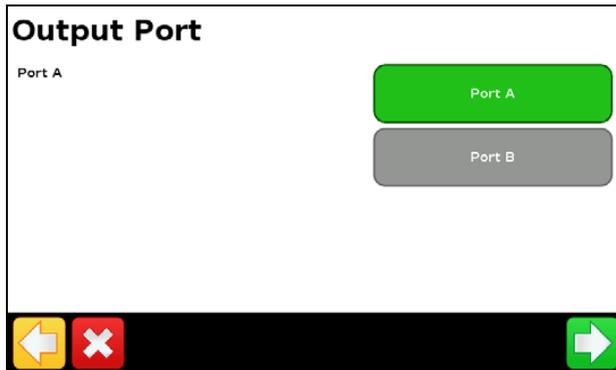


Item	Description	Notes
❶	Quick Access icon	See Quick Access icon , page 34.
❷	Boom section status indicators	Shows the current state of each boom section: <ul style="list-style-type: none"> • Green: Enabled and spraying • Gray: Enabled but not currently spraying • Red: The section is off (the switch is off)
❸	Target rate	If a prescription is loaded, P displays to indicate that the prescription rate is being used rather than the target rate.
❹	Actual rate	The actual application rate. This is the amount of product that is currently being applied.
	Application indicator	The wheel on the display spins when the LH 5000 master switch is on and the lightbar receives flow messages from the controller.

Vaderstad controller

Setup

1. Once you select Vaderstad as your controller, the following screen appears on the display:



Note – Do not configure the display to output NMEA messages on the same port that your controller is connected to.

2. In the Device Type screen, select the type of implement you are using:
 - Sprayer
 - Planter/Seeder
 - Fertilizer/Spreader
3. On the Vaderstad controller, go to the setup screen.
4. Set GPS to No.

Advanced

Use the Advanced option in the Implement screen to configure the following:

- Boom Setup
- Swath Control
- Rate Control
- Target Rate
- Single section boom switching
- Rate Snapping

Boom Setup

Note – The boom setup on the CFX-750 display must match the setup on the LH 5000 controller. If the boom setup differs between the display and the LH 5000 controller, a warning message appears on the display.

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Fence Nozzles	Enter the locations of any fence nozzles.
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Rate control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
On	Application rates are sent from a prescription loaded in the display or the target rate manually configured on the display.
Off	The target rate must be set on the LH 5000 controller. The CFX-750 display does not send target rates to the controller. This is the default setting.

Note – When sending a target rate to the LH 5000 controller that is higher than 99.9, the display rounds to the nearest whole number. For example, 0-99.9 is not rounded. 101.4 is rounded to 101.

Target Rate

Set the target application rate that will be sent to the LH 5000 controller. Enter a rate between 0.0 - 11000.0.

Single section boom switching

Use this to turn off the implement in areas that have already been applied.

Note – This setting can only turn the entire boom on and off. It does not support individual sections.

- Select Yes to avoid spraying an area that has previously been sprayed.
- Select No to spray an area that has previously been sprayed.

Rate Snapping

Due to pump constraints, liquid flow is generally inconsistent. To control how these inconsistencies appear on your display, turn rate snapping on or off.

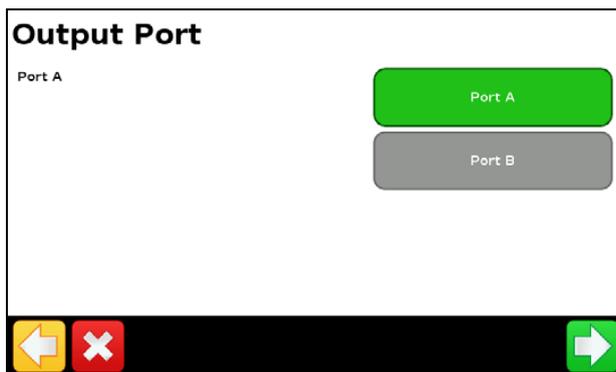
Value ...	Notes ...
On	Matches the applied rate to the target rate when within 10% of the value.
Off	Shows all fluctuations in the actual applied rate.

Bogballe controller

The CFX-750 display is compatible with Bogballe Calibrator ZURF, ICON, and UNIQ controllers.

Setup

1. Once you select Bogballe as your controller, the following screen appears on the display:



Note – Do not configure the display to output NMEA messages on the same port that your controller is connected to.

- On the Bogballe controller, press Return / Return / Fertil.-Distrib / Select Type / Bogballe E/EX / Accept

For more information on setting up the Bogballe controller, refer to the Bogballe instruction manual.

Advanced

Use the Advanced option in the Implement screen to configure the following:

- Boom Setup
- Swath Control
- Rate Control
- Target Rate
- Single Section Boom Switching

Boom Setup

Note – The boom setup on the CFX-750 display must match the setup on the LH 5000 controller. If the boom setup differs between the display and the LH 5000 controller, a warning message appears on the display.

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Implement width	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Fence Nozzles	Enter the locations of any fence nozzles.
Number of sections	Enter a number between 1 - 10.

Swath Control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
Boom control	Enter a width between 1' 00" - 328' 01" (0.30 - 99.99 m).
Coverage switching overlap	Control the amount of boom switching overlap allowed before the section will be switched by the system. Enter a value between 1 - 99%.
Boundary switching overlap	Control the amount of overlap on a boundary before the boom section is switched off. Enter a value between 1 - 99%.
On/Off valve latency	Tune the section switching to allow for hardware delays. Enter a time between 0.0 - 10.0 seconds.
Intentional overlap	Set a distance to be overlapped when moving to an unsprayed area or out of a sprayed area. Enter a distance between 0' 00" - 32' 10" (0.00 - 10.00 m).

Rate control

Use this option to view and adjust the following settings:

Setting ...	Notes ...
On	Application rates are sent from a prescription loaded in the display or the target rate manually configured on the display.
Off	The target rate must be set on the LH 5000 controller. The CFX-750 display does not send target rates to the controller. This is the default setting.

Note – When sending a target rate to the LH 5000 controller that is higher than 99.9, the display rounds to the nearest whole number. For example, 0-99.9 is not rounded. 101.4 is rounded to 101.

Target Rate

Set the target application rate that will be sent to the LH 5000 controller. Enter a rate between 0.0 - 11000.0.

Single section boom switching

Use this to turn off the implement in areas that have already been applied.

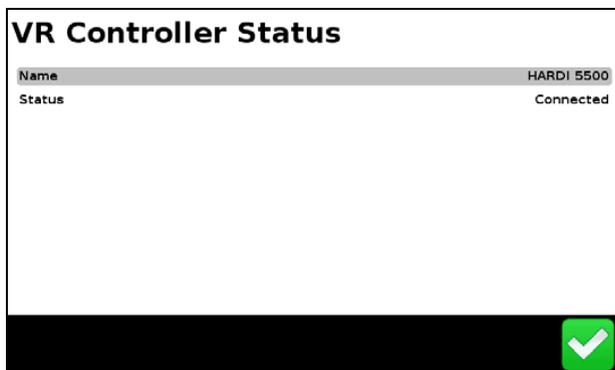
Note – This setting can only turn the entire boom on and off. It does not support individual sections.

- Select Yes to avoid spraying an area that has previously been sprayed.
- Select No to spray an area that has previously been sprayed.

Checking the implement connection

To check that the CFX-750 display and your implement controller are communicating correctly, access the *VR Controller Status* screen:

1. In the *Settings* screen, tap **Vehicle** and then tap **Status**.
2. Tap **VR Controller Status**. A screen similar to the following appears:



3. Check that the status displays *Connected*.

Note – *If the status displays Not Connected, verify that the controller cable is securely connected to the display. If the cable is secure, verify that the display and the controller are configured correctly, as detailed in the sections above.*

Field-IQ Crop Input Control System

In this chapter:

- [Overview](#)
- [Installing the Field-IQ hardware](#)
- [Setting up the Field-IQ system](#)
- [Operation](#)

The Field-IQ crop input control system enables the CFX-750 display to control the following:

- planters
- sprayers
- liquid strip-till toolbars
- spinner spreaders

Additionally, it enables the display to use the Tru Count Air Clutch® or Tru Count LiquiBlock™ valves to perform automatic section control, and/or use a prescription with Rawson® drives to control seed or liquid fertilizer rates.

Overview

The different functions of the Field-IQ system that you can configure and control are:

Application	Main functions
Planter	<ul style="list-style-type: none"> Seed section control of up to 48 individual rows (Field-IQ section control module(s) needed) using the Tru Count Air Clutch. Seed rate control using up to 4 Rawson drives to change seed population (Field-IQ Rawson Control Module(s) needed). Seed rate control using up to 4 PWM drives to change seed population. Liquid fertilizer control of up to 48 individual liquid nozzles (Field-IQ section control module(s) needed) using Tru Count LiquiBlock valves.
Sprayer	<ul style="list-style-type: none"> Liquid section control of up to 48 individual rows (Field-IQ section control module(s) needed) using existing boom shutoff valves or Tru Count LiquiBlock valves. Connects to spraying systems that are configured with servo, pump servo, PWM, bypass, dump and master valves.
Strip-till (liquid)	<ul style="list-style-type: none"> Liquid section control of up to 48 individual spray nozzles (Field-IQ Section Control Module(s) needed) using Tru Count LiquiBlock valves. Liquid rate control using up to 2 Rawson drives connected to fixed displacement pumps, such as CDS-John Blue piston pumps, to change liquid rate (Field-IQ Rawson Control Module(s) needed). Liquid rate control using either a PWM or Servo control valve and flow meter.
Spreading	<ul style="list-style-type: none"> Spreading rate control using a Rawson Drive (Field-IQ Rawson Control Module(s) needed). Spreading rate control using either a PWM or Servo control valve and application rate sensor.

Definitions

Term	Definition
Section	A number of rows or spray nozzles that are controlled by the Tru Count Air Clutch or Tru Count LiquiBlock valves, or boom valves. A section can have either a single row/nozzle or multiple rows/nozzles depending on how the system is set up.
Row	The individual row unit that material comes from on the implement. This can be controlled individually as a single row section, or as a group with other rows in a multiple row section.
Master Switch Box (MSB)	Master on/off/jump start, auto/manual switch, rate selection, and increment/decrement switch. See Field-IQ master switch box, page 148
12 Section Switch Box (12SSB)	Required for section control. Manually control sections/rows. See Field-IQ 12-section switch box, page 149
Section Control Module (SCM)	Controls 12 sections/rows per module with up to 4 modules (48 module sections / rows).

Term	Definition
Rate and Section Control Module (RSCM)	Controls 12 sections and application rate for spraying, spreading and NH ₃ .
Rawson Control Module (RWCM)	Controls 1 Rawson variable rate drive per module with up to 4 modules.
Implement Switch	Included in planter, NH ₃ and strip-till platform kits.

Units of measure

Type	Unit	Symbol	Description
Seed	Metric	kS/ha	Thousands of seeds per hectare
	US/Imperial	kS/a	Thousands of seeds per acre
Granular seed	Metric	kg/ha	Kilograms of seed per hectare
	US/Imperial	lbs/a	Pounds of seed per acre
Liquid application	Metric	L/ha	Liters per hectare
	US/Imperial	Gal/a	Gallons per acre
Granular fertilizer	Metric	kg/ha	Kilograms of fertilizer per hectare
	US/Imperial	lbs/a	Pounds of fertilizer per acre
NH ₃	Metric	kg/NH ₃	Kilograms of anhydrous per hectare
	US/Imperial	lbs/NH ₃	Pounds of anhydrous per acre
	Metric	kg/N	Kilograms of nitrogen per hectare
	US/Imperial	lbs/N	Pounds of nitrogen per acre

Installing the Field-IQ hardware



WARNING – Anhydrous ammonia (NH₃) can cause severe burning, blindness, or death. Before you begin to operate or service equipment that contains NH₃, carefully read and follow all safety instructions in [Working with anhydrous ammonia, page 7](#).

For information on installing the Field-IQ crop input control system on your implement, refer to:

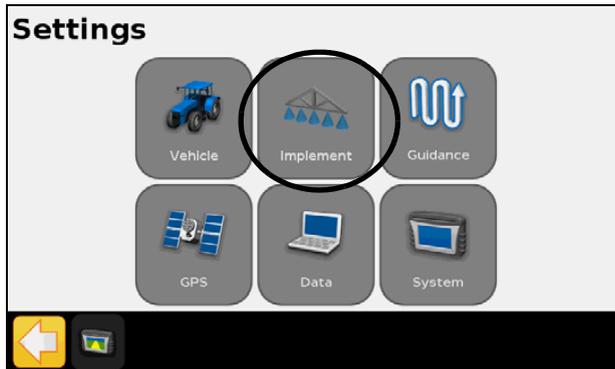
- *Field-IQ Platform Installation Instructions*
- *Tru Count Air Clutch Installation Instructions*
- *Rawson Installation Instructions*

For the latest versions of these documents, go to www.trimble.com/agriculture.

Setting up the Field-IQ system

Setting up the Implement and Control type

1. In the guidance screen, tap .
2. In the *Settings* screen, tap **Implement**:

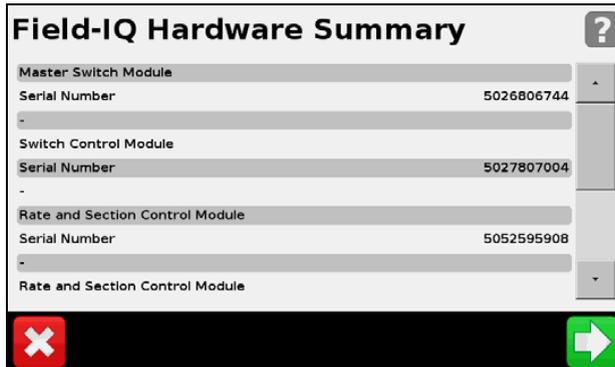


3. In the *Implement* screen, tap **Initial Setup**.

Note – When you are setting the system up for the first time, this is the only button that appears. However, if you have previously installed the Field-IQ system, more options will appear.

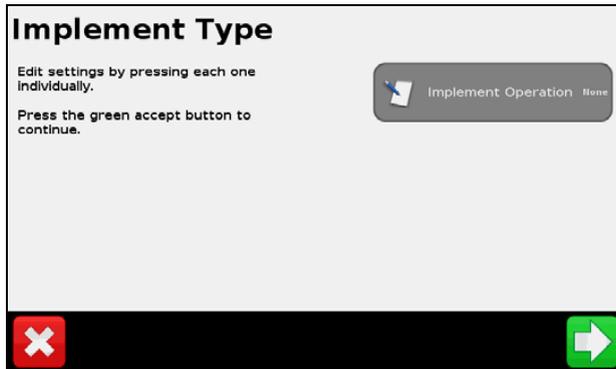
4. In the *Controller Type* screen, tap **Field-IQ** and then tap .

A *Summary* screen appears that shows all the Field-IQ components (with their serial numbers) detected by the display. To continue, tap :



Setting up the Implement Operation and Implement Layout

1. In the *Implement Type* screen, tap **Implement Operation**:



2. In the *Implement Operation* screen, tap the required operation and then tap :



3. In the *Implement Type* screen, tap **Implement Layout**.

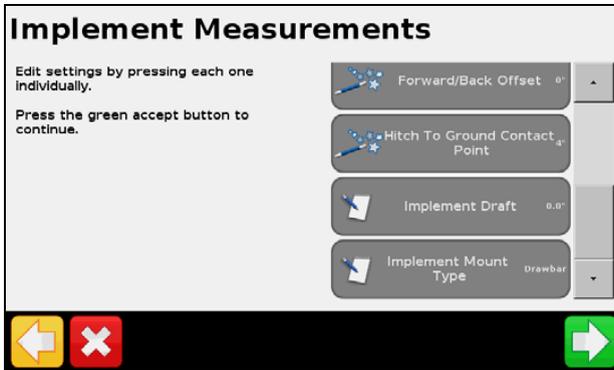
The options that you can select depend on the operation you selected. The options are:

Implement operation	Implement layout options
Spreading	Pull-type spreader Spreader truck
Spraying	Front sprayer Rear sprayer Pull-type sprayer
Planting	Standard
Tillage	Tillage

4. Once you select both the Implement Operation and the Implement Layout, tap .

Setting up the Implement Measurements

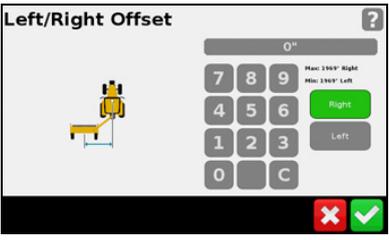
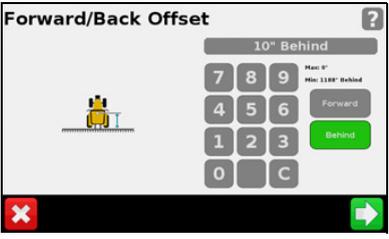
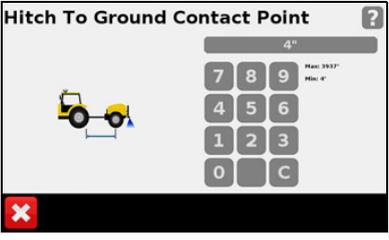
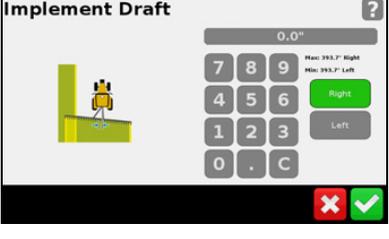
1. In the *Implement Measurements* screen, tap each option in turn to enter the measurements for your implement:

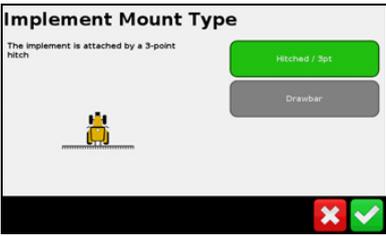
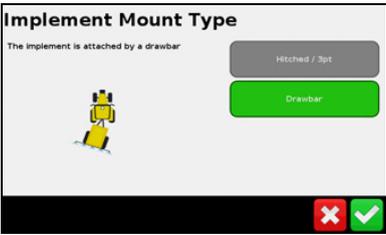


2. Once you enter the required measurements in a settings screen, tap  to return to the *Implement Measurement* screen and select the next option.

For the best performance, physically measure your implement and enter accurate values for each setting. The options are:

Tap	Description	
Number of Rows	Number of rows covered by the implement.	
Row Spacing	Spacing between the rows.	
Overlap / Skip	<p>The amount of overlap or skip between swaths.</p> <ul style="list-style-type: none"> • Overlap is a intentional overlap between swaths to avoid any skips. • Skip is a intentional skip between swaths. <p>Note – This setting is used with the <i>Implement Width</i> to set the spacing of the swaths in the field.</p>	
Implement Width	<p>The width of the implement’s application coverage area. This measurement is used for coverage logging.</p> <ul style="list-style-type: none"> • For planters this is calculated using the Number of Rows and the Row Spacing. • The swath spacing is calculated by the Implement Width and the Overlap/Skip setting. 	

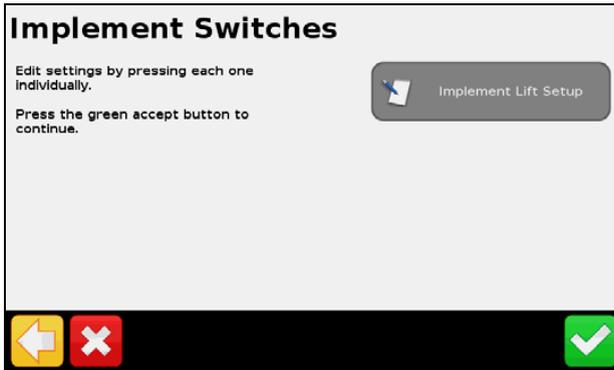
Tap	Description	
Left / Right Offset	<p>Used for implements that are offset to the left or right from the vehicle center line.</p> <p>This is measured from the center of the vehicle to the center of the implement.</p> <p>The measurement adjusts the tractor's path so that the implement is centered on the line.</p>	
Forward / Back Offset	<p>Used to reference the distance from the vehicle to the implement / application point.</p> <p>The offset is measured from the fixed axle of the vehicle to the point on the implement where coverage logging will be mapped.</p> <p>The fixed axle varies depending on vehicle type:</p> <ul style="list-style-type: none"> • Rear axle on front steering tractors and self-propelled sprayers • Front axle on 4 x 4 articulated tractors • Center of tracks on tracked tractors 	
Hitch to Ground Contact Point	<p>Distance from the hitch to where the implement pivots on its ground contact point.</p> <p>Measured from the tractor's hitch pin to the soil engagement point that the implement rotates about.</p> <p>For planters this is typically the seeding units or the midpoint of several rows of tools.</p>	
Implement Draft	<p>Distance that the implement drifts away from the center line of the vehicle.</p> <p>This setting is used to adjust the implement back on line if the implement is physically drifting offline in the field.</p> <p>Note – This setting is similar to the Left/Right Offset.</p>	

Tap	Description	
Implement Mount Type	<p>Select the required mount type:</p> <ul style="list-style-type: none"> Hitched / 3pt: The implement is mounted on a 3-point hitch, which means that the implement rotates around the vehicle. <p>Note – When the vehicle makes a slight correction you will instantly see a change in the implement’s location.</p> <ul style="list-style-type: none"> Drawbar: The implement is attached by a drawbar, which means that the implement rotates around its ground contact point. <p>Note – When the vehicle makes a correction you may not see a change in the implement until a certain distance has been traveled.</p>	 

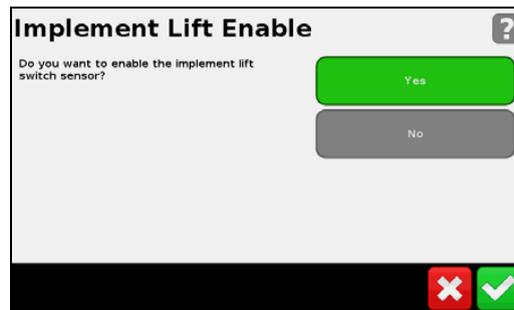
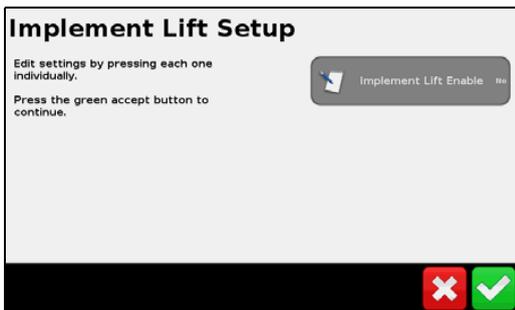
3. Once you enter all the required measurements, tap .

Setting up the Implement Switches

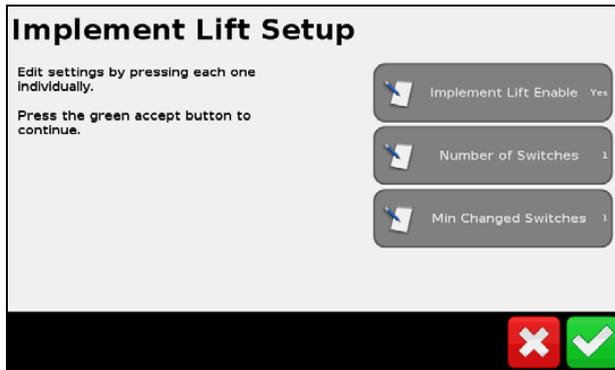
1. In the *Implement Switches* screen, tap **Implement Lift Setup**:



2. In the *Implement Lift Setup* screen, tap **Implement Lift Enable**, tap **Yes** in the *Implement Lift Enable* screen and then tap :



- You are returned to the *Implement Lift Setup* screen, where you can now set up the following:



Tap	Description
Number of Switches	Number of implement switches hooked up to the Field-IQ system.
Min Changed Switches	Number of switch changes that are required to show the implement in a lifted state. For example, if three switches are hooked up to the Field-IQ system and this setting is set to two, the system must see two switches in the lifted position before the implement appears as lifted on the display.

- Tap  when done.

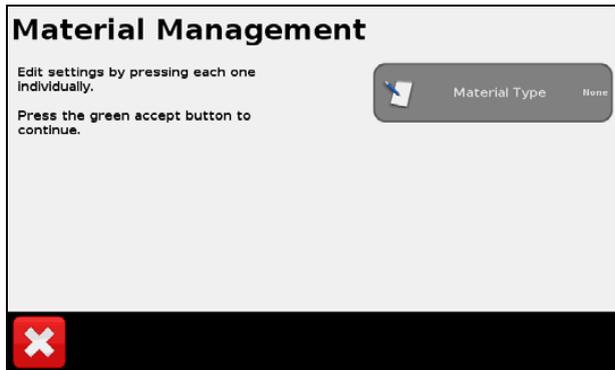
Setting up a Material

- In the *Implement* screen, tap **Material Setup**:

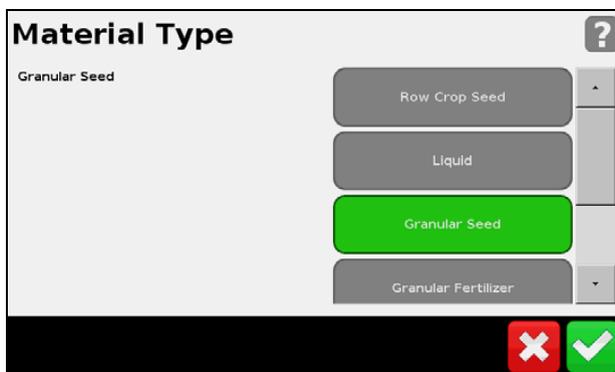


- In the *Material Setup* screen, tap **New Material**.

3. In the *Material Management* screen, tap **Material Type**:



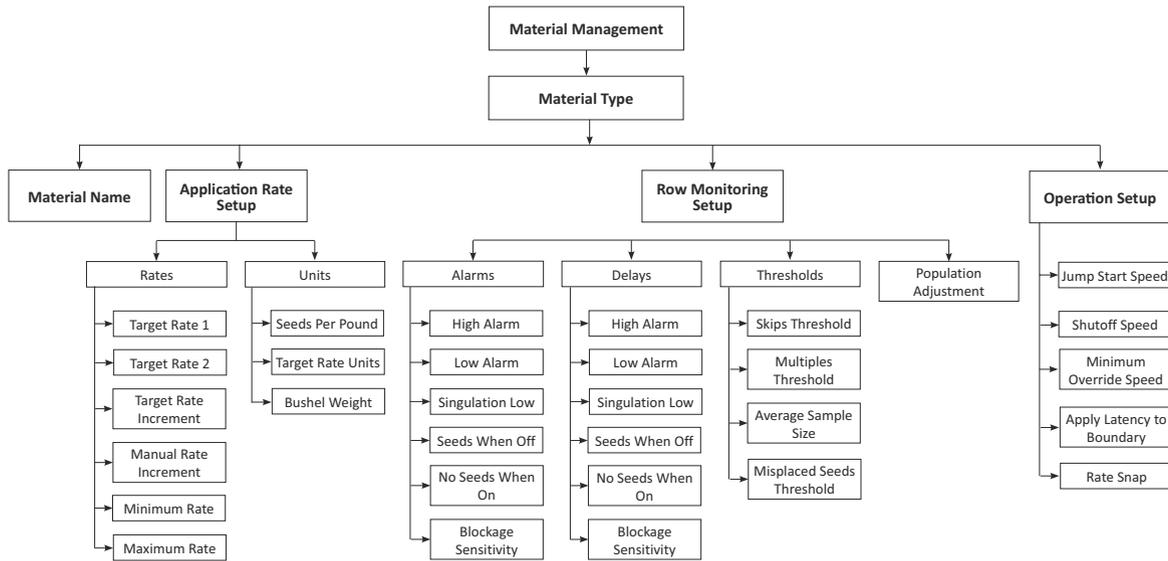
4. In the *Material Type* screen, select the material type you require:



The options are:

- Row Crop Seed
 - Liquid
 - Granular Seed
 - Granular Fertilizer
 - Anhydrous
5. Once you make your selection, tap  to return to the *Material Management* screen.
From this screen, you can now set up a specific material type.

Setting up a Row Crop Seed in the Material Setup screen



Once you select a *Material Type*, in the *Material Management* screen, tap **Material Name**, enter a name for the material and then tap .

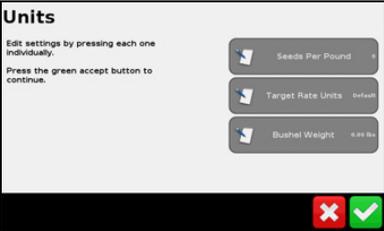
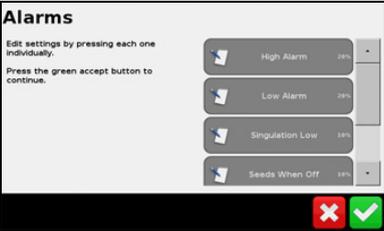
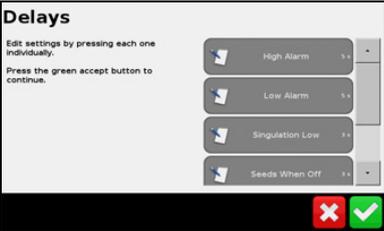
Once you have done this, the following options appear in the *Material Management* screen:

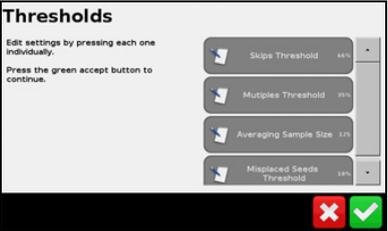
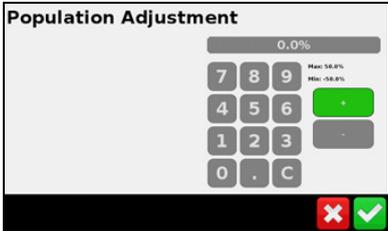
- Application Rate Setup
- Row Monitoring Setup
- Operation Setup

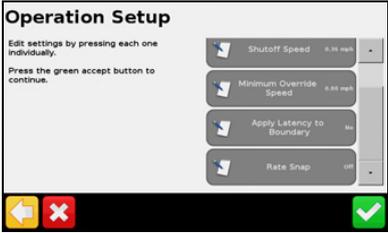
Select each option in turn and complete all settings for that option until you reach the final screen for that option—if you then tap , you are returned to the *Material Type* screen where you can select the next option.

The options are as follows:

Select ...	Options	Description
	Application Rate Setup: Rates	
	Target Rate 1	Preset rate for position 1 on the rate switch.
	Target Rate 2	Preset rate for position 2 on the rate switch.
	Target Rate Increment	Rate increase / decrease for Target Rate 1 or 2, when the Rate Adjustment Switch is clicked once.
	Manual Rate Increment	Valve movement when the Rate Adjustment Switch is used with the Rate Switch set to Manual.
	Minimum Rate	Minimum rate that will be applied with this material.
	Maximum Rate	Maximum rate that will be applied with this material.

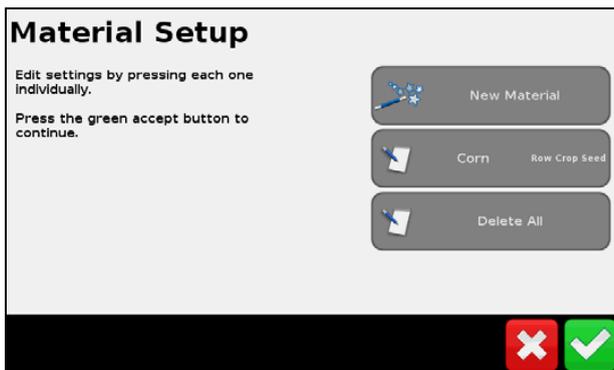
Select ...	Options	Description
Application Rate Setup: Units		
	Seeds Per Pound	Number of seeds per pound.
	Target Rate Units	If you select this option, you can select on the following in the <i>Target Rate Units</i> screen: <ul style="list-style-type: none"> • Default (kS/a or kS/ha) • Bushels
	Bushel Weight	Weight per bushel.
Row Monitoring Setup: Alarms		
	High Alarm	Triggers when the seed sensor population rises above the selected percentage from the Target Rate for longer than the delay time.
	Low Alarm	Triggers when the seed sensor population drops below the selected percentage from the Target Rate for longer than the delay time.
	Singulation Low	Triggers when the singulation drops below the selected percentage lower than 100% for longer than the delay time.
	Seeds When Off	Triggers when this percentage of seeds are detected while the sections are off for longer than the delay time.
	No Seeds When On	Triggers when this percentage of seeds are not detected for longer than the delay time.
	Blockage Sensitivity	Triggers when less than this amount of material is sensed for longer than the delay time.
Rate Monitoring Setup: Delays		
	High Alarm	Amount of time that the row sensor population has to be above the High Alarm setting before warning.
	Low Alarm	Amount of time that the row sensor population has to be below the Low Alarm setting before warning.
	Singulation Low	Amount of time that the singulation has to be below the Singulation Alarm setting before warning.
	Seeds When Off	Amount of time that the Seeds When Off setting is above the Seeds When Off Alarm setting before warning.
	No Seeds When On	Amount of time that the Seeds When On is above the No Seeds When On Alarm setting before warning.
	Blockage Alarm	Amount of time that the Blockage Alarm is outside the Alarm setting before warning.

Select ...	Options	Description
Rate Monitoring Setup: Thresholds 	Skips Threshold	If no seeds fall within the percentage of theoretical seed placement, it is considered a Skip.
	Multiples Threshold	If two or more seeds fall within the percentage of the theoretical seed placement, it is considered a Multiple.
	Average Sample Size	The number of seeds used to calculate the averages.
	Misplaced Seeds Threshold	If seeds fall outside of this percentage from the theoretical seed placement, they are considered misplaced and will reduce the spacing quality.
	Population Adjustment	Adjusts the population reading of the seed sensors, independent of the Rate Population.
Rate Monitoring Setup: Population Adjustment 		Set the <i>Population Adjustment Percentage</i> . Note – In most cases this Adjustment setting will be 0%. This feature is for Higher Population Planting.

Select ...	Options	Description
Operation Setup 	Jump Start Speed	The speed that the control system will use when the master switch is held in the Jump Start Position. Note – The Rate Switch has to be in Position 1 or 2 for the Jump Start Feature to work.
	Shutoff Speed	The system will shut down if the vehicle drops below this speed.
	Minimum Override Speed	The system will continue to run at this speed if the vehicle drops below this speed.
	Apply Latency to Boundary	<ul style="list-style-type: none"> • Yes: The system starts when needed to begin applying immediately when crossing a boundary. • No: The system starts when the boundary is reached and any mechanical delay could leave a gap between the boundary and where the product is applied. When GPS accuracy is low, this is the preferred selection. <p>Note – This setting only applies to fields that have a boundary.</p> <p>Note – This setting is also applied when you exit an exclusion zone and return to the workable area of the field.</p>
	Rate Snap	<ul style="list-style-type: none"> • Enabled: Shows the Applied Rate the same as the Target Rate when the Applied Rate is within 10% of the Target Rate. • Off: Shows the actual Applied Rate.

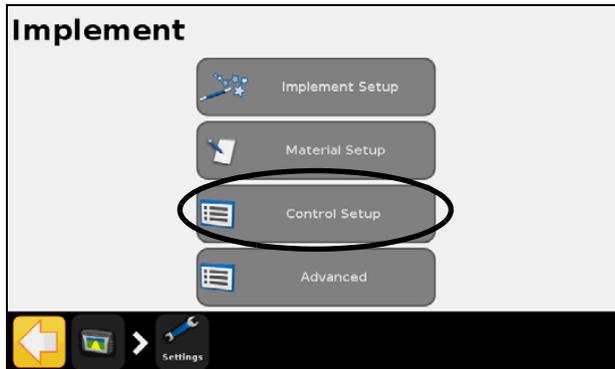
Once you complete all the *Material Type* options, tap  to return to the *Material Setup* screen.

Note – Once you tap  in the *Operation Setup* screen, the setup of this material is complete. The *Material Setup* screen now shows **New Material** and **Delete All** buttons and a list of the materials you have set up:

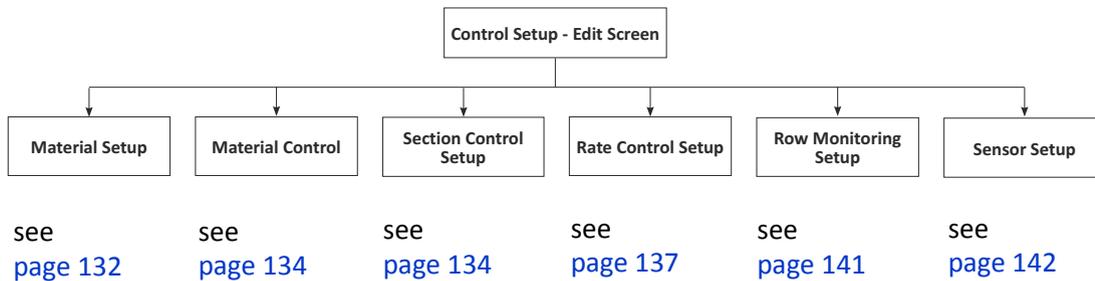


Setting up a Location

1. In the *Implement* screen, tap **Control Setup**:



2. In the *Control Setup* screen, tap the location button for the location you want to set up. If this is the first time that you are setting up a control setup, there will be one button only, **Unassigned**.
3. In the *Unassigned* screen, tap **Edit**.



4. In the *Edit* screen, select each option in turn and complete all options and settings. If you tap  you are either taken to the next screen in a sequence, or returned to the *Edit* screen where you can select the next option. Additional options appear as you complete each one.

Material Setup

The *Material Setup* screen allows you to easily switch the materials into a control location. The location button shows the name of the location and the material that is currently assigned.

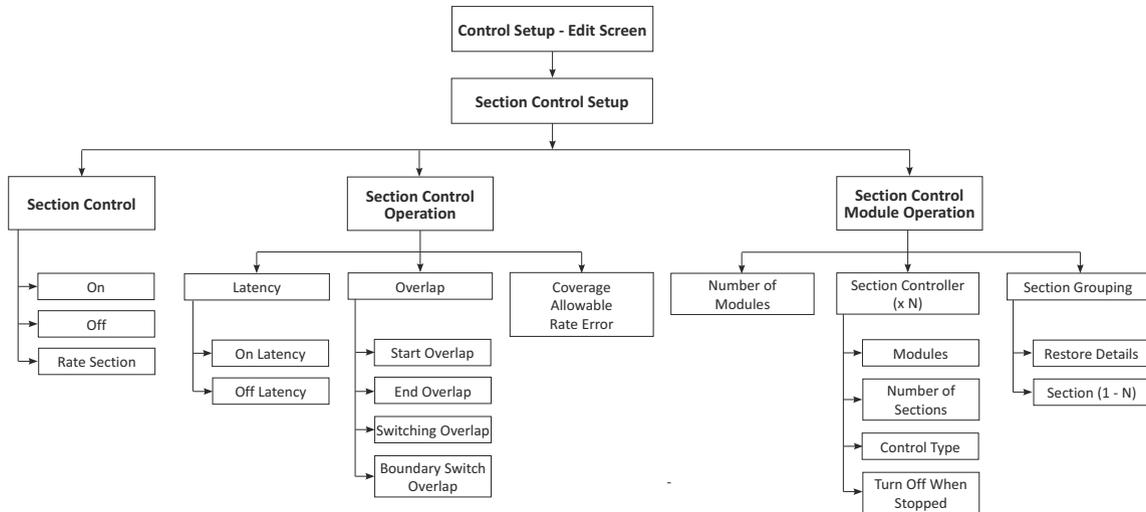
Select	Options	Description
Location Name		Select the location name.

Select	Options	Description
<p>Material Assignment</p>  	<p>No Material</p> <p>Named materials (for example, Corn, Soy)</p>	<p>This is the default of a location and means that the location is disabled.</p> <p>Select a material to assign to the location. To change the material, tap the location button (in this example Hoppers) and select a new material. To disable the location, select <i>No Material</i>.</p> <p>Note – If the material you require is not listed, exit from this screen and then set it up using the <i>Material Setup</i> procedures. See Setting up a Material, page 126.</p>

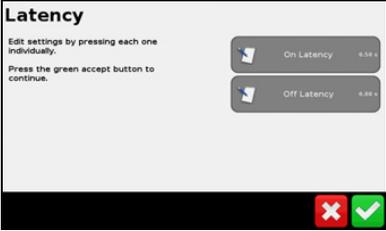
Material Control

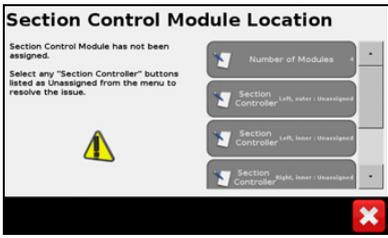
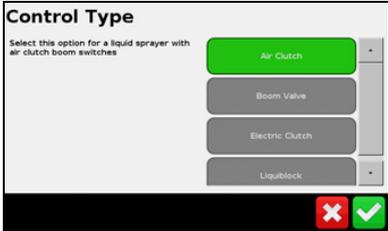
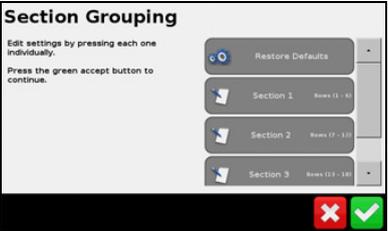
Select	Options	Description
Material Control	Switch Boxes	The location is linked to both the master switch box and the 12-section switch box.
	Touchscreen Only	The location is controlled from the touchscreen. Note – The CFX-750 display requires the use of a 12-section switch box for section control.

Section Control Setup

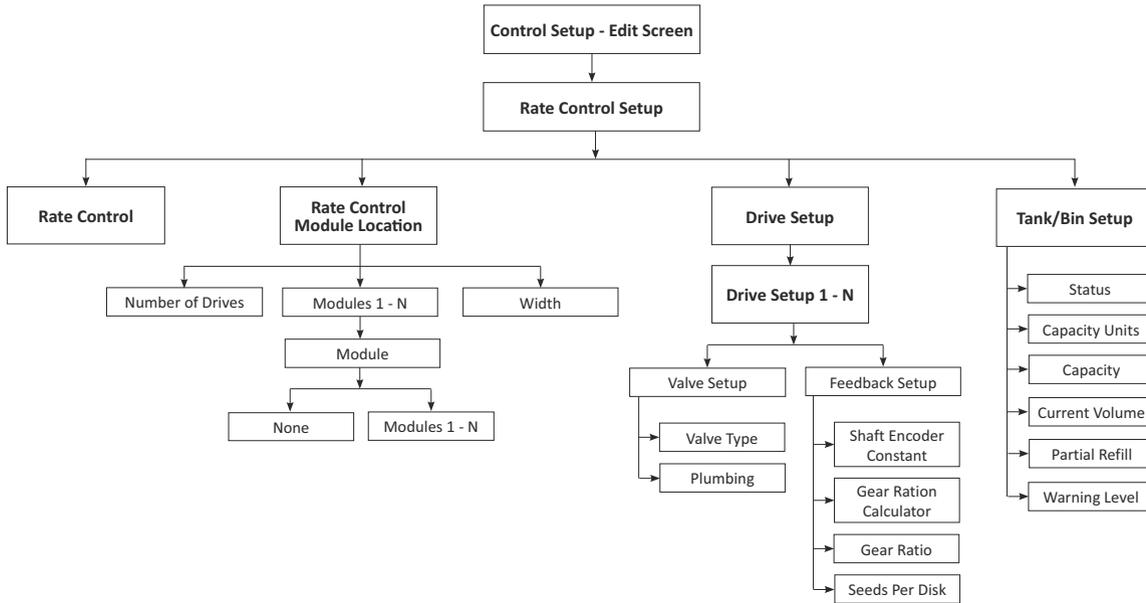


Select	Options	Description
	On	Turn section control on.
	Off	No section control used for this location.
	Rate As Section	Use the rate control as section control. Note – This means that the rate will go to zero and shut down the control in a covered area or non-productive zone.

Select	Options	Description
Section Control Operation: Latency 	On Latency <hr/> Off Latency	The length of time that is required before a material is applied when the section is turned on. <hr/> The length of time that is required before a material stops applying once the section is turned off.
Section Control Operation: Overlap 	Start Overlap <hr/> End Overlap <hr/> Coverage Switch Overlap <hr/> Boundary Switch Overlap	The amount of intentional overlap required when leaving already covered area and going into a non-covered section of the field. <hr/> The amount of intentional overlap required when going into a covered area. <hr/> The amount of side-to-side coverage overlap before a section shuts down. <hr/> The amount of side to side boundary overlap before a section shuts down.
Section Control Operation: Coverage Allowable Rate Error		Set the coverage allowable rate error. Note – This setting is used only if you are running very large fields.
Section Control Module Location		This option appears if the <i>Section Control</i> is set to On .
Section Control Module Location: Number of Modules		Select the total number of section control modules for this location.
		

Select	Options	Description
<p>Section Control Module Location: Section Controller</p> 	<p>Modules</p>	<p>Select each module in turn and complete its setup before continuing with the next module.</p> <p>Select the serial number of the module that you want to assign to the location.</p>
	<p>Number of Sections</p> <p>Control Type</p>	<p>Select the number of section to assign to the selected module.</p> <p>Select the section control type. The options are:</p> <ul style="list-style-type: none"> • Air Clutch: The section control module sends power to the section valve to turn the clutch off. • Boom Valve: The section control module sends power to the section valve to turn the clutch on. • Electric Clutch: The section control module sends power to the section valve to turn the clutch on. • LiquiBlock: The section control module sends power to the section valve to turn the clutch off.
	<p>Turn Off When Stopped</p>	<p>Select one of the following:</p> <ul style="list-style-type: none"> • Yes: The section closes (turned off) when stopped. • No: The section remains open (turned on) when stopped.
<p>Section Control Module Location: Section Grouping</p> 	<p>Restore Defaults</p> <p>Section 1 - N</p>	<p>Set up the section grouping to match how the sections are physically configured on the implement.</p> <p>Return the settings to the default.</p> <p>Note – For the default, the rows are divided evenly across all sections. In most applications this will be the correct setup.</p> <p>Start with Section 1 and select the number of rows that are connected; continue with the sections in order until all rows are assigned.</p>

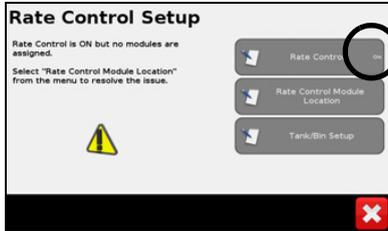
Rate Control Setup



Select	Options	Description
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Rate Control

Tap the button and then select **On**.



**Rate Control Module Location:
Number of Drives**

Select the number of drives that you have at the location.

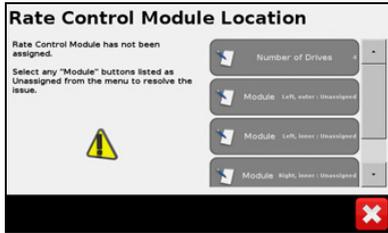


Select	Options	Description
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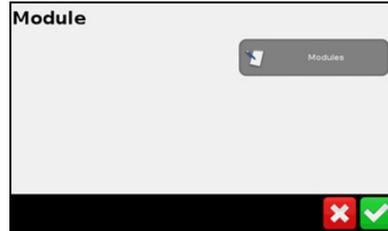
Rate Control Module Location:
Modules

Module

Select each module in turn and complete its setup before continuing with the next module.



1. In the *Rate Control Module Location* screen, select the first module location.
2. In the *Module* screen, tap **Modules**:



3. In the *Modules* screen, tap the button showing the serial number of the module physically connected to that location and then tap .



Rate Control Module Location:
Width

Set the width of the selected location.

Note – If you have one drive only selected, you will only have one *Module Setup* to perform and the width is then assumed to be the full implement width

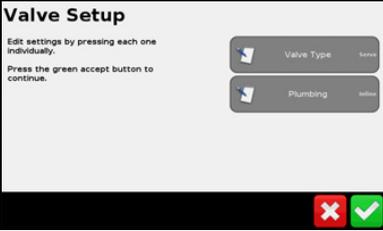
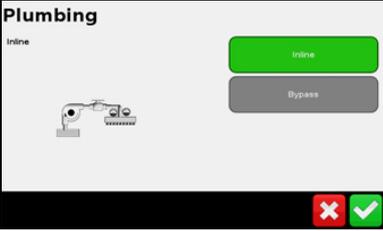
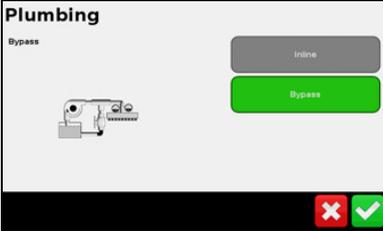
Drive Setup

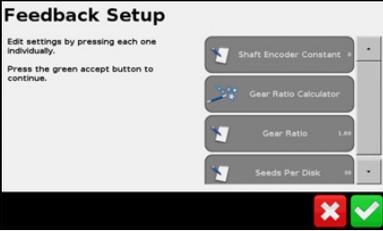
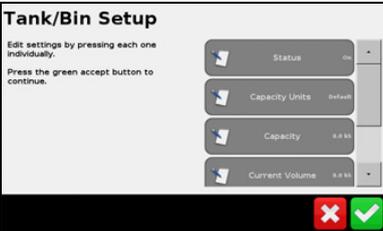


Select each drive in turn and complete its setup before continuing with the next drive.

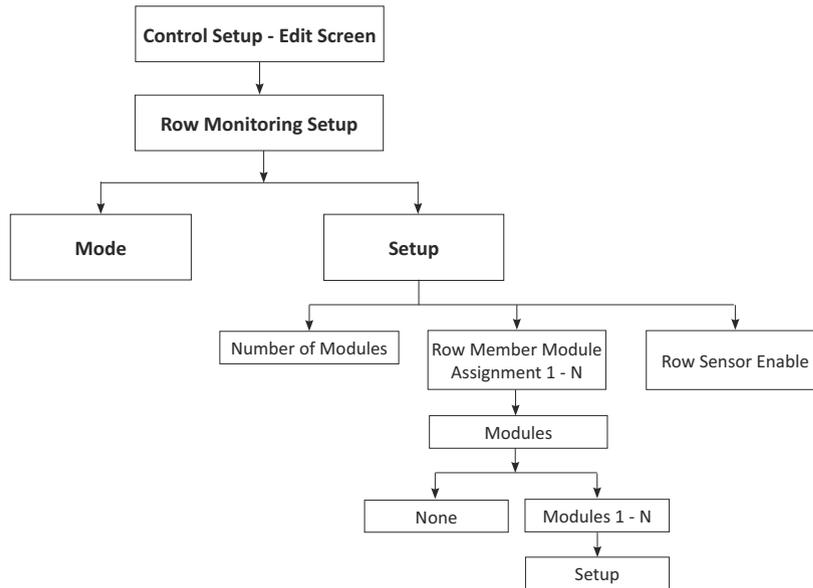
Select the **Drive Setup** button showing the serial number of the first drive that you want to set up.

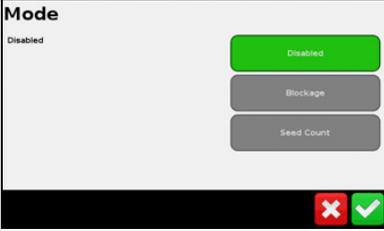
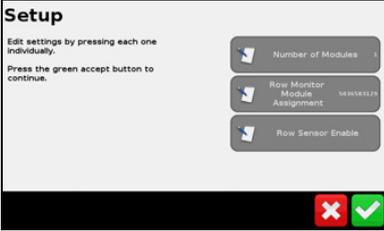
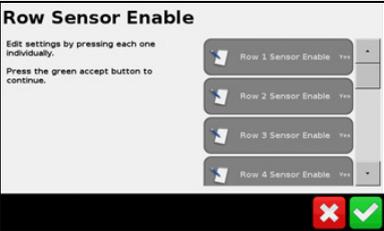
Note – If you have one module only set up, this screen does not appear—instead the *Drive Setup* screen with the **Valve Setup** button appears.

Select	Options	Description
<p>Drive Setup: Valve Setup</p>  <p>Valve Setup Edit settings by pressing each one individually. Press the green accept button to continue.</p> <p>Valve Type</p> <p>Plumbing</p>	<p>Valve Type</p>	<p>Select the <i>Valve Type</i> for the valve physically connected to the module.</p> <p>The options are:</p> <ul style="list-style-type: none"> • Servo: Standard 2-wire servo, performs more slowly. • Servo Fast: Fast 4-wire servo, performs more quickly. • PWM: 2-wire PWM valve, commonly used to control hydraulic flow to the pump. • Hardi % Bypass Servo: Used on Hardi sprayers equipped with 3-way section valves that return flow to the tank when the boom section is off. • Pump Servo: Servo valve commonly used to control hydraulic flow to the pump. • Electric Over Hydraulic: A valve that uses electric current to control the hydraulic valve output. <p>Note – These settings also control the default setting for <i>Valve Response</i>.</p>
 <p>Plumbing</p> <p>Inline</p> <p>Inline</p> <p>Bypass</p>	<p>Plumbing</p>	<p>Set the valve plumbing for servo-type valves only (that is, Servo, Servo Fast, and Hardi % Bypass Servo).</p> <p>Note – Pump Servo does not have a plumbing type as it controls hydraulic flow to the pump. This is similar to a PWM setup.</p> <p>The options are:</p> <ul style="list-style-type: none"> • Inline: The control valve is between the pump and the sections/nozzles. This means that the control valve controls the amount of material out to the section/nozzles directly. • Bypass: The control valve is between the pump and the tank. This means that the control valve controls the amount of material that goes back to the tank. <p>Note – To increase the amount of material that is sent to the section/nozzles, the control valve must open more in order to force more material to the sections/nozzles.</p> <p>Note – To increase the amount of material that is sent to the section/nozzles, the control valve must close more in order to force more material to the sections/nozzles.</p>
 <p>Plumbing</p> <p>Bypass</p> <p>Inline</p> <p>Bypass</p>		

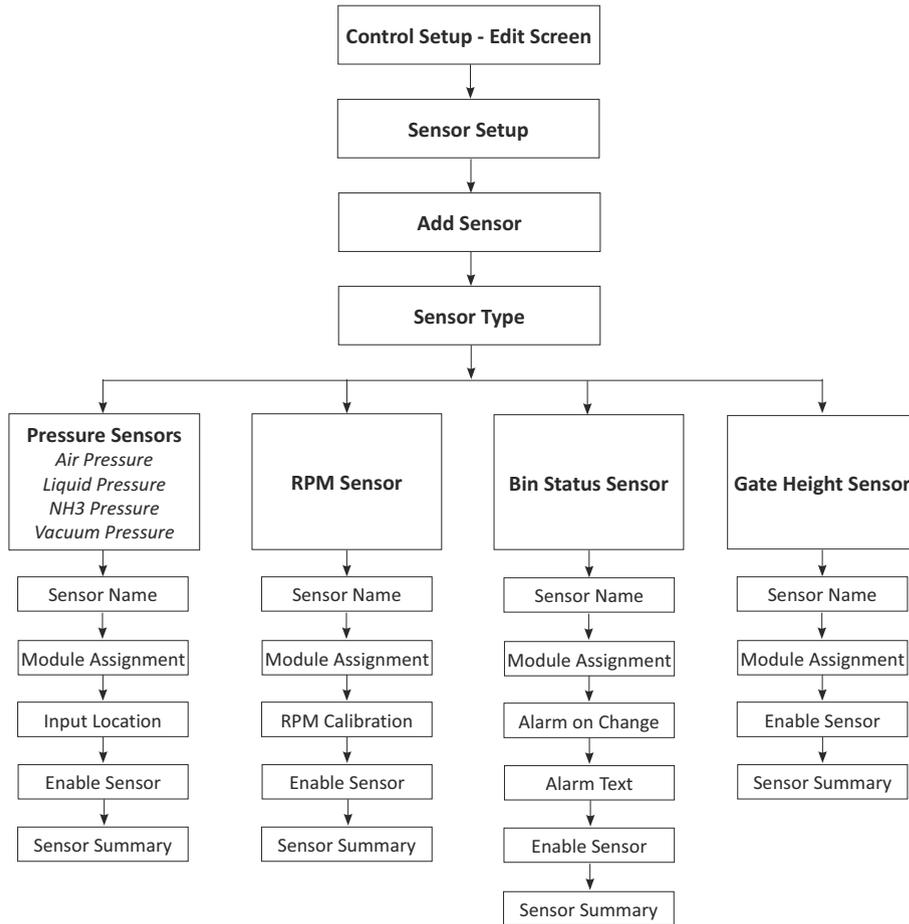
Select	Options	Description
Drive Setup: Feedback Setup		
	Shaft Encoder Constant	Enter the pulse per revolution for the feedback sensor you have connected to this module.
	Gear Ratio Calculator	Use the calculator to calculate the gear ratio, if required.
	Gear Ratio	Enter the gear ratio from the feedback sensor to the seed disk.
	Seeds Per Disk	Enter the number of holes in the seed disk.
Tank / Bin Setup		
	Status	Select On to enable the Tank/Bin. Select Off to turn the Tank /Bin setup off.
	Capacity Units	Select the units for the Tank/Bin.
	Capacity	Set the total volume for the Tank/Bin.
	Current Volume	Enter the current volume of material in the Tank/Bin.
	Partial Refill	Enter a amount that you want to use for a partial refill.
	Warning Level	Enter the amount of material that you want to trigger a Low Material Warning.

Row Monitoring Setup



Select	Options	Description
<p>Mode</p> 		<p>Select the type of row monitoring that you want to enable. The options are:</p> <ul style="list-style-type: none"> • None • Blockage • Seed Count
<p>Setup: Number of Modules</p> 	<p>Number of Modules</p>	<p>Select the total number of Row Monitoring Modules you have connected to this location.</p>
	<p>Row Member Module Assignment</p>	<p>Select the button showing the location that you want to set up first and then select the serial number of the row monitoring module connected to this location.</p> <p>Note – If you have two row monitoring Modules on this location, repeat these steps, for the second module. You can have no more than two modules per location</p>
<p>Row Sensor Enable</p> 	<p>Row Sensor Enable</p>	<p>Enable and disable individual sensors.</p>

Sensor Setup



Once you select a sensor type, complete the screens as described below—tap  to move to the next screen. **Not all options apply to all sensors.**

Select	Options	Description
Sensor Type	Air Pressure Liquid Pressure NH3 Pressure Vacuum Pressure RPM Sensor Bin Status Sensor Gate Height Sensor	Select the type of sensor that you want to set up.

Sensor Type

Select the type of sensor you want to add

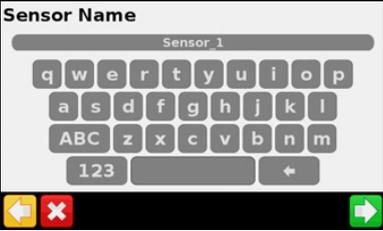
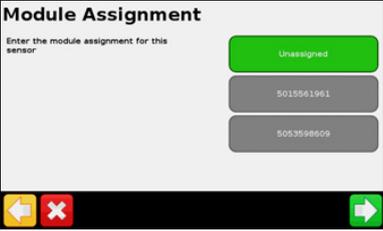
Air Pressure

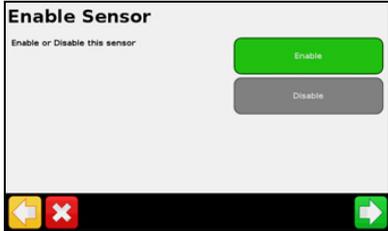
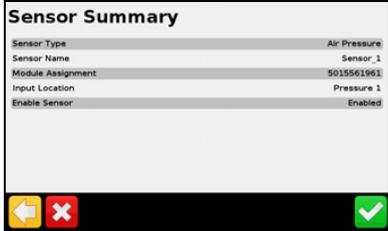
Liquid Pressure

NH3 Pressure

Vacuum Pressure

✖
➡

Select	Options	Description
Sensor Name		Use the on-screen keyboard to enter a name for the sensor.
Module Assignment		Select the serial number of the module the sensor is connected to.
Input Location (<i>Pressure Sensors only</i>)		Select the location the pressure sensor is connected to on the module.
RPM Calibration (<i>RPM Sensors only</i>)		Enter the Pulse per Revolution number for the RPM sensor.
Alarm on Change (<i>Bin State Sensors only</i>)		Select the change of state that will trigger the sensor alarm. The options are: <ul style="list-style-type: none"> • Low to High: The alarm is triggered when the module sees the sensor go from 0 V to 12 V. • High to Low: -The alarm is triggered when the module sees the sensor go from 12 V to 0 V.

Select	Options	Description
Alarm Text <i>(Bin Status Sensors only)</i>		Enter the text you want to appear when the alarm is triggered.
		
Enable Sensor		Enable or disable the sensor.
		
Sensor Summary		Review the summary. If correct, tap  .
		

Field-IQ Hydraulics Test

 **WARNING – MOVING PARTS DURING THIS TEST!** Please stay clear of the implement. Ensure the implement is raised, the transmission is in PARK and the emergency brake is applied before continuing.

After the setup wizard is complete, the display tests the hydraulics of your system. During this test you must run the motor(s) at the minimum and maximum RPM and make sure the motor(s) achieve these RPM.

Field-IQ Calibrations

After the hydraulics test is complete, the display calibrates your system. The available calibrations are:

- Field-IQ Rawson Control Module
- Servo Pump or PWM Pump
- Pressure Sensors

- Implement Lift Switch

When the calibration is complete, save the data to a configuration file and export it to the USB drive. See [Chapter 11, Data](#).

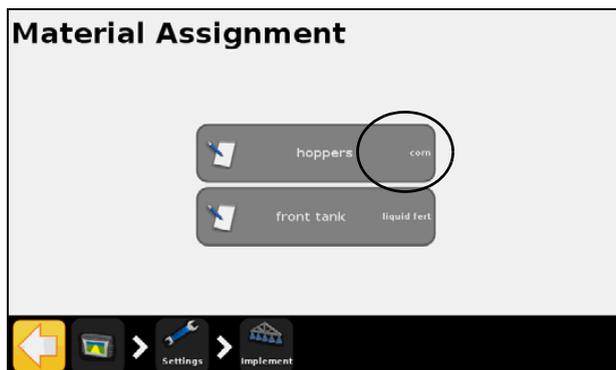
Field-IQ System Status

Select this option to view the status for the following:

- Master Switch Module
- Section Switch Module
- Rate Control Module
- Section Control Module
- OEM Switch Interface
- Accessories

Material Assignment screen

The Material Assignment screen allows you to easily switch a material in a control location. The location button (in this example, *Hoppers*) shows the name of the location and the material (in this example, *Corn*) that is currently assigned.

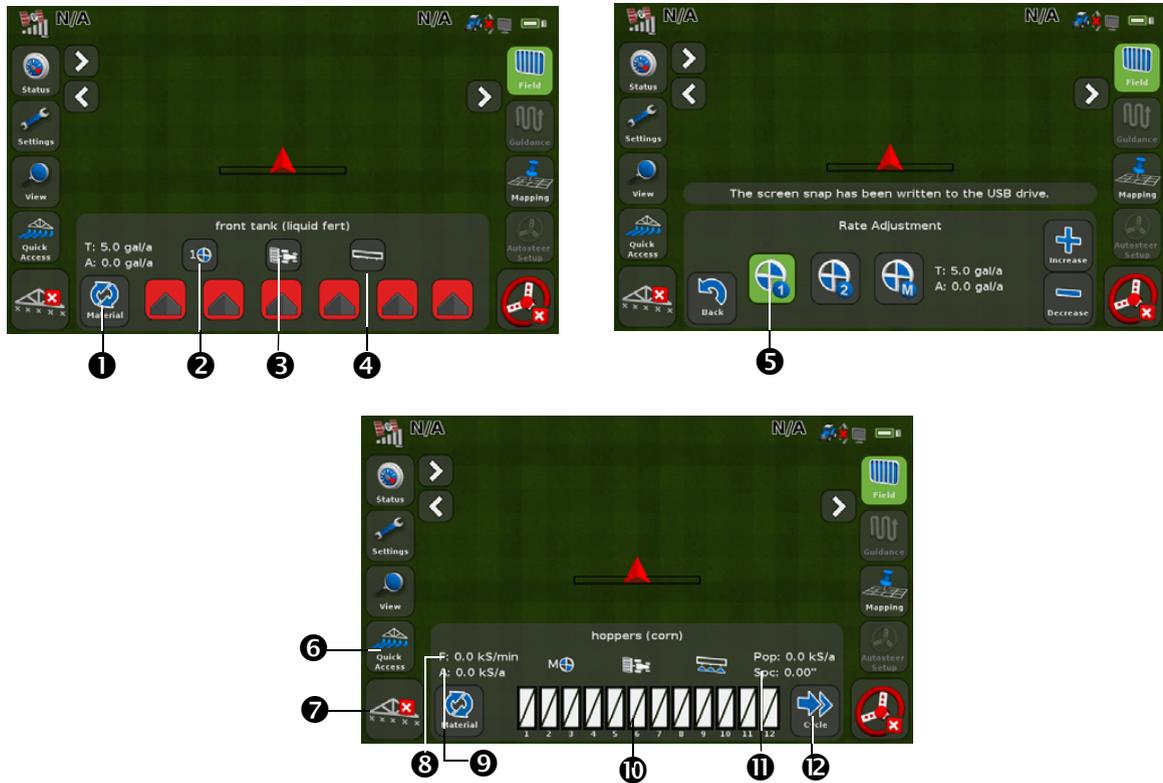


To change the material, tap the location button and then select a new material. If you select *No Material*, the location is disabled.



Operation

Once you have enabled, configured and calibrated your Field-IQ crop input control system, the following items may appear on the guidance screens:



Item	Description	Notes
1	Material	Use this button to switch between materials

Item	Description	Notes
②	Virtual Rate button	Opens the second image (shown to the right) where you can adjust your rates.
③	Virtual Section Auto / Manual switch	Shows the current mode for the controller. The options are Automatic  and Manual 
④	Virtual Master Switch	Shows the Master Switch status. The options are On  and Off 
⑤	Rate switch position	Indicates the current position of the rate switch.
⑥	Quick Access icon	See Quick Access icon, page 34 .
⑦	Coverage status	On:  Off:  Inactive: 
⑧	Target rate	The target application rate for the current rate switch position. This is the amount of product that you want to apply.
⑨	Actual rate	The actual application rate. This is the amount of product that is currently being applied.
⑩	Row monitoring bar	
⑪	Sensor Information	Shows current information for the selected sensors.
⑫	Cycle button	Available if you have more than 12 rows to view.

Field-IQ master switch box



Feature	Function
❶ Increment/decrement switch	Increases the applied amount by a set amount (the amount set in the Setup screen, Rate tab).
❷ Rate switch	Choose to use preset Rate 1, preset Rate 2, or Manual rate.
❸ LED indicator	Red – Unit is powered but not communicating with the CFX-750 display. Green – Unit is powered and communicating with the CFX-750 display. Yellow – Unit is initializing communications with the CFX-750 display.
❹ Automatic/Manual section switch	Automatic mode – The CFX-750 display automatically opens and closes sections when entering areas of overlap, non-apply zones, or crossing boundaries. Manual mode – The sections are controlled manually, bypassing the CFX-750 display. You can switch from Automatic to Manual mode while traveling.
❺ Master switch	<ul style="list-style-type: none"> • A. Jump start (top position) The sections and rate are ready to be commanded by the CFX-750 display, and the system is overridden to use a preset control speed (the speed is set in the Setup screen, Override tab). Use the jump start function if you lose a GPS signal or you want to start applying before your implement is up to speed. • B. On (middle position) The sections and rate are ready to be commanded by the CFX-750 display. • C. Off (lower position) Sections are closed and rate is set to zero.

Note – All systems must have a Field-IQ master switch box.

Field-IQ 12-section switch box



Note – The 12 section switch box is required for section control. For rate control only, the switch box is optional.

Only one section switch box can be used on each system. Each section switch is automatically assigned to the corresponding module. The modules are read from left to right. For example, switch 1 assigns to the module furthest on the left when standing behind the implement.

The section switches have different functions, depending upon the status of the master Automatic/Manual section switch on the master switch box.

When the Automatic/Manual section switch is in the **Automatic** position:

- If the section switch is in the on/up position the section(s) assigned to it are commanded automatically by the CFX-750 display.
- If the section switch is in the off/down position the section(s) assigned to it are commanded to be off.

When the Automatic/Manual section switch is in the **Manual** position:

- If the section switch is in the on/up position, the section(s) assigned to it are commanded to be on. This overrides the CFX-750 display and coverage logging is ignored.
- If the section switch is in the off/down position, the section(s) assigned to it are commanded to be off. This overrides the CFX-750 display and coverage logging is ignored.

The LED has the following status indicators:

- Green – The unit is powered and is communicating with the CFX-750 display.
- Yellow – The unit is initializing communications with the CFX-750 display.
- Red – The unit is powered but not communicating with the CFX-750 display.

Field-IQ Boom Height Control System

In this chapter:

- [Installing the Boom Height Control hardware](#)
- [Setting up the Boom Height Control system](#)
- [Using the Boom Height Control system](#)

The Field-IQ Boom Height Control system enables the CFX-750 display to control the height of spray nozzles above a crop canopy or bare ground.

Installing the Boom Height Control hardware

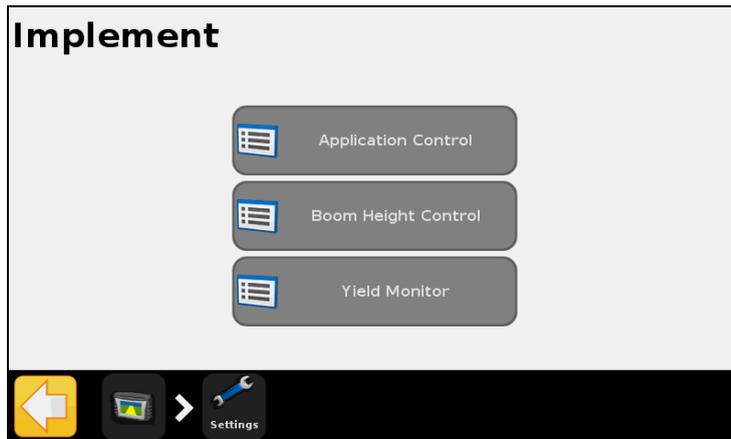
For information on installing the Boom Height Control system on your equipment, refer to the *Boom Height Control Platform Installation Instructions*. For the latest versions of these documents, go to www.trimble.com/agriculture.

Setting up the Boom Height Control system

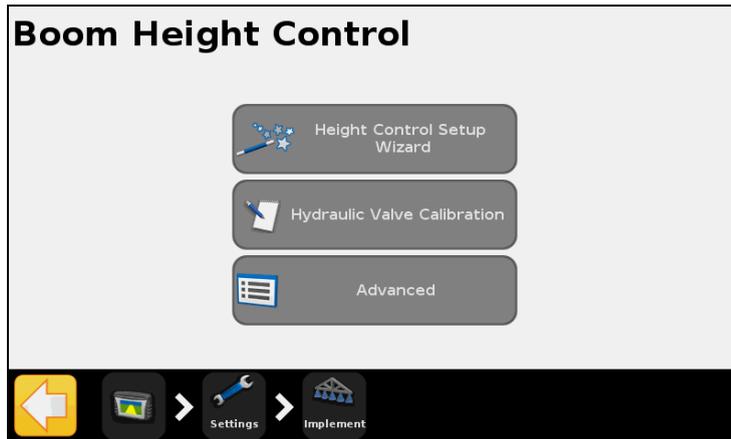
1. In the guidance screen, tap  .
2. In the **Settings** screen, tap **Implement**:



3. In the *Implement* screen tap **Boom Height Control**:



4. In the *Height Control* screen, tap **Height Control Setup Wizard**:

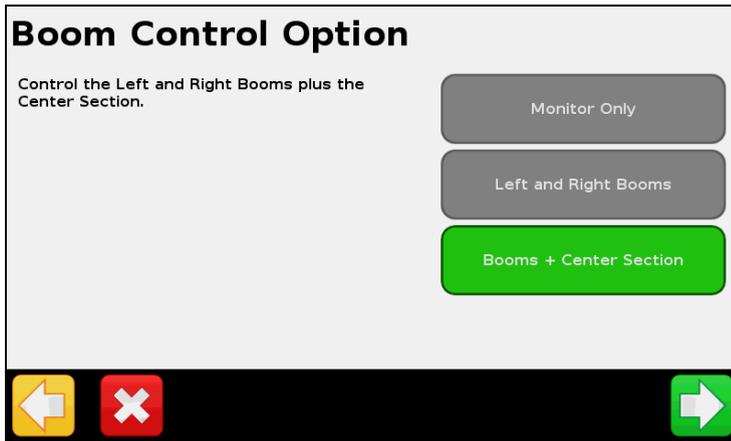


5. In the next screen, tap **Enable** and then tap :



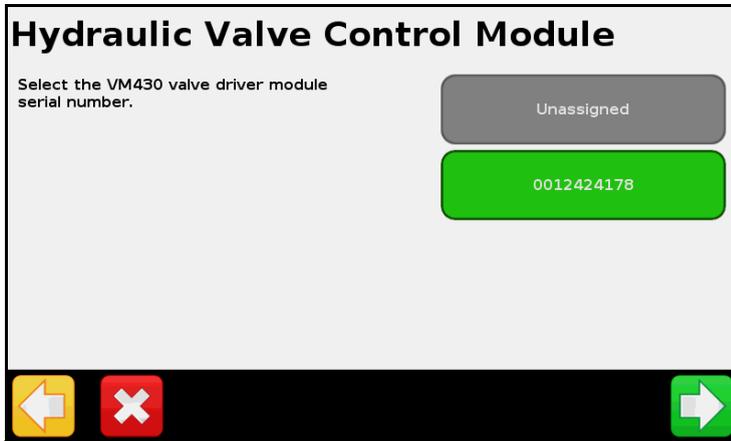
6. In the *Welcome to Boom Height Control Setup* screen, tap  to start the Boom Height Control Setup Wizard.

7. In the *Boom Control Options* screen, select a control option and then tap :

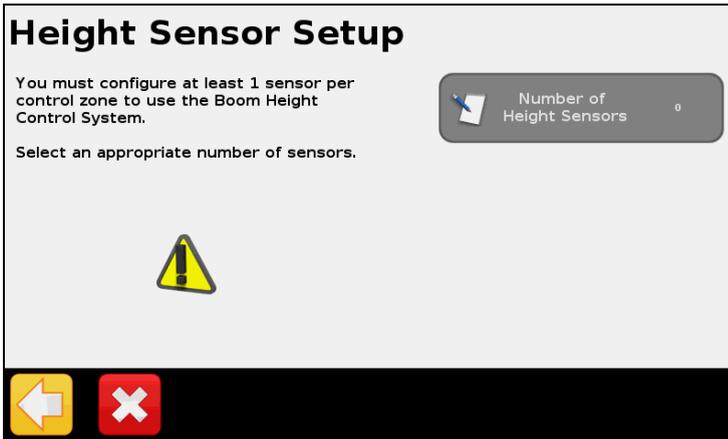


Select...	Description
Monitor Only	Auto-height control is not used. The SS100 sensors are used to monitor the height above the crop or ground.
Left and Right Booms	Auto-height control is used for the wings only.
Booms + Center Section	Auto-height control is used for the wings and the center section.

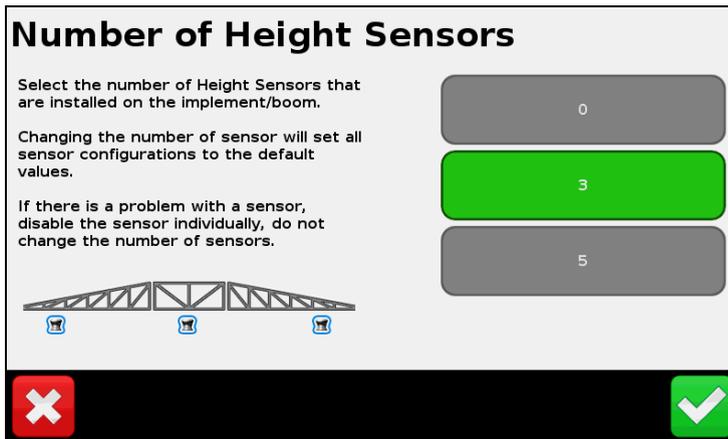
8. In the *Hydraulic Valve Control Module* screen, select the serial number of the Hydraulic Valve Control module and then tap :



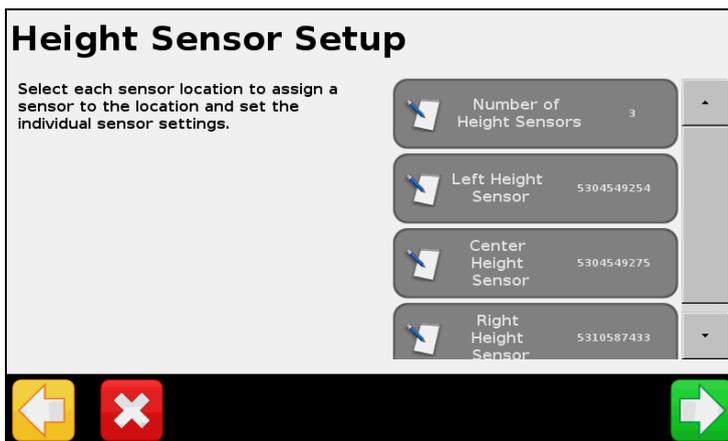
- In the *Height Sensor Setup* screen, tap **Number of Height Sensors**:



- In the *Number of Height Sensors* screen, select the number of height sensors that are attached to the boom and then tap :

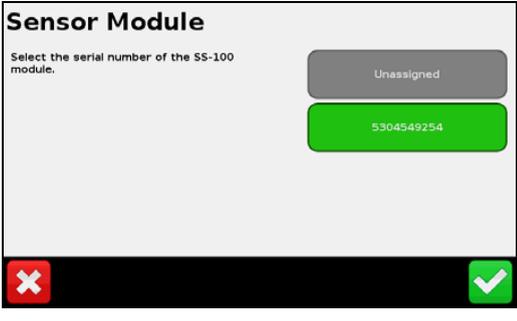
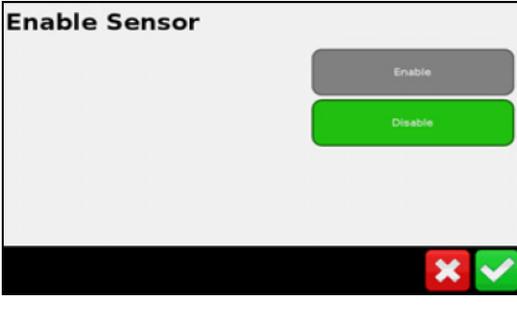
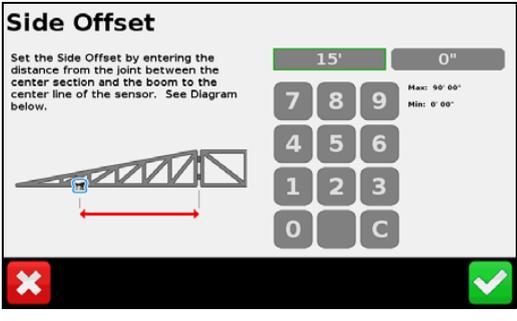
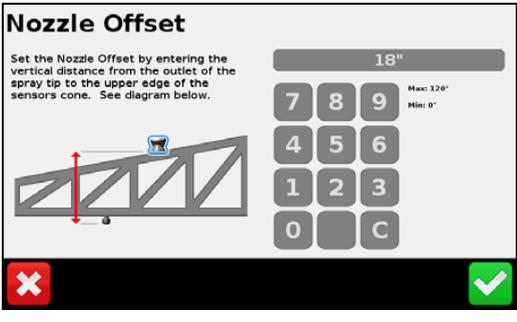


- In the *Height Sensor Setup* screen, tap each of the sensor location buttons in turn:

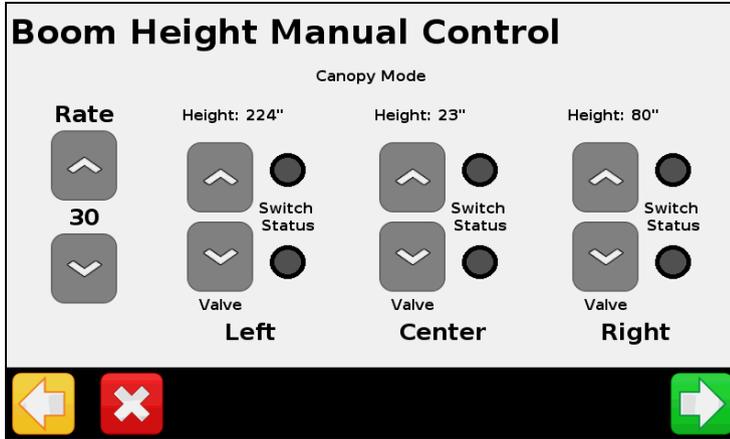


- Set each sensor setting and then tap  to continue.

- Repeat until all sensors are set up then tap 

Item	Description
<p>Sensor Module</p> 	<p>Select the serial number of the sensor that is installed in the selected location.</p>
<p>Enable Sensor</p> 	<p>Enable or disable the sensor.</p>
<p>Side Offset</p> 	<p>Enter the distance from the center line of the sensor to the hinge point of the boom.</p>
<p>Nozzle Offset</p> 	<p>Enter the distance from the bottom edge of the sensor cone to the outlet of the spray nozzle tip.</p>

12. In the *Boom Height Manual Control* screen, verify the correct operation of the Manual Boom Switch detection by monitoring the circles next to the control sections. If you use the Raise position on the manual switch, the top circle should turn green. If you use the Lower position on the manual switch, the bottom circle should turn green. Do this for each of the Manual control switches.



13. In the *Height Control Operation Setup* screen, enter the following:

Item	Description
Sensing Mode	<p>Ground: Target height is based on the surface of the ground. Select Ground mode to sense the ground surface through low coverage vegetation, such as stubble or young crops. Ground mode is susceptible to unwanted reflectance on hard or wet surfaces, such as bare ground. If this is an issue, select Canopy mode.</p> <p>Canopy: Target height based on the height on the crop canopy. Select Canopy mode to sense the closest object seen. This is used to sense bare ground or high-coverage broad leaf crop canopy.</p>
Target Height	Enter the desired height above the ground or crop canopy, depending on the sensing mode.
Boom Down Rate	Lower this setting to reduce the maximum downward speed of the boom.
Boom Roll Stabilizer	Raise this setting to increase the boom roll stability. Note – Raising this setting will decrease the downward speed of the boom.
Height Error Indication Band	This is the band for which the screen will indicate you are on-target height. Note – This setting is for on screen indication and does not affect performance.
Target Height Step	Enter the distance that the target height should change when you tap Increase or Decrease.
Minimum Target Height	Set the minimum height that the Target Height can be set to. On a multi-sensor control zone, this setting is used as a minimum height for the average of the system. For quicker performance, set this value close to the Target Height setting.
Maximum Target Height	Set the maximum height that the Target Height can be set to.

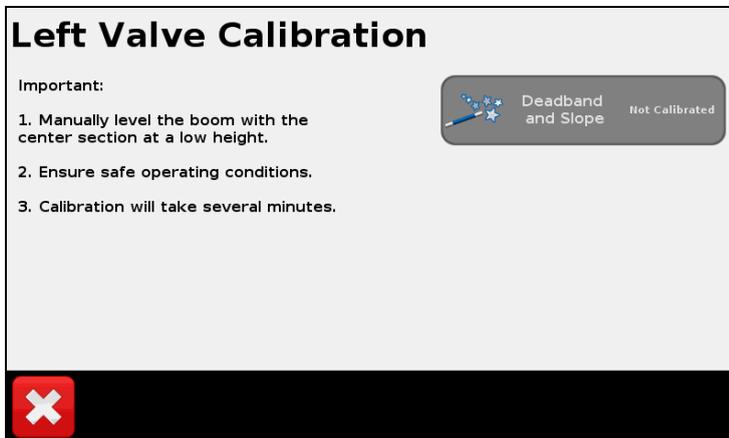
Item	Description
System Aggressiveness	Set the aggressiveness for the Boom Height Control system. A higher number is more aggressive and a lower number is less aggressive.

Calibrating the Field-IQ Boom Height system

1. In the guidance screen, tap .
2. In the *Settings* screen, tap **Implement**:

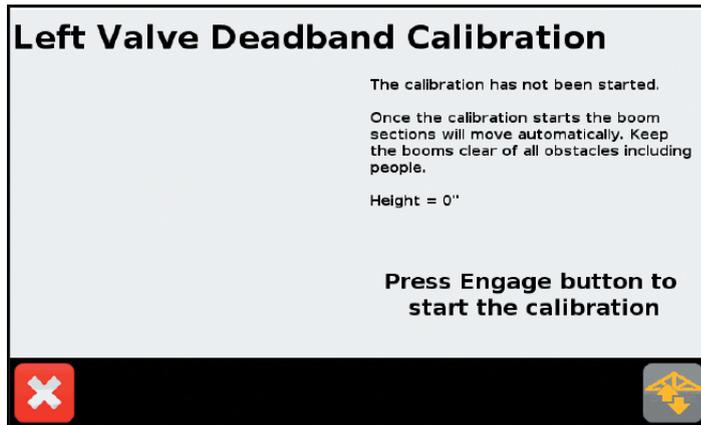


3. In the *Implement* screen tap **Boom Height Control**.
4. In the *Height Control* screen tap **Hydraulic Valve Calibration**.
5. In the *Hydraulic Valve Calibration* screen, tap the **Zone** you want to calibrate.
6. In the Zone Valve Calibration screen, tap the **Deadband and Slope** button:



7. Make sure that you lower the center section to a lower height and level the booms before you start the calibration procedure. If the Center or Booms are too high or too low, the calibration may fail.

8. In the *Deadband Calibration* or *Slope Calibration* screen, tap **Engage** to start the calibration.



9. Repeat [Step 5](#) through [Step 8](#) until all zones are calibrated and then tap .

Using the Boom Height Control system

1. Monitor boom height (before enabling, or if you selected *Monitor Only* on the *Boom Control Options* screen).
2. Enable the zone or zones you want to control.
3. Engage the enabled zone or zones.
4. Use the *Controls* to adjust *Target Height* and *Aggressiveness*.
5. Before transporting the vehicle or folding the booms:
 - Disable boom height control on all zones.
 - Press the **E-Stop** button.
 - Close the field.

Monitoring boom height

When Boom Height Control is disabled on zones (or of you set *Monitor Only* on the *Boom Control Options* screen) the section buttons are gray.

A symbol on the buttons (for example, a red arrow) indicates:

- The direction that the section is off target
- How far the section is off target

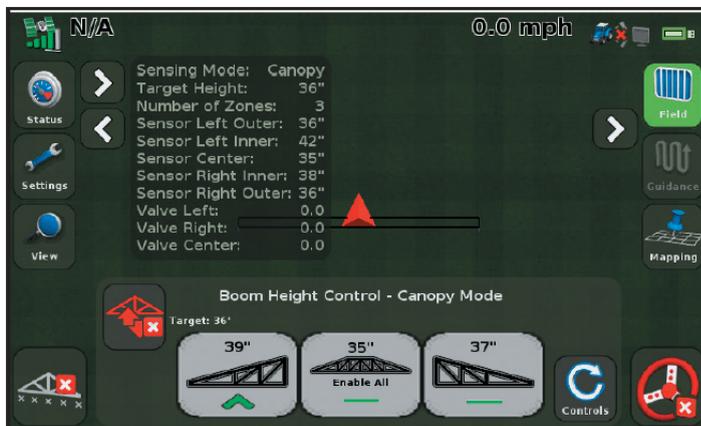
Item	Description
	The boom is significantly below the target height. Raise the boom to reach the target.

Item	Description
	The boom is somewhat below the target height. Raise the boom to reach the target.
	The boom is slightly below the target height. Raise the boom to reach the target.
	The boom is at the target height.
	The boom is slightly above the target height. Lower the boom to reach the target.
	The boom is somewhat above the target height. Lower the boom to reach the target.
	The boom is substantially above the target height. Lower the boom to reach the target.

Enabling a control zone

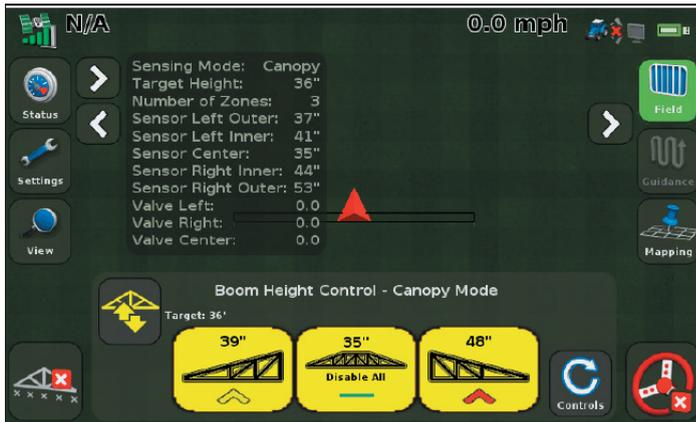
When a zone is disabled, the button for that section is gray and Boom Height Control is not available on that section. Enabling a control zone makes automatic height control available for that section.

- To enable a single control zone, tap the button for that section.
- To enable all zones, tap **Enable All**. This button is available only when the system is not engaged and all zones are disabled (gray).



Note – If you are currently engaged on other zones, any additional zones will engage automatically.

- Once a zone is enabled, the button for that section turns yellow:



- The **Enable All** button also turns yellow.
 - If all zones are enabled, the center button changes to **Disable All**.
 - If any sections are not enabled, the center button shows the center section.
- The **Engage** button also turns yellow when one or more zones have been enabled:



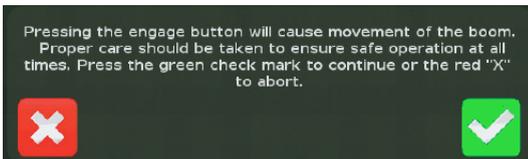
- Boom Height Control is not active until you engage the enabled zones.

Engaging enabled zones

To engage all enabled zones, tap **Engage**:



The first time you engage Boom Height Control after the display is turned on, the following safety message appears:



In the safety message screen:

- Tap  to engage the enabled zones.
- Tap  if you do not want to engage the enabled zones.

Note – If all zones are enabled but not engaged for 30 seconds, Boom Height Control disables the zones as a safety measure. You must re-enable zones once again before engaging the system.

While Boom Height Control is engaged:

- The **Engage** button is green.
- The button for each engaged section is green.



- The number at the top of each button is:
 - The distance from the sensor to the ground or canopy if the section has one sensor.
 - The average distance from the sensors to the ground or canopy if the section has multiple sensors.
- A symbol on the buttons (for example, a red arrow) shows:
 - The direction that the section is moving to get closer to the target height
 - How far the section is off target (indicated by color)

Adjusting the Target Height and Aggressiveness Controls

1. Tap **Controls**:



2. The Boom Height Control section of the screen changes to show the *Target Height* and *Aggressiveness* controls:



- To adjust the *Target Height*, tap the increase or decrease arrows below the *Target Height* heading.
- To adjust the *Aggressiveness* of the system, tap the increase or decrease arrows below the *Aggressiveness* heading.
- To set the Target Height to the current boom height, tap **Use Current**.



- To return to the sections view, tap **Boom**:



Disengaging engaged zones

To disengage a zone, tap the button for that section:

- The button for the section changes from green to yellow.
- Boom Height Control is no longer actively controlling the section, but is still enabled.
- Tapping the button while it is yellow:
 - Re-engages Boom Height Control for that section if any other sections are still engaged.
 - Disables that section if no other section is engaged.

To disengage all zones, tap the green **Engage** button.

- The **Engage** button is green when any zone is engaged.
- When you tap the green **Engage** button, the buttons for all engaged sections change from green to yellow (enabled but not engaged).
- The **Engage** button is yellow when *all* sections are disengaged, and at least one is enabled.

Disabling Boom Height Control

Before transporting the vehicle or folding the booms:

1. Disengage all zones by doing one of the following:
 - Tap each green section button individually (that is, set each to yellow).
 - Tap the **Engage** button if it is green:



2. Disable all zones by doing one of the following:
 - Tap **Disable All**. This button is available only when all zones are disengaged but enabled.



- Tap the enabled (yellow) sections individually.

Note – If any section is still engaged, this will re-engage the section you tap. You must disengage all sections first.

3. Make sure that all zones are disabled:
 - If any button is yellow or green, repeat steps 1-3 until all sections are disabled.

- The buttons for each zone should be gray and the Engage button should be red.



4. Press the **E-Stop** button. The **E-Stop** button is a red hardware button that prevents Boom Height Control from communicating with the equipment. Refer to the *Boom Height Control Installation Instructions* for additional information.
5. To close the field, tap .
6. When asked if you are finished with the current field, tap **Yes**.

Follow the equipment manufacturer's recommendations to fold the booms or transport the vehicle.

Note – If the center boom section is raised for 3 seconds using input from a joystick, Boom Height Control is disabled as a safety feature for folding the boom.

Yield Monitoring System

In this chapter:

- [Setting up the Yield Monitoring system](#)
- [Calibration](#)
- [In field calibrations](#)
- [In field operations](#)
- [Status items](#)

The CFX-750 display supports Trimble Yield Monitoring.

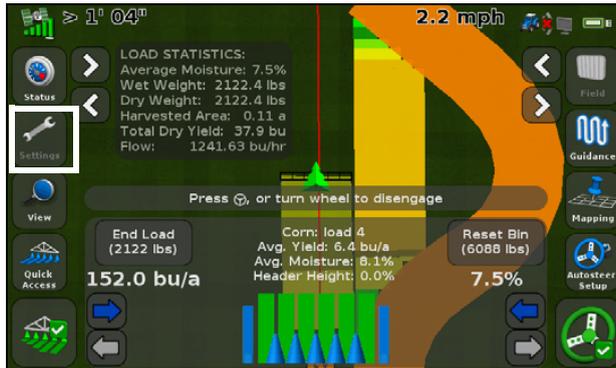
This chapter describes how to set up the Yield Monitoring system on the CFX-750 display.

Setting up the Yield Monitoring system

Once you have installed the Yield Monitoring component, you must set up the system.

To do this:

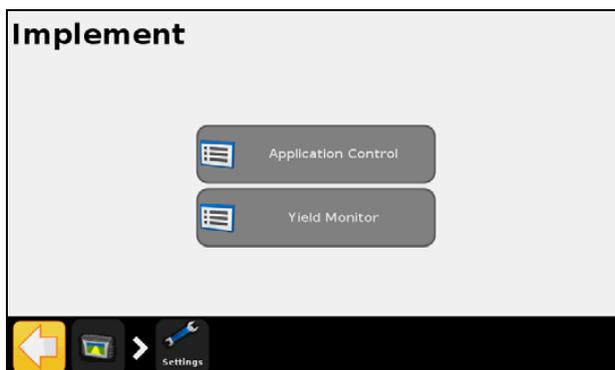
1. From the guidance screen, tap :
2. Tap the **Settings** button:

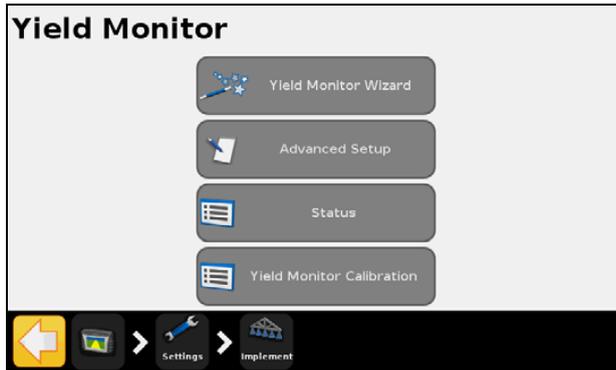
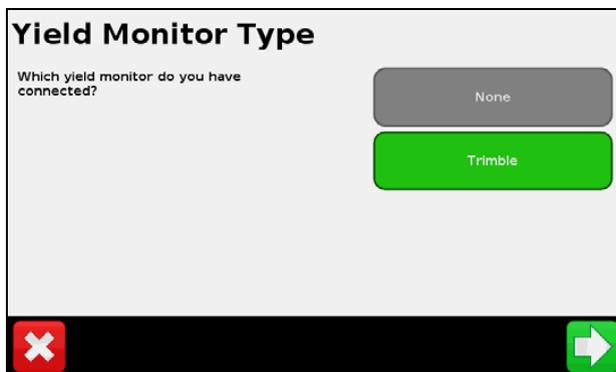


3. Tap **Implement**:



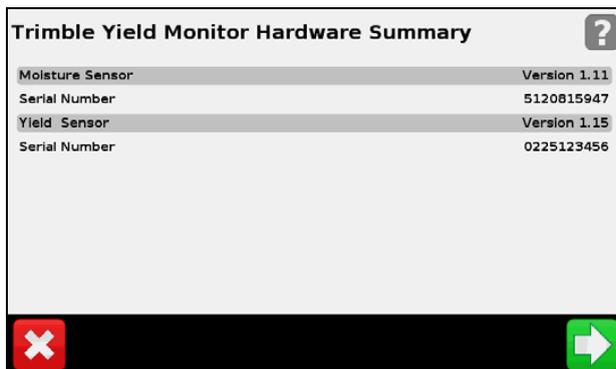
4. Tap **Yield Monitor**:



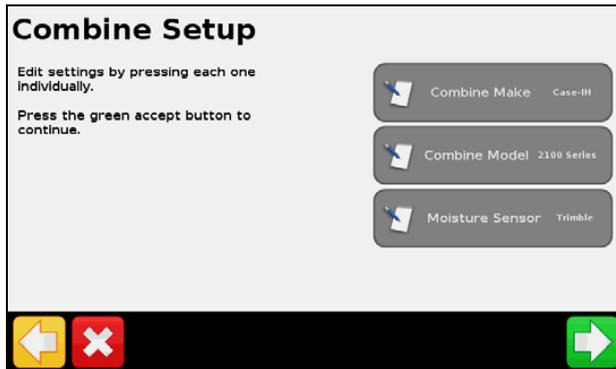
5. Tap **Yield Monitor Wizard**:6. Select the *Yield Monitor Type*:

Note – If you select **None**, this removes the Yield Monitor Plugin from the Run screen.

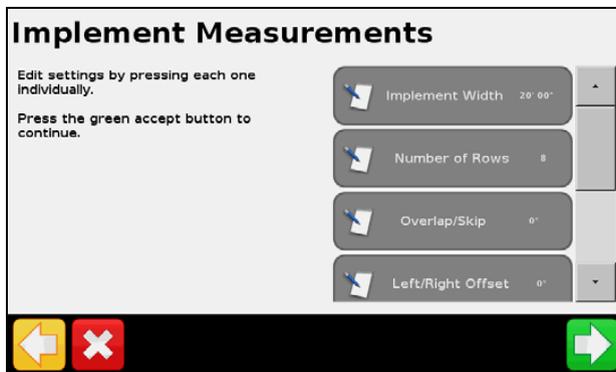
The following screens shows a summary of the hardware attached to the CFX-750 display:



7. In the *Combine Setup* screen, select the **Combine Make**, **Model**, and **Moisture Sensor** type in turn and then tap :

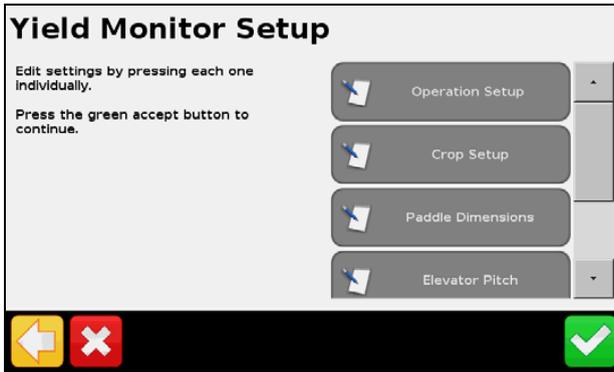


8. In turn, edit each the *Implement Measurement* settings and then tap :



- Implement Width
- Number of Rows (or sections for the header swath control)
- Overlap/Skip
- Left/Right Header offset
- Forward/Back Offset
- Allowable Side to Side coverage overlap

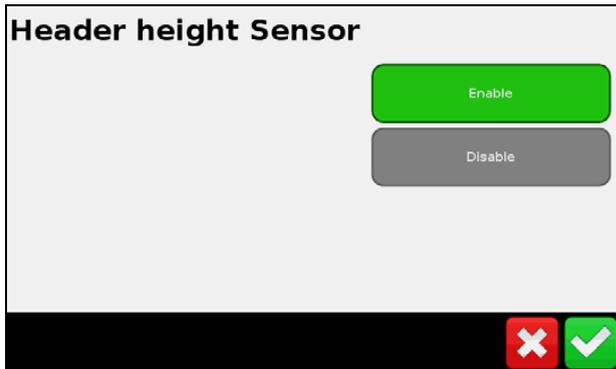
9. Edit the *Yield Monitoring Setup* in accordance with the vehicle requirements and then tap :



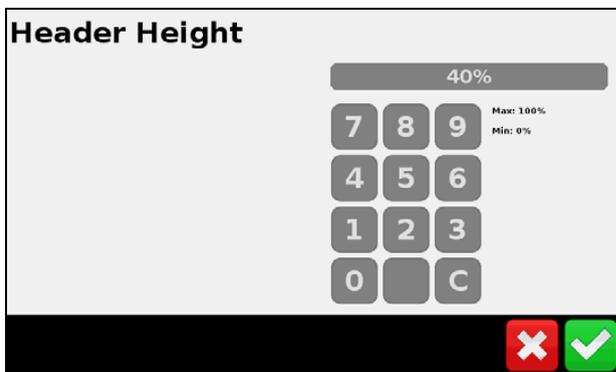
Tap each button in turn and tap  once you have completed the settings required.

Operation Setup includes the following:

- a. *Header height Sensor*— **Enable** or **Disable** logging control, based on the header height sensor:



- b. *Header Height*—set the height percentage at which logging turns on and off:



- c. *Grain Flow Delay*—set the length of time the combine takes to process grain for correct mapping of yields. This value should be the time it takes grain to go from the header to the grain tank:

Grain Flow Delay

8 s

7 8 9 Max: 100 s
4 5 6 Min: 1 s
1 2 3
0 C

✖ ✔

- d. *Reset Autocut*—enables resetting of swath control to full width when header is raised and lowered

Reset Autocut

Never

When header is lifted

✖ ✔

Crop Setup includes the following:

a. *Commodity:*

Commodity

Rice

Sorghum, Grain

Soybean

Wheat

X ✓

b. *Units*—define which units yield will be displayed in:

Units

Bushels/a

Tons/a

Lbs/a

Hundred Weight/a

X ✓

c. *Moisture Upper Limit*—the highest moisture value that will be recorded for a crop sample:

Moisture Upper Limit

40%

7 8 9 Max: 100%
Min: 0%

4 5 6

1 2 3

0 C

X ✓

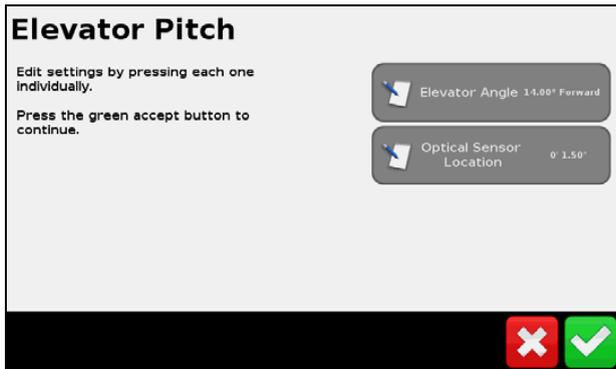
- d. *Standard Bushel Weight*—the standard density for the crop being harvested:

- e. *Storage Moisture*—the standard moisture that wet yield will be adjusted to for dry yield:

Paddle dimensions enables you to, in turn, verify the length, width, and distance between the paddles on your machine:

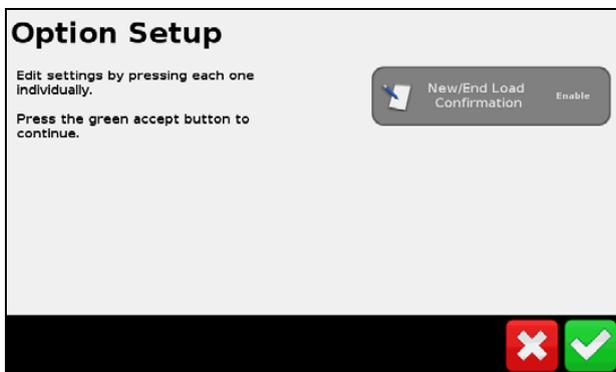
Note – Failure to verify these dimensions can cause degraded performance.

Elevator pitch enables you to, in turn, to verify the pitch angle of the clean grain elevator from the vertical and the distance of the sensors from the rear wall:

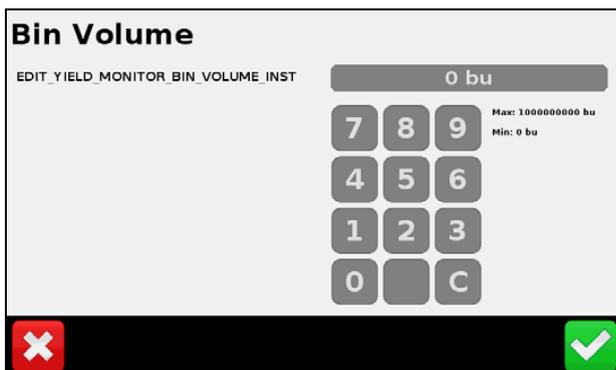


Note – Failure to set the correct optical sensor spacing from the rear wall can cause degraded performance.

Option Setup enables/disables the *Start New Load* confirmations. If you enable this setting, the operator has the option to confirm that they want to end the load. If you disable the setting, the operator is not prompted to confirm the end of the load they tap the **New Load** button:



Bin Volume—enter the size of the combine's grain tank:



Bin Display Type—select to view the current grain bin capacity in either actual units or as a percentage of the bin capacity:

The screenshot shows a menu titled "Bin Display Type" with the instruction: "When applying Anhydrous which units do you prefer to work in?". There are two buttons: "Actual Volume" (highlighted in green) and "Percentage" (grey). At the bottom, there are two navigation buttons: a red "X" (cancel) and a green checkmark (accept).

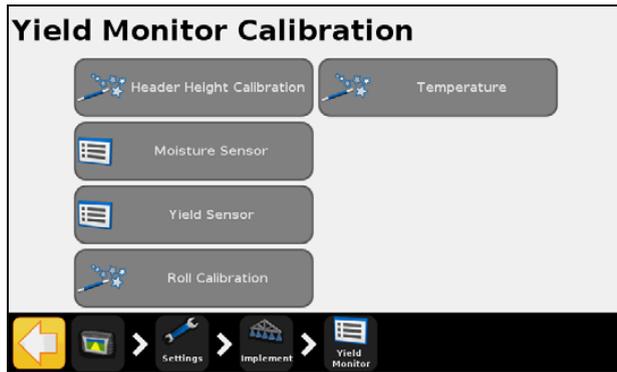
Map Legend Setup enables you to determine, in turn, the scale on the Yield and Moisture layers that are displayed on the CFX-750 display:

The screenshot shows a menu titled "Map Legend Setup" with the instruction: "Edit settings by pressing each one individually. Press the green accept button to continue." There are four settings, each with a pencil icon and a value: "Low Yield" (5.0 bu/a), "High Yield" (100.0 bu/a), "Low Moisture" (5%), and "High Moisture" (20%). At the bottom, there are two navigation buttons: a red "X" (cancel) and a green checkmark (accept).

Calibration

Set up calibrations

This section describes the calibrations that you must carry out before going to the field:

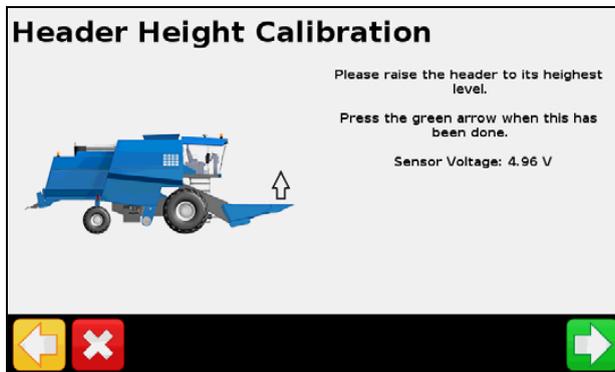


Header Height Calibration

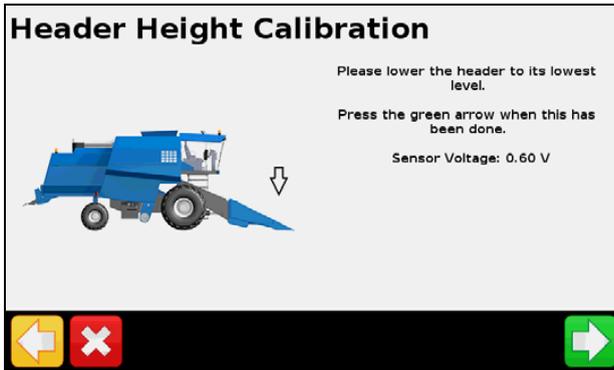
The Header Height Calibration wizard allows you to set the high and low points for the header height position:

Note – For accurate operation, the highest and lowest point of header operation must fall within the 0-5 Volt range of the sensor. If the sensor reaches maximum value **before** the full range of the header movement, you will need to adjust the linkage on the sensor.

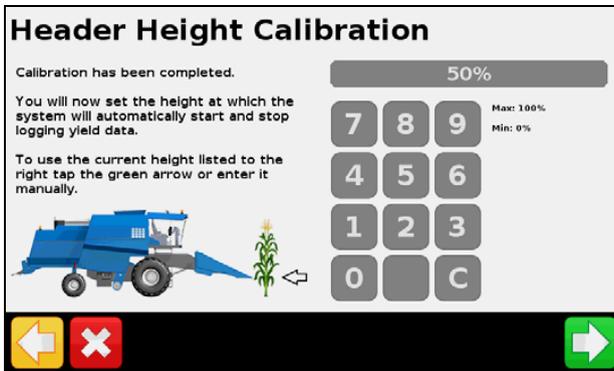
1. Start the wizard, raise the header to its highest point and then tap :



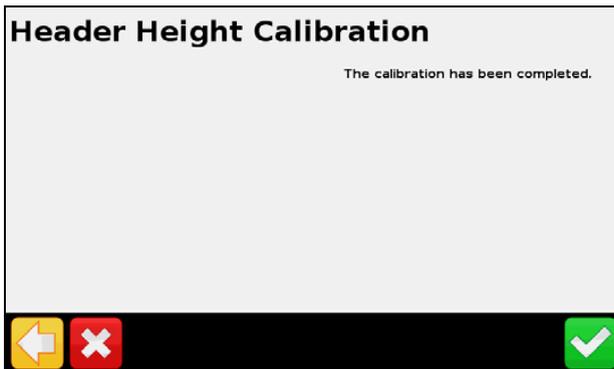
2. Lower the header to its lowest position and then tap :



3. Set the *Header Height* percentage at which logging should toggle on and off and then tap :



4. Once calibration is complete, tap :

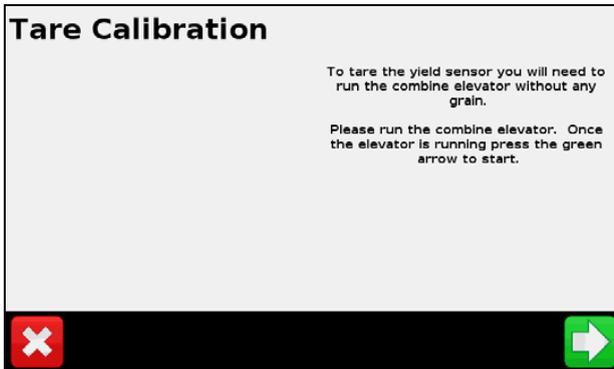


Moisture Sensor Calibration

This will be performed in the field.

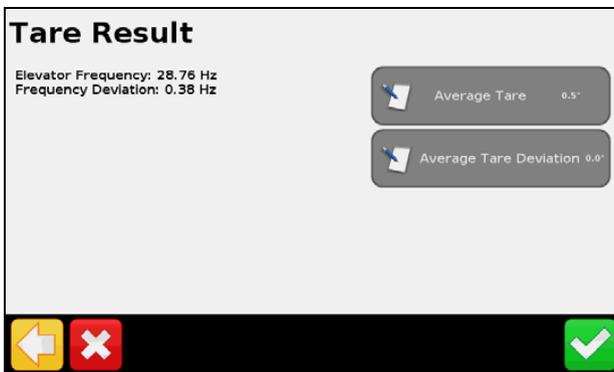
Tare Calibration

To tare the yield sensor, engage the separator, run the combine at full throttle and then tap :



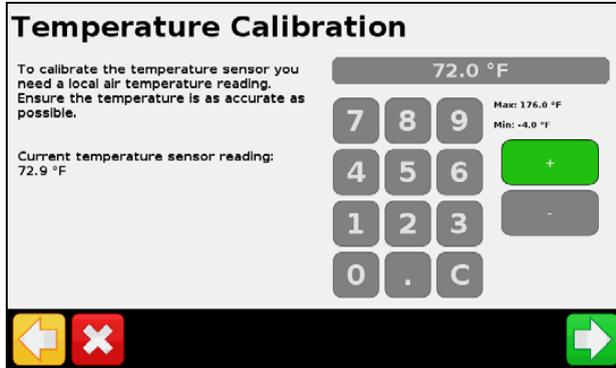
Note – Tare Calibration is important to the performance of the system. Ensure that the clean grain elevator is at proper tension with all paddles present and of uniform size.

Tare results should be close to paddle thickness but may be off a little bit. More important is a small deviation of Tare. This value should be less than 25% of the tare:



Temperature Calibration

Park the combine so that the Yield Monitoring Module and moisture sensor are in the shade and place a thermometer next to them for a while. Read the thermometer and then enter the correct temperature:

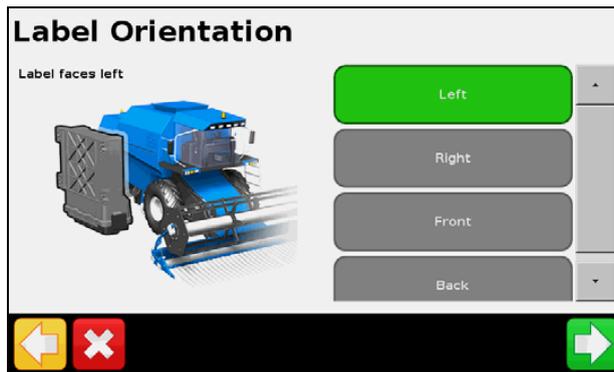


Note – Failure to complete this calibration can degrade moisture sensor performance.

Roll Calibration

The Yield Monitoring Module has inertial measuring devices to compensate for the terrain you encounter while harvesting. You need a GNSS location to perform this calibration.

1. Select the *Connector Orientation* and *Label Orientation* relative to the vehicle:

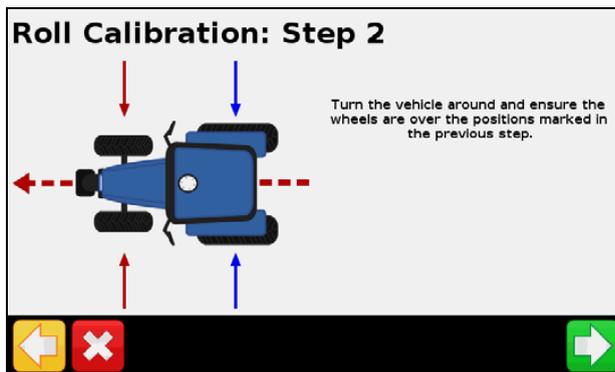


2. Park the vehicle on flat ground, mark the inside position of the front and rear wheels and then tap :



3. Wait while the roll is determined.

4. When prompted, turn the vehicle around so that the front wheels are in the position where the rear wheels were and the rear wheels line up with the marks from the front wheels, tap  and then wait for the roll offset to be determined



In field calibrations

For accurate performance of the Trimble Yield Monitor, the optical yield sensors and moisture sensor must be calibrated in the field in reference to a known good scale and moisture sensor.

Yield flow calibration

Calibrating the Yield Monitoring system across the full range of flows improves the accuracy of the system. To obtain a good calibration, do the following:

- Select calibration loads where the conditions are consistent—where the crop quality is as even as possible, the ground is as level as possible, and the passes are as long as possible. Keep the combine speed constant during the entire run.
- Collect loads that are as large as is practical without sacrificing consistency.
- Collect as many different calibration loads as possible, with each load at a different flow rate. To accomplish this, you can run the system at different speeds, or harvest partial header widths.

1. Select one of the following Calibration methods:

- **Speed method.** Uses a consistent header width while varying speed to calibrate for Low, Medium, and High grain flows.
 - a. Conduct a calibration load of 3,000-6,000 lbs. at your normal harvest speed, making sure to keep it constant.
 - b. Repeat this procedure for one load at 1 mph less than the normal operating speed; one load at 2 mph less than then normal operating speed; and one load at 1 mph higher than then normal operating speed.

This provides a calibration curve for Low, Medium, and High flow variations throughout the course of Harvest.

An example of calibration loads using this method is as follows:

Load 1 = 4,547 lbs. @ 2 mph

Load 2 = 3,834 lbs. @ 3 mph

Load 3 = 2,764 lbs. @ 4 mph

Load 4 = 5,768 lbs. @ 5 mph

- **Cut Width method.** This uses a consistent speed with different cut widths to calibrate for Low, Medium, and High flows.
 - a. Conduct a calibration load of 3,000-6,000 lbs. at your normal constant speed with a 100% cut width (that is, 12 rows at 30 ft).
 - b. Repeat this procedure for one load at 75% of the normal cut width (9 rows at 22.5 ft); one load at 50% of normal cut width (6 rows at 15 ft); and one load at 25% of normal cut width (3 rows at 7.5 ft) at the same constant speed.

This provides a calibration curve for Low, Medium, and High flow variations throughout the course of Harvest.

An example of calibration loads using this method is as follows:

Load 1 = 5,768 lbs. @ 4 mph @ 100% swath width

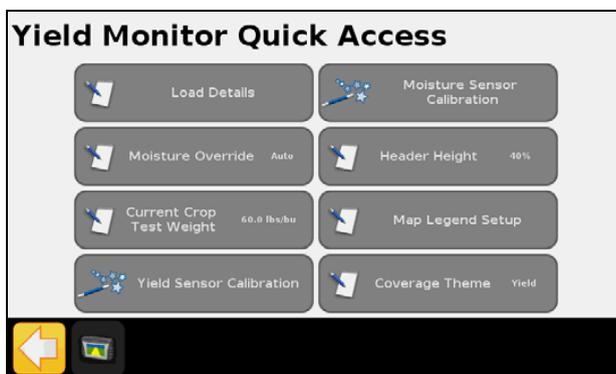
Load 2 = 4,547 lbs. @ 4 mph @ 75% swath width

Load 3 = 3,834 lbs. @ 4 mph @ 50% swath width

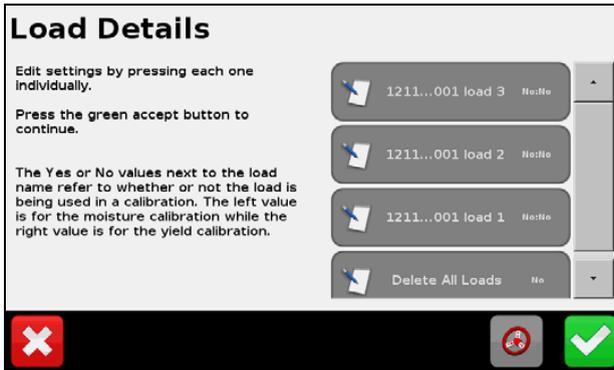
Load 4 = 2,764 lbs. @ 4 mph @ 25% swath width

It is highly recommended that you conduct a minimum of three calibration loads to ensure that the system provides accurate readings for all low, medium, and high flows throughout harvest. If you conduct a Single Load calibration, this may result in poor accuracy performance when Harvesting outside the Flow range at which the system was initially calibrated.

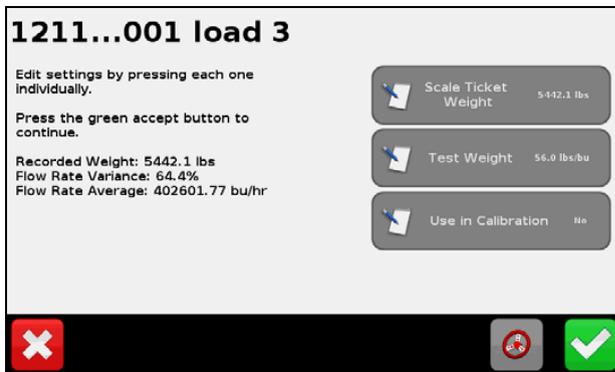
2. Collect all calibration loads.
3. Tap the **Quick Access** button and then tap **Load Details**:



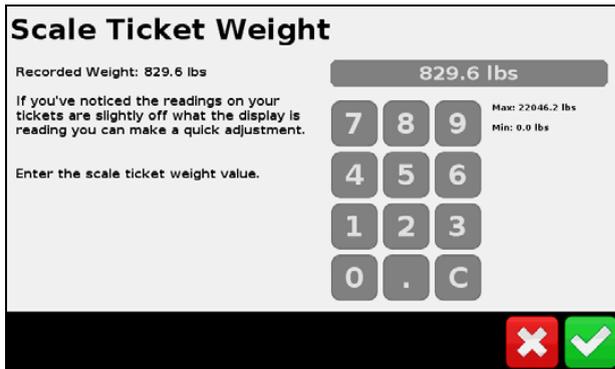
4. For each load:



– Tap the load button:



– Enter the Actual Scale Weight and then tap :



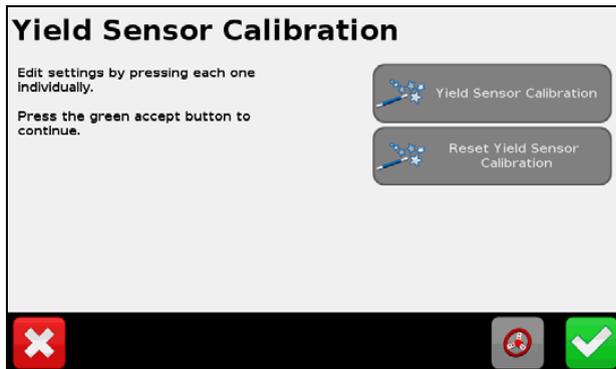
- Enter the Actual Test Weight and then tap  :



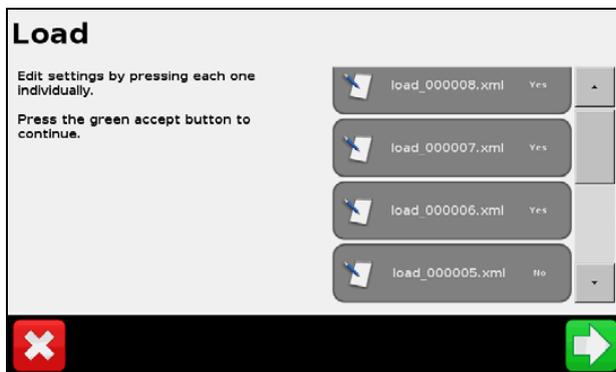
- Enter the actual moisture for the load.

Note – Evaluate each load for the flow variance. Only use loads that have a low flow variation in the calibration.

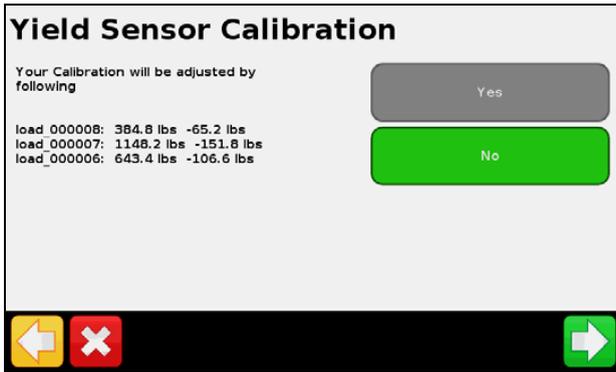
5. Tap **Yield Sensor Calibration**, tap **Yield Sensor Calibration** again and then tap  .



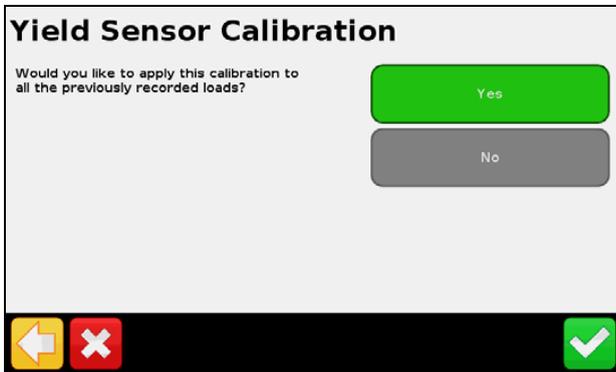
6. Confirm which loads are to be used in the calibration and then tap  :



7. Confirm the load adjustments—tap **Yes** or **No** and then tap :

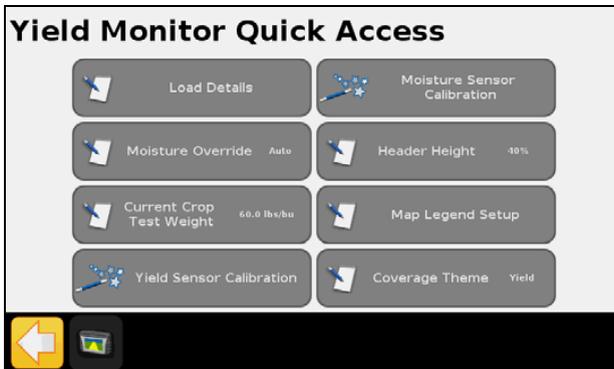


8. Confirm whether you want to apply the sensor calibration to previously recorded loads in the field—tap **Yes** or **No** and then tap :

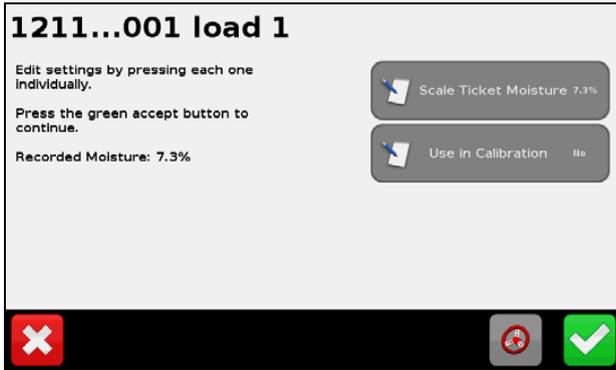


A message appears stating that the current field has been calibrated successfully.

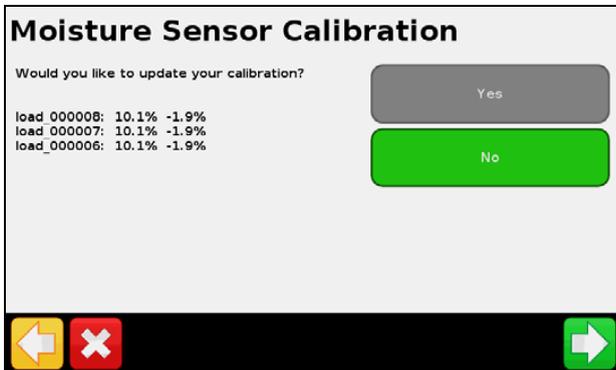
9. In the *Yield Monitor Quick Access* screen, tap **Moisture Sensor Calibration**:



- Tap **Scale Ticket Moisture** and enter the correct moisture from the scale ticket; tap **Use in Calibration** if you want to use the value in the calibration and then tap :

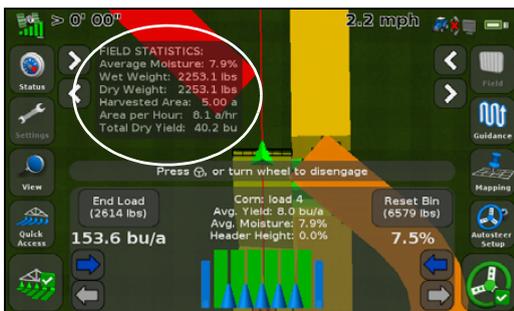


- Tap **Yes** and then tap  to confirm the Calibration adjustments:



In field operations

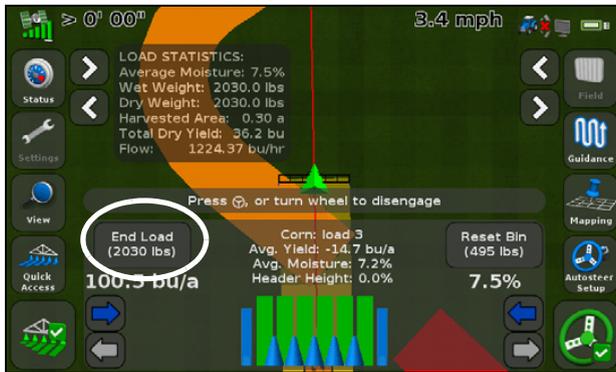
- Tap **Status** to scroll through *Field* or *Load Statistics* or the map legend:



- Tap the arrow buttons to increase or decrease header swath width: Tap **Status** to scroll through *Field* or *Load Statistics*:



- Tap **New Load** to start and stop loads for calibrations and load tracking. The CFX-750 display can hold up to 250 loads:



- Tap the logging button to manually turn logging on or off.

Note – The header height function will turn it on and off in accordance with the header position:



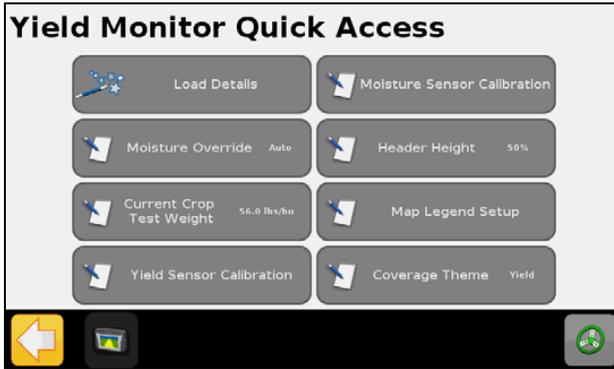
The Legend correlates the yield to the color shown for the current coverage theme:



- You can use the grain *Bin* level status item to track the amount of grain in the Grain Bin. Set up the size of the grain bin in the Yield Monitoring Setup wizard. Tap the button to reset the counter:



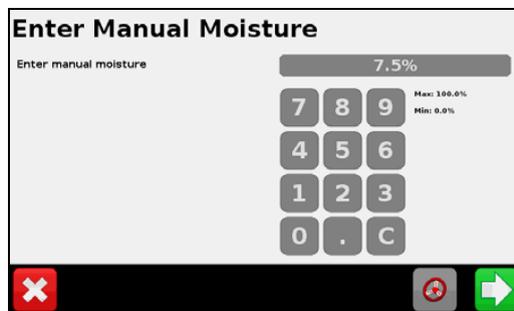
- Tap *Quick Access* to access the Yield Monitor Quick Access menu and then tap **Coverage Theme** to change the coverage layer theme:



You options in the Coverage Theme screen are *Yield*, *Moisture*, and *Overlap*:



In the *Moisture Override* screen, tap **Manual** to turn off the automated moisture sensor readings and apply a constant moisture value to the crop being harvested. You can enter the test weight of the crop being harvested to maintain yield monitoring accuracy:



You can enter the test weight of the crop being harvested to maintain yield monitoring accuracy:

Current Crop Test Weight

Enter test weight 56.0 lbs/bu

Max: 776.9 lbs/bu
Min: 0.0 lbs/bu

7	8	9
4	5	6
1	2	3
0	.	C

Status items

- The *Yield Monitor Status* screen provides detailed information on the system:

Yield Monitor Status

Field Wet Weight	0.00 lbs	▲
Load Wet Weight	0.00 lbs	
Moisture	7.37%	
Header Height	100.00% (0.00 V)	
Roll Angle	90.00°	
Pitch Angle	90.00°	
Flow	0.00 bu/hr	
Temperature	70.3 °F	
Density	56.00 lbs/bu	
Tare	0.42"	▼

- The *Sensor Status* screen provides information on the optical sensor operation:

Sensor Status

Optical Sensor	Active
Noise Level	0.00%
Elevator Speed	0.000 Hz
Percent Dark	0.00%
Moisture Sensor	Active
Sensor Value	6.86% (1.581 V)
Temperature	67.9 °F

Mapping and Guidance

In this chapter:

- Introduction
- Configuring the Guidance settings
- Starting Guidance
- Fields
- Resetting guidance
- Guidance lines
- Guidance patterns
- Line Feature Guidance
- Coverage logging
- The pause / resume function
- Curve smoothing

This chapter describes the type of guidance information that the CFX-750 display provides.

Introduction

While you work, guidance information appears on the CFX-750 display screen and the integrated lightbar that indicate the:

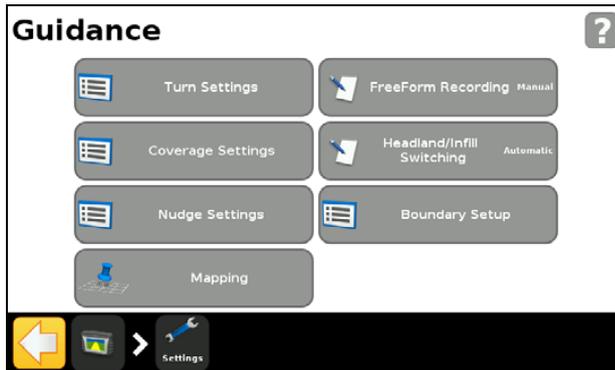
- position of your vehicle in the field
- guidance lines
- offline distance

To receive this guidance information (and any assistance from an auto steer system) you must do the following:

1. Configure how the guidance appears on your screen. See [Configuring the Guidance settings](#), below.
2. Set a guidance line. See [Guidance lines](#), page 198.
3. Configure the lightbar. See [Lightbar Setup](#), page 233.

Configuring the Guidance settings

1. From the guidance screen, tap .
2. From the *Settings* screen, tap **Guidance**.



3. Select the options to configure.

Option	To learn more, see ...
Turn Settings	page 191
Coverage Settings	page 191
Nudge Settings	page 192
Mapping	page 192
FreeForm Recording	page 193
Headland/Infill Switching	page 193
Boundary Setup	page 193

Turn Settings

The available Turn Settings are described below.

Minimum turn radius mode

This setting smoothes corners on curved AB lines, which optimizes the accuracy of your auto steer system when steering curves.

Use this mode ...	To ...
Automatic (This is the default mode.)	Set the radius to 80% of the swath width or 32.8' (10 m), whichever is larger.
Disabled	No attempt is made to keep the corners above a minimum turn radius. Note – <i>If you use this mode, curves may be very tight and the auto steering system may be unable to successfully complete the turn.</i>
Manual	Manually choose the minimum radius.

Tight turn alert threshold

The CFX-750 display alerts you when your machine is within a specified distance of a tight turn.

The threshold is set between 1 and 10. To increase the sensitivity of the alert, lower the number.

Auto U-turn detection

Auto U-turn detection operates only on FreeForm™ and adaptive curve patterns. For more information, see [Guidance patterns, page 199](#).

Use this mode ...	To ...
On	Automatically detect that the vehicle has done a U-turn and generate the next guidance line.
Off	Manually control when a path is finished. With the FreeForm pattern, you must manually stop recording. With the adaptive curve pattern, you must manually set the B point.

Coverage Settings

Configure the *Coverage Settings* options to suit the requirements of your system.

Coverage on/off delay

If you activate coverage logging at the same time as you enable your spraying or spreading system, set a coverage delay that matches the time it takes for flow to start when you turn on your spraying/spreading system. This ensures that the display records coverage from the actual start point of application. You can enter a delay time between 0.0 - 10.0 seconds.

Coverage logging

Note – Coverage logging can be recorded at speeds as low as 1.3 km/h (0.8 mph).

Use this mode ...	To ...
Disabled	Turn coverage logging off.
Manual	Turn coverage logging on and off manually.
Engaged	Automatically enable coverage logging when the auto steer system is engaged.
Switch	Use a remote switch to turn coverage logging on or off.

Nudge Settings

Option	Description
Clear nudge at swath end	When enabled, the display clears the nudged position each time you change swaths.
Reset nudge	When enabled, any applied nudge is cleared and all swaths return to their original positions.
Nudge increment	Each nudge moves the guidance line by this value. The default nudge increment is 0' 1" (2.5 cm). Enter a value between 2 - 12" (3 - 30 cm).

Mapping

Use this setting to set warning distance and recording positions for the following features:

- Point
- Line
- Area

Warning distance

You can set a warning distance so that the CFX-750 display alerts you when your machine approaches a feature.

As the machine moves to within the specified distance, a warning screen appears on the display. If you have an EZ-Steer or Autopilot system with a sonalert connected, an audible alarm also sounds.

You can set the warning distance to between 0'00" - 984' 03" (0.0 - 300.0 m).

Recording position

Choose the point at which a feature is recorded. When your vehicle is at this point, the feature will be recorded.

Delete features

Use this function to delete point, line, and area features from a selected field. Only the features are deleted—not the field itself.

FreeForm Recording

Use this setting to choose how the display records a FreeForm pattern:

Select this mode ...	To ...
Manual	Use the icons on the guidance screen to control when the path is recorded. To start recording tap  , to stop, tap  .
Record with coverage	Automatically begin and end recording the FreeForm pattern when coverage logging begins and ends. <i>Note – You can still use the FreeForm recording icon to manually override recording.</i>

Headland/Infill Switching

Use this setting to choose how guidance switches between the headland and the infill part of the field:

Select this mode ...	To ...
Automatic	Automatically switch from headland to infill when the vehicle moves inside the inner headland boundary.
Manual	Use the icons on the guidance screen to select when guidance switches from headland to infill.

Boundary setup

Use the *Boundary Setup* option to configure:

- When boundaries are active. See [Boundaries](#), below.
- How the display records boundaries. See [Expand Boundaries](#), below.

Note the following:

- When you record a boundary, the display automatically calculates the area of the boundary and shows this information on the *Status* tab.
- When you load a field that contains a boundary, the boundary also loads.
- You can record multiple boundaries in a single field.
- If your variable rate controller has section switching capability, a boundary acts as a switching barrier. When you move outside the boundary, the controller will automatically switch off the implement.

Boundaries

Select this mode ...	To ...
Enabled	Use existing boundaries and create new ones for all your fields.
Disabled for this field	Turn off boundaries for only the current field you are working in. When you begin your next field, the option will automatically change to Enabled.
Disabled for all fields	Turn off boundaries for all fields you work in, including boundaries made with headland patterns.

Expand Boundaries

Use this setting to determine how the display manages the boundary after you finish recording.

If you select this mode ...	The boundary will ...
Do not expand	Not alter once you have finished recording
Half swath width	Expand by one half swath width toward the outside of the pass
One swath width	Expand by one full swath width toward the outside of the pass

Starting Guidance

Before you can use the display for guidance, you must configure your implement:

1. From the guidance screen, tap  and then tap **Create New Field**.
2. In the *Create New Field* screen, tap **Implement Setup**.
3. Edit the settings for each option. For more information, see [Implement Setup options, page 194](#).
4. Select a pattern type (see [Guidance patterns, page 199](#)) and continue through the wizard.

Implement Setup options

For optimum guidance, make sure that you enter accurate information for the implement that is attached to the vehicle. Incorrect information may result in gaps and overlaps in coverage.

The following table describes each of the Implement Setup options:

Option	Enter a measurement between ...	This adjusts guidance and coverage logging when ...	Notes
Implement Width	1' 00" - 328' 01" (0.305 - 99.990 m)		
Overlap/Skip	394" skip and 394" overlap (1000 cm)		To avoid skips in application coverage, set an intentional overlap.

Option	Enter a measurement between ...	This adjusts guidance and coverage logging when ...	Notes
Left/Right Offset	1969" right and 1969" left (5000 cm)	The implement is offset from the vehicle center line.	When configured and online, the implement should be over the guidance line, with the vehicle to the side. For guidance when driving, use the LEDs on the lightbar. For more information, see Reading lightbar patterns, page 37 .
Forward/Back Offset	1188" behind and 384" forward (3018 cm - 975 cm)	The implement is not centered directly under the GPS antenna (for EZ-Steer systems) or the fixed axle of the vehicle (for Autopilot systems).	Set a Forward Offset when the implement is forward of the antenna (on the front of the vehicle) for EZ-Steer systems, or forward of the fixed axle of the vehicle for Autopilot systems. Set a Back Offset when the implement is behind the antenna (on the back of the vehicle) for EZ-Steer systems, or behind the fixed axle of the vehicle for Autopilot systems.
Implement Draft	393.7" left and 393.7" right (1000.0 cm)	There is a variable implement draft caused by a side slope and/or an implement pulling to one side.	
Implement Mount Type			Choose the type of implement mount that is in use

Using guidance on curved segments

After you define a guidance line, there are two ways to get guidance:

- Drive the vehicle through a tight U-turn. The next guidance line appears.
- If you are manually logging a FreeForm curve, tap  to stop defining the current line.

The FreeForm curve is similar to an adaptive curve. You must record your line on each pass to receive guidance on the next. If the vehicle is not drawing a line (or guidance trail) behind it, you are not recording your path and therefore the next guidance line will not appear.

Note – Do not confuse the existing guidance line with the guidance trail appearing behind the vehicle that shows your current guidance. You need to create a new guidance line to receive guidance on the next pass.

Using guidance on straight segments

When driving on straight AB lines, you do not have to record your path because the guidance lines are generated automatically.

Creating straight sections on Headland or Curve swaths

To create straight sections when recording headland or curve swaths:

1. Tap .
2. Drive the section.
3. Tap  to finish recording the straight section and to start recording a curve again.

Fields

A “field” is specific area of land where events (such as planting seed or applying fertilizer) are carried out.

You create your first field when you first configure your implement (see [Starting Guidance, page 194](#)). That field remains open until you do one of the following:

- Create a new field, or load a previously saved field.
- Calibrate your EZ-Steer system.
- Perform a hard reset.

Note – *Fields are stored automatically. You do not have to actively save a field.*

The following sections describe how to use the field function when there is already a field currently loaded on the display.

Creating a new field

1. In the guidance view tap . The *Finished with Field* screen appears.
2. Tap **Yes**.
3. In the *Create New or Select Old Field* screen, tap **Create New Field**.
4. To setup the new field, progress through the wizard.
5. Follow the on screen instructions to drive your new line. For more information, see [Mapping an AB line, page 200](#).

Adding an AB line to a current field

To create a new AB line in a current field:

1. In the guidance view tap . The *Finished with Field* screen appears.
2. In the *Finished with Field* screen tap **No**.
3. In the *Create New or Select Old Swath* screen, tap **Add AB Line**.
4. To set up the new field, progress through the wizard.
5. Follow the on screen instructions to drive your new line. (For more information, see [Mapping an AB line, page 200](#)).

Selecting (loading) an AB line into a field

1. In the guidance view tap . The *Finished with Field* screen appears.
2. In the *Finished with Field* screen tap **No**.
3. In the *Create New or Select Old Swath* screen, tap **Select Old**.
4. To set up the new field, progress through the wizard.
5. Follow the on screen instructions to drive your new line. For more information, see [Mapping an AB line, page 200](#).

Record keeping

Optionally, you can record operational and environmental information about each field that you create, including:

- Operator
- Farm location
- Application method
- Wind direction
- Temperature
- Target pests
- EPA license number
- Vehicle
- Wind speed
- Sky conditions
- Humidity
- Applied material
- Harvest year
- Implement
- Wind gust speed
- Soil conditions
- Crop

Additionally, there are four custom fields where you can enter your own values.

To learn how to use this information, see [Chapter 11, Data](#).

Resetting guidance

To reset guidance, in the guidance view, tap . The *Finished with Field* screen appears:



To map a new:

- **field** or select an existing field, select *Yes*.
- **AB line** or select an existing AB line in the current field, select *No*.

Note – If you select ‘Yes’, then the current field automatically closes. This means that you cannot cancel out of the New Field wizard and go back to your current field.

Guidance lines

To create a guidance line, you define a start point (A) and an end point (B). Once you define the A and B points, the display draws a line between them. This is the master AB line.

Note – AB lines are stored automatically. You do not have to actively save an AB line.

When you define the first guidance line, the display copies it to create additional guidance lines.

Distance between guidance lines

When you define the AB line, you specify the width of the implement that is attached to the vehicle. The display uses this measurement to calculate the distance between the guidance lines. If you do not want the guidance lines to be exactly one implement width apart, you can set an overlap or skip.

Headlands

You can record a headland boundary, or you can work without a headland.

On screen appearance

When the guidance screen shows the trailing view, it tags the guidance lines with the following icons:

These icon/s	Are tagged to ...
	The master line that you created. The swaths are based on this line.
 	The A (start) and B (end) point on the master line.
	The first swath to the left of the master line, where 'left' is relative to the direction the master line was drawn, not the vehicle's current position. Note the following: <ul style="list-style-type: none"> • The current swath and tag are orange. • On a Pivot pattern, the swaths are numbered out from the center, not from the initial swath.
	The second line to the left of the master line.

Guidance patterns

Select a guidance pattern that enables you to create a guidance line to suit your field:

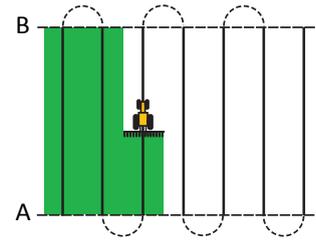
1. From the guidance screen, tap  and then tap **Create New Field**.
2. In the *Create New Field* screen, tap **Pattern Type**.
3. Select the pattern to use:

Pattern	To learn more, see ...
Straight AB	page 200
A+ line	page 200
Identical curve	page 201
Adaptive curve	page 201
Pivot	page 202
Headland	page 202
FreeForm	page 204

Straight AB

Use a straight AB line when you do not need to define headlands and you want to drive the field in parallel straight lines.

Note – When the vehicle is on a guidance line, the line extends 1 km (0.6 miles) before point A and 1 km beyond point B. This makes it easier to see where the next swath is and to get online after a turn.



Mapping an AB line

1. Drive to the start point of the master line.
2. Tap  and then drive to the end of the line.
3. When the icon is highlighted, tap . The master AB line appears.
4. Turn left or right for the next swath. As you move toward the next swath, it appears on the screen and turns orange to show that it is selected.

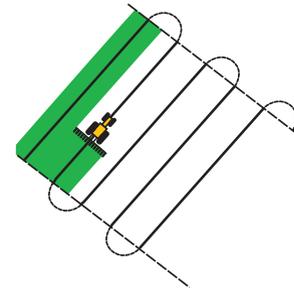
A+ line

An A+ line is a straight line, defined by a single A point on the line and the heading of the line. When you create an A+ line, you must enter a heading in the *A+ Heading* screen. By default, the A+ heading is the same as the previous AB line.

An A+ line is useful when you need guidance exactly parallel to the last AB line, for example when:

- driving adjacent fields
- mapping the AB line on a road down the side of the field
- skipping an access road in a field

The A+ line extends 1 km (0.6 miles) before and after the A point.



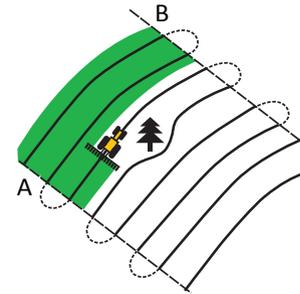
Mapping an A+ line

1. Drive to the start point of the master line.
2. Tap  and then drive to the end of the line. Because you have already set the line heading, the master AB line appears on the screen.
3. For guidance down the first swath follow the AB line.
4. Turn left or right for the next swath. As you move toward the next swath, it appears on the screen and turns orange to show that it is selected.

Identical curve

The identical curve pattern records your exact route between the A and B points, instead of creating a straight line. All subsequent guidance lines will match the master curve, regardless of where you drive the vehicle.

Use the identical curve pattern when you want to work a field with gentle curves.

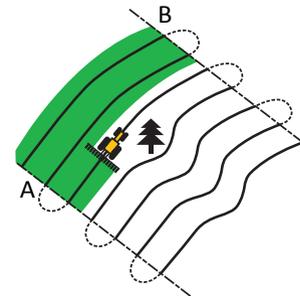


Mapping an identical curve

1. Drive to the start point of the curve.
2. Tap  and then drive the initial curve.
3. When the icon is highlighted, tap . The master curve appears on the screen.
4. Turn left or right for the next swath. As you move toward the next swath, it appears on the screen and turns orange to show that it is selected.

Adaptive curve

The adaptive curve pattern provides guidance along a curve and updates guidance after each swath to take into account any deviations you make. It continually records your path and provides guidance that matches the last path you drove.



Mapping an adaptive curve

You can map an adaptive curve either manually or automatically. The method you use depends on the Auto U-turn detection setting.

To change the Auto U-turn detection setting:

1. In the *Settings* screen, tap **Guidance**.
2. Tap **Turn Settings**, then **Auto U-Turn Detection**.
3. If you want to map the adaptive curve:
 - Automatically; select *On*.
 - Manually; select *Off*.

To map an adaptive curve with automatic turn detection:

1. Drive to the start point of the curve.
2. Tap  and then drive the initial curve.
3. At the end of the first curve, perform a U-turn. The system detects the turn and generates the next swath.

To map an adaptive curve manually:

1. Drive to the start point of the curve.
2. Tap  and then drive the initial curve.
3. At the end of the first curve, tap . The system generates the next swath.
4. Continue to drive the swaths, setting the B point at the end of each one.

Using the adaptive curve pattern for row-finding

1. Set *Auto U-Turn Detection* to *Off*.
2. Create a guidance line based on the adaptive curve pattern.
3. Set the B point at the end of each row.
4. Turn the vehicle toward the next swath. When the vehicle is halfway through the turn, guidance along the next swath appears.

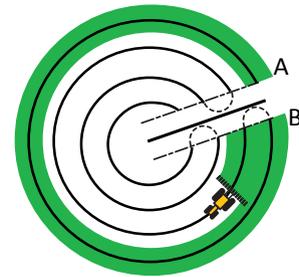
Pivot

Use the pivot pattern on fields that use center-pivot irrigation. With this pattern, you can drive concentric circles around the center-pivot.

To map a pivot:

Note – Always set the master line near the outer edge of the field.

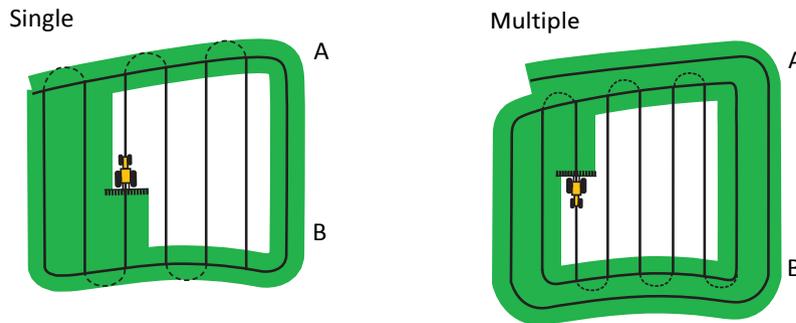
1. Drive to the start point of the pivot.
2. Position one wheel of the vehicle in a pivot wheel rut, with the rear of the vehicle to the pivot arm. If the field is not a full circle pivot, face the rear of the vehicle to the edge of the field.
3. Tap  and then drive around the field. Keep the vehicle in the rut. The display will generate guidance swaths.
4. Turn left or right for the next swath. As you move toward the next swath, it appears on the screen and turns orange to show that it is selected.
5. Steer the vehicle so that the lit LEDs are centered on the lightbar as you drive forward along the swath.



Headland

The headland pattern enables you to define the boundary (headland) of the area, as well as the guidance lines contained within it. Use the headland pattern to allow room to turn.

The following diagrams show the two headland patterns:



When you start to define the headland, you define the internal guidance line as you drive around the headland and then you complete the headland.

You can change two settings for the headland pattern:

- The number of circuits
- The internal pattern

Number of circuits

When you create a headland, you must specify the total number of circuits (including the master headland). This defines how wide the headland is.

Note – No matter how many circuits you create, define only the outside headland. The inner headlands are copied from that original circuit.

Internal pattern

The internal pattern is the pattern of the guidance lines inside the headland. Choose from the following:

Choose this pattern ...	To create ...
Straight AB	Standard parallel swaths inside a headland
A+	Parallel swaths at a pre-defined heading

Reselecting the headland

When you use the headland pattern, you can see either the headland or the internal pattern.

To see the headland guidance again when you are driving the internal pattern, drive into the headland before the first internal swath or after the final internal swath. The headland appears automatically.

Mapping a headland

1. Drive to the start point of the headland.
2. Tap  to set the start point of the headland.
3. Begin to drive the circuit of the headland.

Note – To ensure straight sides on the headland, you can use the pause feature. See [Creating straight sections on Headland or Curve swaths, page 196](#).

4. Tap  to set the A point of your guidance line. If the internal pattern is an:
 - A+ line, the line is set.
 - An AB Line, continue to drive around the headland. When you reach the other end of the internal guidance line, tap  to set the B point.

When you define the internal pattern guidance line, the start-point circle appears around the start point of the headland.

Note – If you return to the start of the headland before you define a guidance line, the headland will not complete.

5. To complete the headland, do one of the following:

Note – Define the master line for the internal pattern before you complete the headland.

- Drive around the rest of the headland until you return to the start-point circle. When you drive into the start-point circle, the headland completes automatically.
- Drive part of the headland and then tap . The headland completes with a straight line from the vehicle position back to the start point.

Once you complete the headland, the headland guidance line appears.

When the vehicle moves out of the headland and into the interior of the pattern, the interior is populated with your selected the guidance line pattern (straight AB or A+).

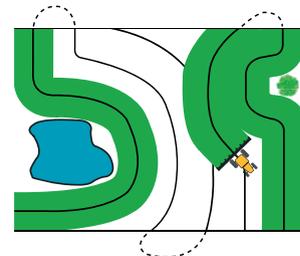
FreeForm

Use this pattern type to create curved and straight lines for guidance in fields of any shape.

The display records the exact path you drive, and uses this to generate the next guidance line.

To select the FreeForm recording option:

1. In the *Settings* screen, tap **Guidance** and then **FreeForm Recording**.
2. Tap **Manual** or **Record with coverage**.



Recording a FreeForm curve

1. Drive to the start point of the FreeForm curve.
2. To use:
 - **Manual** recording, tap .
 - **Record with Coverage** tap either  or .

While the display is recording the current path,  appears on the guidance screen.
3. Drive the curve. To record straight sections, you can use the pause feature. See [Creating straight sections on Headland or Curve swaths, page 196](#)
4. To finish recording, do one of the following:
 - If Auto U-Turn Detection is on, perform a tight U-turn.
 - For **Manual** recording, tap .
 - If you are using **Record with Coverage**, tap  or .

Note – If Auto U-Turn Detection option is off, you must manually stop recording at the end of each pass and then start recording again at the beginning of the next pass.

Using the FreeForm pattern to define a straight AB line

1. Tap  and then drive to the end of the line.
2. At the end of the line, tap .

Switching to another line

To switch from the current FreeForm guidance line to another, tap .

The first time you tap the icon, guidance snaps to the next nearest curve. Continue tapping the icon to cycle through other guidance lines.

Note – To use this feature, the vehicle must be within 1.5 swath widths of a FreeForm curve.

Using FreeForm curves in spiral fields

If you are creating a spiral into the center of the field, drive the full circuit and then back onto the start of the FreeForm curve. Continue to record your guidance path as you spiral toward the center of the field.

If you encounter an obstacle in the field, continue to record your path as you drive around it. On the next pass the guidance line will adjust to reflect this.

Note – When you create a spiral with the FreeForm guidance pattern, there may be a space at the center of the spiral.

Using FreeForm curves in fields with variable terrain

Start and stop recording guidance at the ends of each pass. If there are two guidance lines in close proximity, tap  to snap to the correct line.

At any point you can add a straight AB line for repeated straight line guidance.

Tap  to switch between straight AB and FreeForm curve guidance lines.

Line Feature Guidance

Line Feature Guidance enables you to select a previously determined line feature to guide the vehicle to.

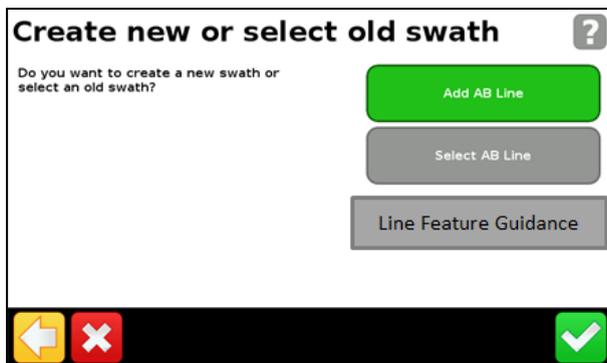
1. After setting up an AB line (see [Mapping an AB line, page 200](#)), tap  and then tap .
2. Following the on-screen instructions, begin mapping the line.
3. Map as many lines as required.

Note – If you have already created lines using the Farm Works software or using another display, you can load these files. Select *Settings / Data / Manage Data / USB / Retrieve Data / Get files from USB*. Ensure that the files are loaded into the same directory as the field that is currently open.

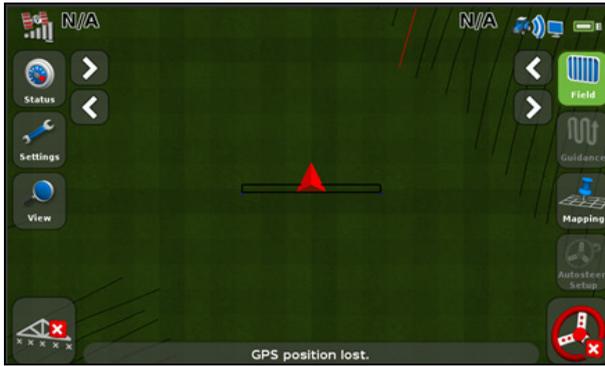
4. Tap . The *Finished with Field* screen appears:



5. Tap **No**. The *Create new or select old swath* screen appears:



6. Tap **Line Feature Guidance**.
7. In the *Select Line Features or Swaths* screen, select the line or lines that were created/imported, or tap **Guide to All**.
8. In the *Confirm Implement* screen, confirm that the information is correct.
9. In the Run screen, the nearest selected line feature is now highlighted and can be guided to.



Coverage logging

Coverage logging draws a solid block of color behind the vehicle to show the area that you have applied. When you pass over an area for the second time, the color of the covered area changes. This is useful for viewing overlaps.

To begin coverage logging, tap  while you are driving; to finish coverage logging tap .

Note – There may be a delay between the time you start or stop coverage logging onscreen and the time the implement actually starts or stops coverage. To compensate for this you can add a time delay to the drawing of coverage logging. See [Coverage on/off delay, page 191](#).

Note – Field coverage is limited to 1000 acres for each event.

The pause / resume function

When you tap Pause , an icon appears on the screen to show your exact location when the guidance was paused. This enables you to return to that position in the field.

When you pause guidance:

- Your current position relative to the pause icon appears in the status bar at the top of the screen.
- The guidance line that you were on is displayed, even if you drive onto another swath.
- The pause/resume icon remembers the vehicle position even when the lightbar is turned off.

Curve smoothing

By default, the CFX-750 display smooths curves for improved guidance and auto steering. You can disable curve smoothing on tight turns (curves that have a radius of less than 3m (10 ft.).

Note – *If you disable curve smoothing, the CFX-750 display or the Autopilot system may not be able to auto steer around the tighter turns. Be careful when you disable curve smoothing.*

To disable curve smoothing:

1. In the *Settings* screen, tap **Guidance** and then tap **Turn Settings**.
2. Tap **Minimum Turn Radius Mode** and then select **Automatic**, **Disabled** or **Manual**.

GPS

In this chapter:

- [Introduction](#)
- [GPS Setup](#)
- [Position Quality](#)
- [Advanced](#)
- [Status](#)

This chapter describes how to set up the GPS receiver.

Introduction

The *GPS* menu enables you to select which GPS system and correction source to use, and the GPS quality tolerance.

To access the menu:

1. From the guidance screen, tap .
2. From the *Settings* screen, tap **GPS**:



GPS Setup

Use the *GPS Correction Source* screen to choose the type of GPS position corrections that you want to use:

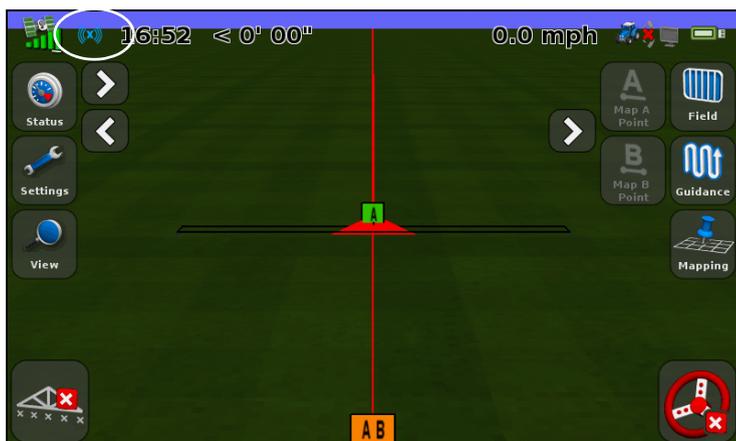
Source	Description
WAAS / EGNOS	Free satellite-based corrections: <ul style="list-style-type: none"> • WAAS (Wide Area Augmentation System) in North America • EGNOS (European Geostationary Navigation Overlay Service) in Europe
OmniSTAR VBS	Satellite-based subscription correction service
OmniSTAR XP/HP/G2	High accuracy satellite -based subscription correction service
RTK (Real Time Kinematic)	Radio-broadcast corrections from a ground-based reference station. When you select RTK as the GPS Correction Source (depending what is unlocked), any of the following may appear: Correction Delivery Method: <ul style="list-style-type: none"> • Internal Trimble Radio • External Trimble Radio • CenterPoint RTX (fast-sat) • CenterPoint RTX (std-sat) • CenterPoint RTX (std-cell) • Trimble VRS Modem • Generic CMR Radio • Generic RTCM3 Radio When any of the above RTK sources are selected, the following option appears in the <i>Advanced</i> screen: <ul style="list-style-type: none"> • RTK Scintillation Mode

Source	Description
<p>RTK, <i>continued</i></p>	<p>If you select one of the Trimble Radio options, you can also enter:</p> <ul style="list-style-type: none"> • Radio Network ID • SecureRTK Keys • SecureRTK Keys Status • Use xFill (select <i>Yes</i> or <i>No</i>. If you select <i>Yes</i>, the next two screens appear, <i>xFill Lband Settings</i> and <i>RTK Base Datum</i>.) • xFill Lband Settings (select the frequency and baud rate) <ul style="list-style-type: none"> • RTK Base Datum (select the datum that was used when the RTK base station was surveyed. For more information, contact your local reseller.) <p> CAUTION – You must select the correct base datum for your location. If you select an incorrect value, this will result in incorrect xFill operation.</p> <p>If you select the Trimble VRS Modem or CenterPoint RTX (std-cell) option you can also select your device (DCM300 or Ag3000).</p> <p>If you select any OmniSTAR or CenterPoint RTX option, also enter:</p> <ul style="list-style-type: none"> • Frequency and Baud Rate • FastRestart: On/Off • Threshold for Favor Accuracy
<p>RangePoint™ RTX™</p>	<p>Satellite-based subscription correction service.</p>
<p>Uncorrected</p>	<p>No GPS corrections</p>
<p>Ext. Corrections</p>	<p>Select when using corrections from an external corection source.</p>

Using xFill technology

During RTK signal interruptions, xFill™ technology can sustain RTK system operation for up to 20 minutes.

xFill technology automatically turns on when the RTK signal is interrupted. The xFill icon appears in the upper left of the Run screen:

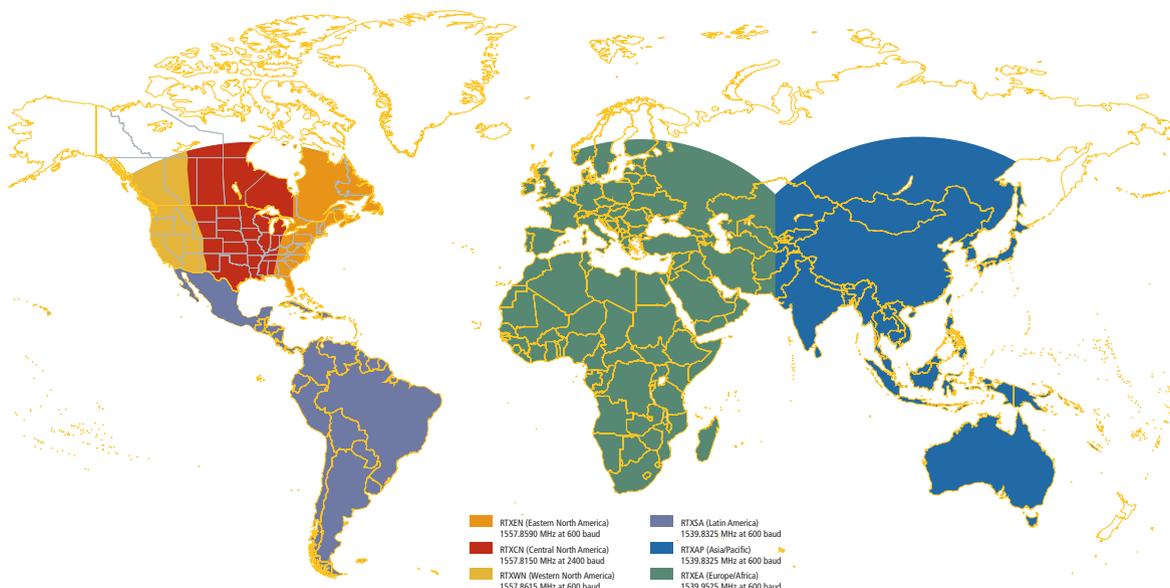


The color of the xFill icon indicates the following:

If the icon is ...	xFill is ...
White	ready.
	
Blue	engaged, and has been used between 0 and 15 minutes.
	
Red	engaged, and 5 minutes remain.
	

Frequency / Baud map

The Frequency / Baud map, shown below, allows you to set the frequency and baud values based on location.



When receiving satellite signals, you must select the frequency and baud rate based on your specific region:

- Western North America (RTX WN): 1557.8615 MHz at 600 baud
- Central North America (RTX CN): 1557.8150 MHz at 2400 baud
- Eastern North America (RTX EN): 1557.8590 MHz at 600 baud
- South/Central America (RTX SA): 1539.8325 MHz at 600 baud
- Europe/Africa (RTX EA): 1539.9525 MHz at 600 baud
- Asia Pacific (RTX AP): 1539.8325 MHz at 600 baud

Note – These frequencies do change occasionally. If you experience issues with the satellite signal, contact your reseller for updated satellite information.

Position Quality

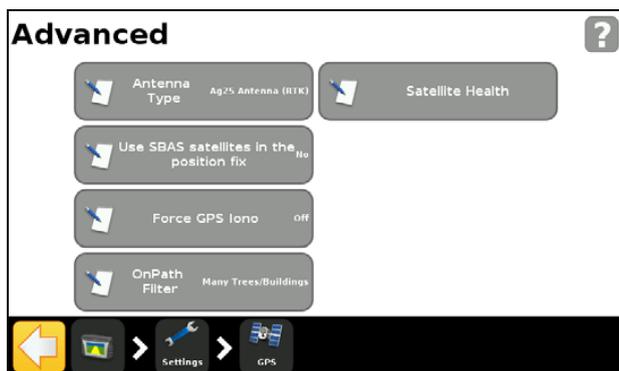
GPS signals can be disrupted by foliage, or when the machine moves out of sight of one or more satellites, or when one or more satellites move out of sight of the machine or 'set' below the horizon.

The *Position Quality* screen provides options that allow you to operate when the quality of GPS position information is compromised.

Option	Description
Favor Accuracy	Provides the highest level of accuracy.
Balanced Quality	Trades potential accuracy for a slight increase in production time.
Favor Availability	Extends production time further, with more potential for reduced accuracy.

Advanced

The *Advanced* screen enables you to view and adjust advanced GPS settings.



Antenna Type

Access the *Antenna Type* screen to alter the internal settings of the GPS receiver to ensure optimum accuracy for the antenna.

Select the antenna you have connected to the display. The AG-25 antenna is white and dome shaped.

Use SBAS satellites in the position fix

Choose this option if you want to use SBAS corrections from WAAS satellites to calculate the GPS positions. For example, if the display receives position information from six standard GPS satellites and two WAAS satellites, the display uses all eight satellites to calculate the GPS position.

This can extend operating time when limited number of satellites are available.

Note – This option does not work with EGNOS satellites, OmniSTAR, or RTK corrections.

Force GPS Iono

Choose *On* to force the use of modeled rather than real-time ionosphere data.

This setting is designed primarily for locations at the edge of SBAS coverage, such as northern Canada, and could affect accuracy if used elsewhere.

Satellite Health

You can use this setting to disregard signals from a specific satellite due to concerns about its state. For more information, contact your reseller.

Status

The *Status* screen enables you to view the current status of the GPS functions.



GPS Status

The *GPS Status* screen displays information about your position and the current GPS signal strength.

Satellite Status

The *Satellite Status* screen displays information about the current satellite constellation.

The information for each satellite is contained in one line. The following table describes fields that the line contains:

Field	Description
Sv	Satellite number <i>Note – GLONASS satellites have an "R" in front of the satellite number; GPS satellites do not.</i>
El	Elevation
Az	Azimuth
L1	L1 SNR
L2	L2 SNR

Field	Description
Corr	Correction (appears only if correction is applied)
Used	Used (appears only if the satellite is used in position calculation)

DGPS Status

The *DGPS Status* screen displays which DGPS signal is selected from the GPS Correction Source screen. For more information, see [GPS Setup, page 210](#).

Data

In this chapter:

- [Introduction](#)
- [Connected Farm Setup](#)
- [Manage Data](#)

The CFX-750 display saves field data to its internal memory. You can transfer this data to your home or office computer through a USB drive, or wirelessly through the Connected Farm™ server.

This chapter describes how to manage the data generated by the CFX-750 display.

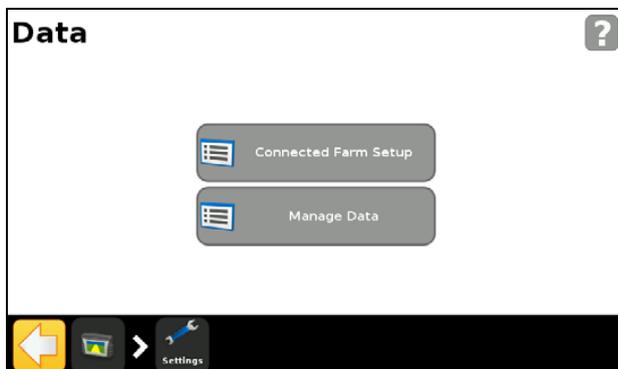
Introduction

In the Connected Farm server, use the options in the *Data* menu to:

- Save and retrieve fields from the USB drive.
- Send fields (via Connected Farm) to your home or office computer.
- Delete fields and coverage logging.
- Export diagnostic log files to the USB drive for technical support purposes.
- Copy prescriptions from the USB drive to the internal memory and delete from the internal memory.

To access the *Data* menu:

1. From the guidance screen, tap .
2. From the *Settings* screen, select *Data*. The following screen appears:



DCM-300 modem

This section describes how to set up a DCM-300 modem for use with VRS™ corrections.

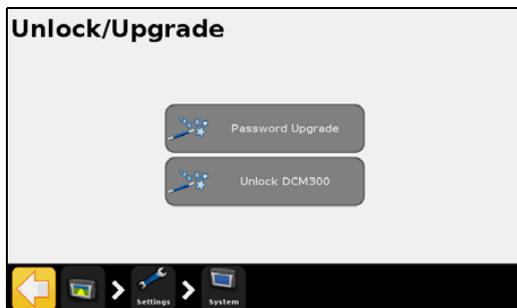
Passcodes

The DCM-300 modem requires a passcode **upgrade** to use VRS and Connected Farm functions.

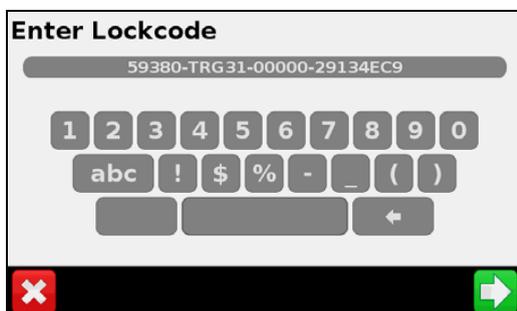
VRS and Sync File Transfer functions in the DCM-300 modem must be **unlocked** to begin using VRS corrections or transferring data.

To unlock the modem with a passcode:

1. Turn on the modem and then connect it to the display's USB port.
2. Select the Wrench icon and then select *System / Unlock/Upgrade*.



3. Enter the passcode. When prompted, select **Yes** to restart the modem.

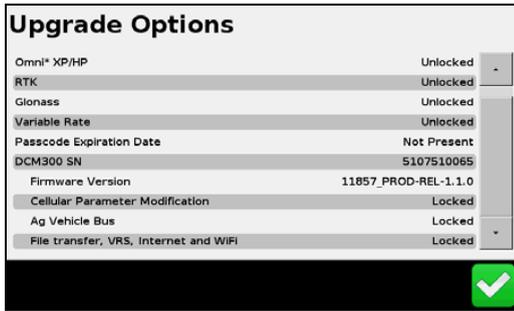


The DCM-300 modem will be ready to use after approximately three minutes.



To view the status of the modem unlocks, select the Wrench icon and then select *System / Status / Upgrade Options*.

To use VRS corrections, you must unlock the File Transfer, VRS, Internet, and WiFi options.

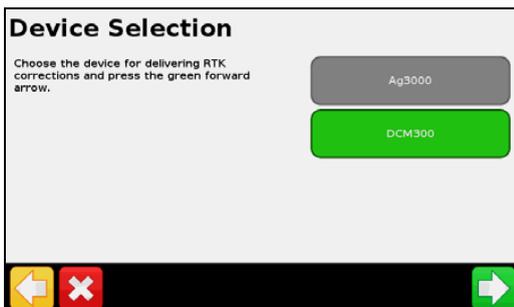
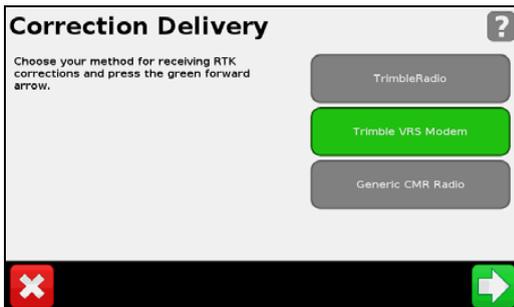


DCM-300 upgrade option	Description
Cellular Parameter Modification	Needed for DCM-300G modem when the customer supplies their own SIM card
Ag Vehicle Bus	Future functionality
File Transfer, VRS, Internet, and WiFi	Required for the use of VRS or Connected Farm Sync functions

Configuring the display for VRS corrections

Note – The display must be unlocked for RTK to use the Trimble VRS correction type.

1. To access the GPS Setup screens, select the Wrench icon and then select GPS / GPS Setup / GPS Correction Source / RTK.
2. Select the option for Trimble VRS Modem and then select Continue.
3. From the device selection list, select the required Trimble modem option.

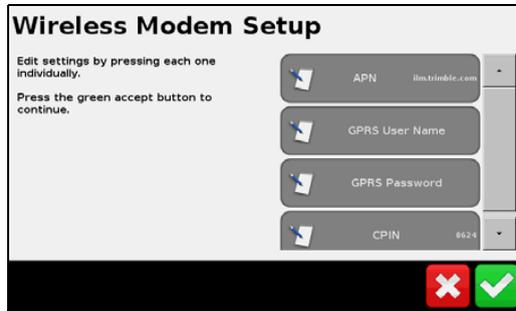


Configuring VRS settings

1. Connect the modem and turn it on.
2. Select the required Trimble modem and then follow the on-screen instructions.

The first step in the VRS setup wizard is Wireless Modem Setup. This is required only for Trimble modems where you have installed a SIM card.

Wireless Modem settings are as follows. The SIM card provider is responsible for providing any settings required.



Wireless modem settings	Description
APN	Mobile Network Access Point Name, usually required by the network
GPRS User Name	Mobile Network User name, optional setting – check with your mobile network if this setting is required
GPRS Password	Mobile Network Password, optional setting – check with your mobile network if this setting is required
CPIN	SIM PIN, optional password lock to restrict use of the SIM card

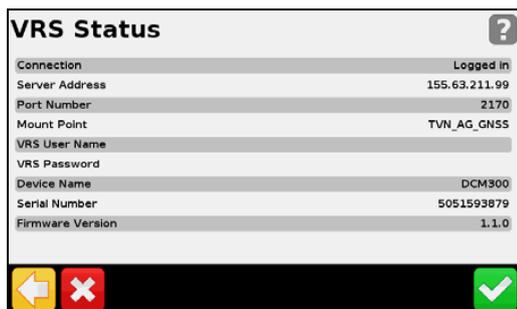
The next steps in the wizard guide you through entering VRS settings provided by your Trimble CenterPoint™ or Network RTK provider. The required settings are as follows:



Internet base settings	Description
Server Name/Address	RTK/VRS/CORS base station broadcast name
Server Port Number	Server Port Number
Mount Point	Base station mount point

Internet base settings	Description
VRS User Name	Network Assigned username
VRS Password	Network Assigned password

Once the wizard is completed, a screen shows the VRS connection status, and details all the settings entered. The VRS status message types are as follows:



VRS connection status	Description
Logged in	VRS connected
Connecting	Mobile network - Searching
Disconnected	Mobile network - No service

Connected Farm Setup

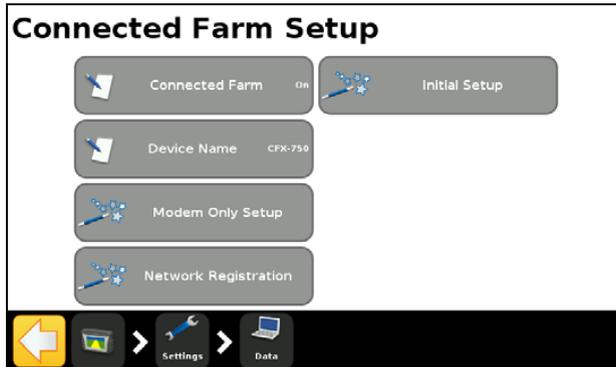
When you enable the Connected Farm feature, this allows the CFX-750 display to use the Connected Farm server to automatically and wirelessly send field information to your home computer.

Initial setup

The Initial Setup wizard takes you through the process of setting up your wireless modem and registering the network.

By default, the Connected Farm feature is set to *Off*. To turn the feature on:

1. Tap **Connected Farm Setup** and then **Connected Farm**.
2. Select *On*. The *Connected Farm Setup* screen appears:



Note – When you turn the *Connected Farm* option *On*, tapping *Connected Farm Setup* takes you directly to the *Connected Farm Setup* screen.

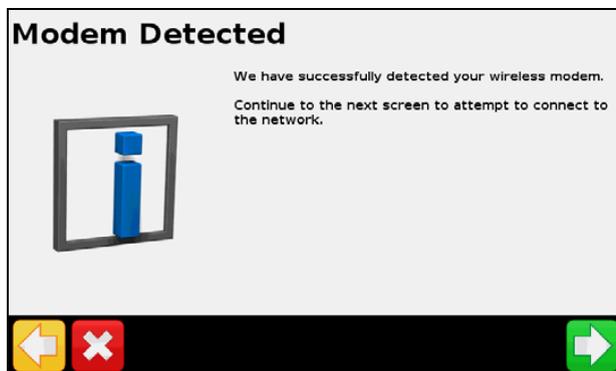
The following sections describe the menu options available from the *Connected Farm Setup* screen.

Device name

Use the on-screen keypad to give your device a name that you will recognize once you transfer the data to your personal computer.

Modem only setup

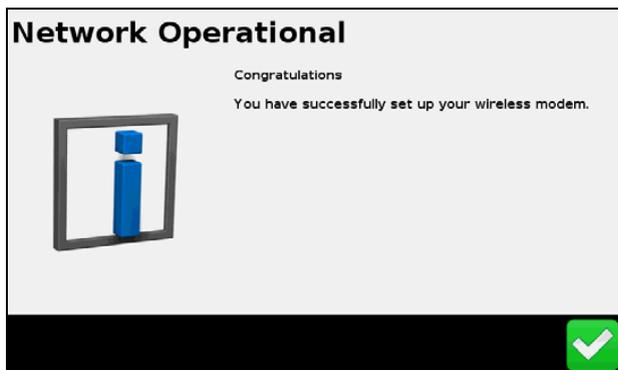
Use this option to set up your wireless modem. Once you connect your modem, the following screen appears:



In the Wireless Modem Setup screen, you can adjust the following:

- APN/Setup String
- SIM PIN
- Network username: change the username used for network registration.
- Network password: change the password used for network registration.

After you set up your modem, the following screen appears:



Once you receive this message, you can continue with the registration process.

Note – The internal settings for your modem are on the SIM card that your modem uses. For further setup information, contact your SIM card provider.

Network registration

Register your information with the Connected Farm Network. Use the username and password you created when you purchased the Connected Farm service. For more information contact your Trimble reseller.

Connected Farm data transfer

Note – The Connected Farm service requires a subscription. For more information on purchasing a subscription, contact a Trimble reseller.

To configure Connected Farm operations:

1. Tap  and then select *Data / Connected Farm Setup*.
2. To enable the feature, select the option to turn on the Connected Farm service.

The setup menu now includes a number of settings, as shown below. If you are a first-time user of the Connected Farm service, select Initial Setup to open a setup wizard:



Connected Farm setup option	Description
Connected Farm	Turns Connected Farm functionality on/off
Device Name	User defined name to identify the display in Farm Works software
Check Server	Controls how often to check for new jobs or data
Modem Only Setup	Checks for a connected modem
Network Registration	Connected Farm registration
Initial Setup	First time Connected Farm setup wizard. This requires a DCM-300 modem to be connected and in an area with good wireless service. Once the initial setup is complete, you can change individual settings as required.

Sending Field data using Connected Farm

Connected Farm field data includes event coverage, field boundaries, guidance lines, area features, line features, and point features: You can wirelessly transfer all this data from the CFX-750 display to the office.

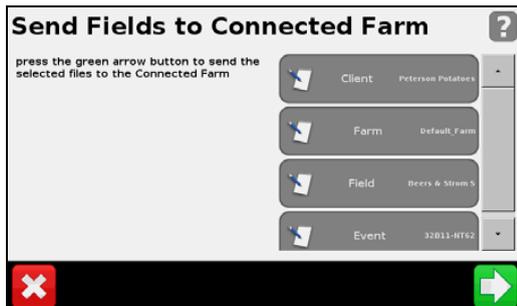
With the Connected Farm service enabled, field event data is automatically sent to the Connected Farm service when you close the event.

To manually send field events:

1. Tap  and then select *Data / Manage Data / Connected Farm / Send Data*.



2. Use the Client, Farm, Field, and Event options to select an individual field or all events, farms, or fields for a client.



Receiving Field data through the Connected Farm service

With the Connected Farm service, you can wirelessly transfer field information from the office to the CFX-750 display. Field data includes field boundaries, guidance lines, prescriptions, area features, line features, and point features.

To receive data from the Connected Farm service:

1. Select the Wrench icon and then select *Data / Manage Data / Connected Farm / Retrieve Data*.
2. From the *Retrieve Data* screen, tap **Check Server** to check for and download new field data from the Connected Farm server.

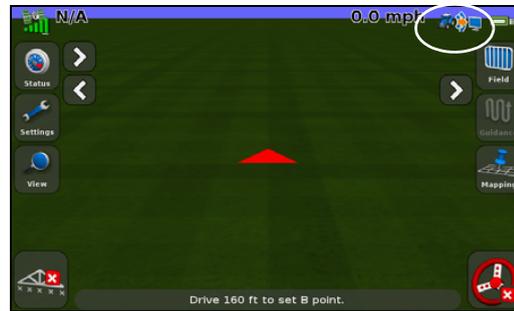
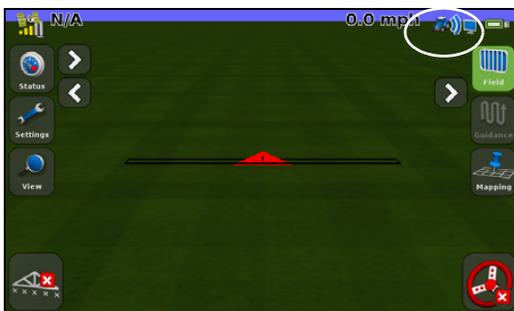
- Once the data is downloaded, select the *Get Fields from Connected Farm* option to import the data into the display. As new data is received, use the *Get Fields from Connected Farm* function to import the most recent data into the display.



The Connected Farm service adds a status icon to the Run screen that shows the status of Connected Farm operation.

An icon at the top right of the screen shows if field data is being sent or received.

When data is being sent or received, an orange arrow blinks between the tractor and office computer.



Manage Data

The *Manage Data* screen enables you to handle your data through the USB drive or the display's internal memory.

USB

The *USB* screen enables you to:

- Retrieve the field data and CFX-750 configuration files from a USB drive and transfer it to the internal memory. The field data includes:
 - Field Boundaries
 - Point, Line and Area features
 - Guidance lines

- Event data (coverage)
- Prescriptions
- Send the following data from the internal memory to the USB drive:
 - Autopilot information
 - Prescriptions
 - Client, farm and field data

Retrieving data from the USB drive

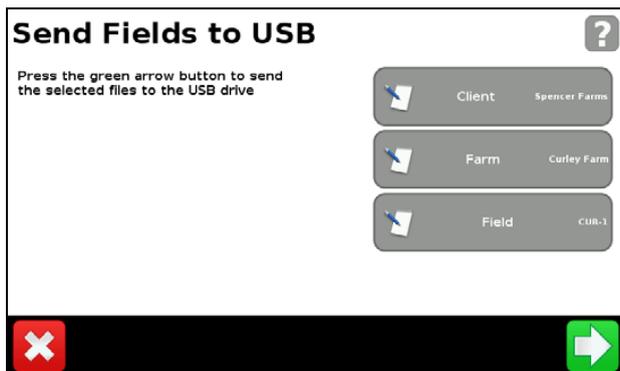
To transfer data from the USB drive to the internal memory:

1. In the *Manage Data* screen, tap USB.
2. Tap *Retrieve Data* and then choose the data that you would like to retrieve.

Sending data to the USB drive

To transfer data from the internal memory to the USB drive:

1. In the *Manage Data* screen, tap USB.
2. Tap *Send Data to USB* and then select the data to send:



Note – You cannot send data to a USB drive that is over 90% full.

For more information, see [The USB socket, page 27](#).

Clearing the internal memory

Over time, the CFX-750 display's internal memory may become full. To avoid this, delete files that you no longer require:

1. In the *Manage Data* screen, tap *Internal* and then *Delete Data*.
2. Select the information to delete and then follow the wizard until the files are deleted.

Note – If a field is currently open it will close prior to the deletion.

System

In this chapter:

- [Introduction](#)
- [Display](#)
- [Advanced](#)
- [EZ-Remote joystick](#)
- [Unlock / Upgrade](#)
- [Status](#)
- [CFX-750 screen](#)
- [Recalibrate touchscreen](#)

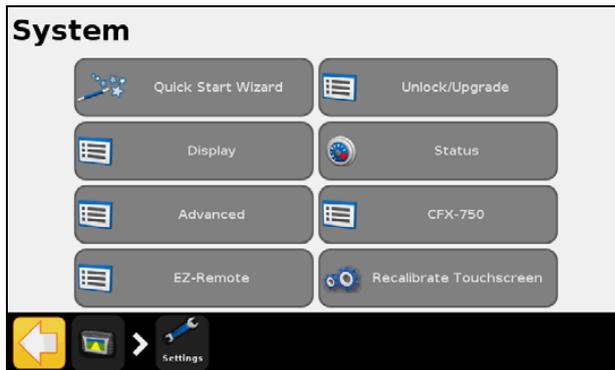
This chapter describes how to configure the system settings.

Introduction

The *System* menu enables you to adjust a variety of the CFX-750 display settings.

To access the *System* menu:

1. From the guidance screen, tap .
2. From the *Settings* screen, tap . The following screen appears:



The following sections describe the various items that are available in the *System* menu.

Display

Use the items in the *Display* screen to adjust the appearance of your CFX-750 display.

Units

You can display distances, speeds and areas in either US/Imperial or Metric format. By default, the display uses the US/Imperial format.

The available units for each format are outlined below:

Unit	US / Imperial	Metric
Distance	inches	centimeters
	feet	meters
	miles	kilometers
Speed	miles per hour	kilometers per hour
Area	acres	hectares

Color Scheme

You can adjust your color scheme according to the cab lighting and time of day. For more information, see [Backlight](#), page 233.

This color scheme ...	Is suitable for ...
Day	A brightly lit environment.
Note – This is the default color scheme.	
Dimmed	Dark and low cab light environments
Red	Dark and low cab light environments

Time Zone

The GPS receiver provides UTC (formerly GMT) time. To display and log times in your local time, set the time zone offset.

Location	Standard Time Offset	Daylight Savings Time Offset
US Eastern Time	-5:00	-4:00
US Central	-6:00	-5:00
US Mountain	-7:00	-6:00
US Pacific	-8:00	-7:00
Australia East	+10:00	-11:00 (excludes QLD)
Australia Central	+9:30	+10:30 (excludes NT)
Australia West	+8:00	+8:00

View

There are three options for the map views:

View	Description
Auto Headland	The view automatically swaps between overhead view (in headlands) and trailing view (on swaths).
Auto Engage	The view automatically swaps between overhead view (not engaged) and trailing view (engaged).
Manual	You must manually change between overhead and trailing view.

Status Popup Transparency

Use this option to control the transparency level of the status popup tab:

At this level of transparency ...	The tab is ...
10	completely solid
1	barely visible

Backlight

You can adjust the brightness of the screen backlight to maximize visibility and reduce glare in different light conditions. For more information, see [Color Scheme, page 232](#).

Touchscreen speaker volume

You can adjust the volume of the speaker according to your preference. Choose from *Loud*, *Quiet* or *Off*.

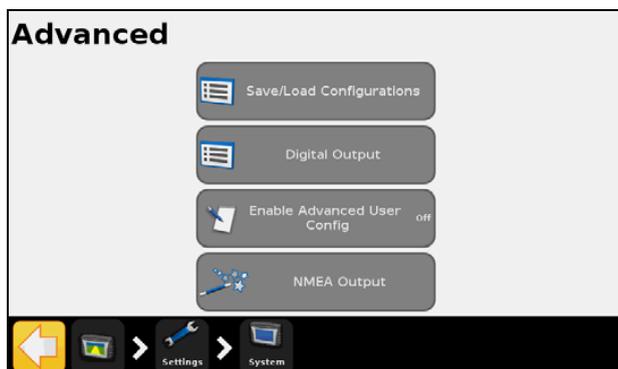
Lightbar Setup

You can adjust the lightbar settings as follows:

Use this setting ...	To ...
Look Ahead	Allow time for large vehicles to correct offline error: <ul style="list-style-type: none"> For large vehicles that take longer to turn, increase the look ahead time. For 4WD articulated tractors, always set the look ahead time to 0 seconds. Look ahead time applies to LED guidance only and does not affect EZ-Steer performance. Set the look ahead time in seconds.
LED Spacing Note – The LED spacing is the distance represented by one LED.	Adjust the sensitivity of the LEDs. To: <ul style="list-style-type: none"> increase sensitivity, decrease the LED spacing decrease sensitivity, increase the LED spacing
LED Brightness	Adjust the LED brightness for maximum visibility.
Main Lightbar LED Mode	Select the required LED mode. There are two modes to choose from: <ul style="list-style-type: none"> Chase: Chase the lights to stay online. The lights represent the swath location relative to the vehicle. Pull: Center the lights to stay online. The lights represent the vehicle location relative to the swath.

Advanced

Use the items in the *Advanced* screen to view and adjust advanced system features.



Save/Load Configurations

Once you set up your lightbar for your current job, you can save the settings to a configuration file. Saving a system configuration can be useful for:

- Quick setup when moving the display between vehicles.
- Quick setup when using the same vehicle but changing the implement or application.
- Tuning the settings for improved performance. Save your improved settings.
- Restoring known good settings if unwanted adjustments have been made.

Digital Output

The CFX-750 display can generate a digital signal on pin 2 of Port A.

Note – Additional equipment may be required to properly use the Digital Output function. To use speed pulse output, you need a radar sensor cable kit that includes a pulse amplifier adapter. Contact your local reseller.

Use this setting...	To...
Disabled	Disable digital output on pin 2 of Port A.
Radar	Output simulated radar pulses at a pre-defined speed pulse output rate. This can be useful to: <ul style="list-style-type: none"> • Replace the radar/true ground speed sensor for speed on the vehicle • Send speed to any other agricultural device requiring speed pulses, such as a yield monitor or variable rate controller. <p>Note – After you select Radar, set the radar frequency rate from the Digital Output screen.</p>
Remote Output	Output a signal whenever auto steering is engaged. This can be useful to drive a switch or relay for equipment that should be active when engaged.

Enable Advanced User Config



CAUTION – Do not use the *Enable Advanced User Config* feature unless you have the support of a Trimble Reseller. Altering any of the settings for this feature may cause system failure.

NMEA Output

NMEA (National Marine Electronics Association) messages are a standard format that GPS devices use to communicate. The CFX-750 display can output NMEA messages to communicate with other NMEA-compatible devices.

In the NMEA Port Parameters screen, specify the following:

Use this setting ...	To ...
NMEA output port	Specify the port that the NMEA device is connected to
Baud Rate	Set the transmit/receive rate of the serial port in bits per second (bps)
Data Parity	Select how the parity bit is added to the data transfer

Note – For the CFX-750 display to communicate with another device, the Port Parameters on the display must match those of the device.

In the *Message Selection* screen, select from the list of available NMEA messages:

Message	Description
GGA	Position and fix related data
VTG	Speed and heading
GSA	Position fix mode, satellites used, and the dilution of precision (DOPs)
GLL	Position and status
RMC	Status, position, speed over ground (SOG), date, and magnetic variation of the position
ZDA	Date and time
GSV	Satellite information

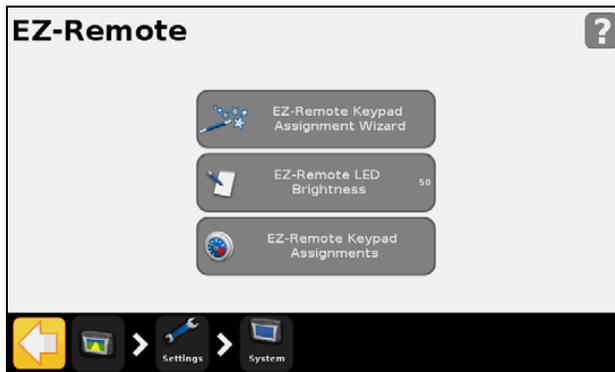
EZ-Remote joystick

The EZ-Remote option appear in the *System* menu only if you have an EZ-Remote joystick installed. For more information, see the *EZ-Remote Joystick Quick Reference Card*.

Use the *EZ-Remote* screen to:

- assign functions to buttons 1-4 on the EZ-Remote joystick
- adjust the LED brightness of the buttons

- review the button assignments.



EZ-Remote Keypad Assignment Wizard

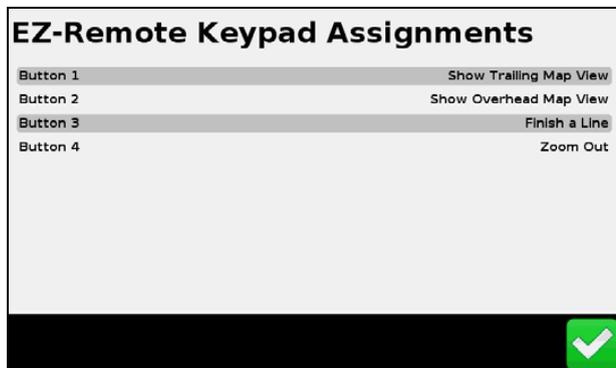
1. On the CFX-750 display, tap the first EZ-Remote joystick button to program.
2. In the *Choose a Function* screen, tap the function to assign to the joystick button. See [Using the EZ-Remote joystick, page 38](#).
3. In the *Finished* screen, select either:
 - **Choose another button** to repeat Step 1 and Step 2.
 - **Complete this wizard** to exit the wizard.

EZ-Remote LED Brightness

Use this screen to adjust the brightness of the LED buttons on the joystick. Enter a number between 0-100.

EZ-Remote Keypad Assignments

The *EZ-Remote Keypad Assignments* screen shows the functions that have been assigned to the four programmable buttons,



EZ-Remote operation

When the Run screen is active on the CFX-750 display, use the buttons on the EZ-Remote joystick to perform the functions you have assigned.



Note: The Up, Down, and Trigger buttons are not supported.

Use this button ...	To ...
Engage	Engage auto steering
Up / Down	N/A
Right	Nudge the guidance line to the right , in the guidance screen.
Left	Nudge the guidance line to the left , in the guidance screen.
Trigger	N/A
1-4	Activate the function that you have assigned. To learn how to assign a function to the programmable button, see the EZ-Remote joystick , page 235.

Unlock / Upgrade

Use the *Unlock/Upgrade* screen to:

- Upgrade your CFX-750 display to a newer firmware version.
- Unlock features, such as the Field-IQ crop input control system.

Upgrading your display

1. Transfer the new firmware file from www.trimble.com to your office computer.
2. Connect the CFX-750 display USB memory stick to your office computer.
3. Unzip the firmware file and then save it to the root folder of the USB memory stick.
4. Insert the USB memory stick into the USB socket of the display.
5. In the Unlock/Upgrade screen, tap **Firmware Upgrade Wizard**.
6. Select the file to upload and then tap . The firmware begins to load.

Once the new firmware has successfully loaded, the display automatically restarts. **Do not** disconnect the power from the display while it is rebooting.

Unlocking features

Note – To unlock features, you must obtain an unlock code from your Trimble reseller.

1. In the Unlock/Upgrade screen, tap **Password Upgrade**.
2. Enter the unlock password. Passwords are case sensitive.

Once the password is successfully entered, the display automatically restarts. **Do not** disconnect the power from the display while it is rebooting.

Unlocking the CenterPoint RTX correction service

1. From the guidance screen, tap .
2. From the *Settings* screen, tap **System**. The following screen appears:
3. In the *System* screen, tap **Unlock/Upgrade**:



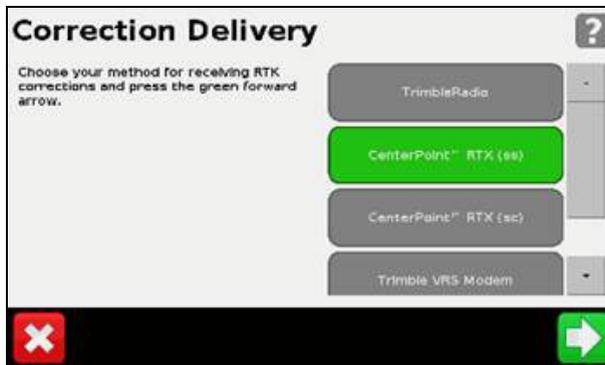
4. Tap **Password Upgrade**. The *Password Upgrade* wizard appears.

- Use the virtual keyboard to enter the password—the password is case sensitive. Ensure that you include dashes where necessary.

After you have entered a valid passcode, the Password Upgrade screen reappears with a message that the upgrade was successful. If you have entered an incorrect password, an error message appears and you are returned to the Unlock/Upgrade screen.

After you have unlocked CenterPoint RTX, set the correction type to CenterPoint RTX:

- In the *Settings* screen, tap **GPS**. The *GPS* screen appears.
- Tap **GPS Setup** and then tap **RTK**. The *GPS Correction Source* screen appears:



The *Correction Delivery* screen may contain the following options:

Option	Definition
CenterPoint RTX (ss)	Standard satellite
CenterPoint RTX (sc)	Standard cellular
CenterPoint RTX (fs)	Fast satellite
CenterPoint RTX (fc)	Fast cellular

- Tap **CenterPoint RTX (ss)**. The *CenterPoint RTX Setup* wizard appears. Read all cautions and warnings carefully. Select the appropriate settings:

Option	Description
Satellite Settings	There is no need to change any settings on this screen unless the CenterPoint RTX broadcast frequency has changed.
Position Quality	This screen provides options that enable you to operate when the quality of GPS position information is comprised. <ul style="list-style-type: none"> Favor Accuracy - Provides the highest level of accuracy. This is the recommended setting. Balanced Quality - Trades potential accuracy for a slight increase in production time. Favor Availability - Extends production time further, with more potential for reduced accuracy.

Option	Description
Threshold for CenterPoint RTX (s) Favor Accuracy	<p>Set the value at which the system will enable you to start guidance operations.</p> <ul style="list-style-type: none"> Enter a high number for broad acre applications. Enter a low number for row crop applications. <p>Note – <i>The current maximum value is 11 inches.</i></p>
FastRestart	<p>FastRestart reduces the time for the position to converge so that the system is ready for operation faster.</p> <ul style="list-style-type: none"> Select <i>On</i> when the vehicle will be parked in an area with a clear view of the sky when not in use. Otherwise select <i>Off</i>.

- In the *Frequency* tab, the frequency and baud rate are pre-selected for the US Central beam. If necessary, these values can be changed manually to track a specific Lband satellite.
- After the wizard has been completed, return to the Run screen.

Notes:

- *GPS Source is CenterPoint RTX (s).*
- *Convergence is a high value.*
- *The satellite icon is yellow, indicating the system is not ready to operate.*

The status values will change while the receiver converges to its final accuracy:

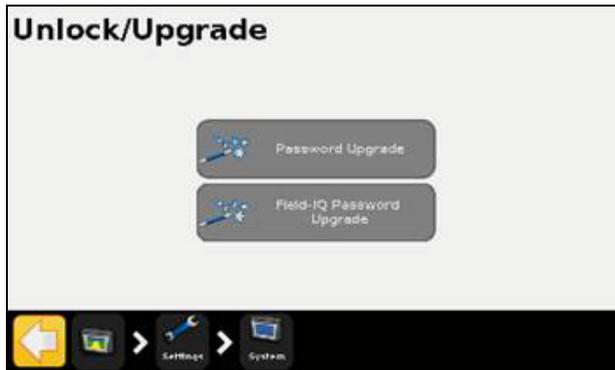


Notes:

- *Convergence has changed to the value you set in the Threshold for CenterPoint RTX (s) Favor Accuracy screen of the wizard. In this example, the threshold was set to 11 inches.*
- *The satellite icon is now green, indicating that the system is now ready to operate.*

Unlocking the RangePoint RTX correction service

1. From the guidance screen, tap .
2. From the *Settings* screen, tap **System**. The following screen appears:
3. In the *System* screen, tap **Unlock/Upgrade**:

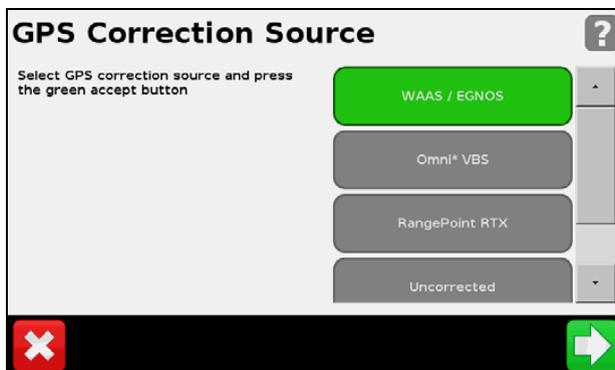


4. Tap **Password Upgrade**. The *Password Upgrade* wizard appears.
5. Use the virtual keyboard to enter the password—the password is case sensitive. Ensure that you include dashes where necessary.

After you have entered a valid passcode, the Password Upgrade screen reappears with a message that the upgrade was successful. If you have entered an incorrect password, an error message appears and you are returned to the Unlock/Upgrade screen.

After you have unlocked RangePoint RTX, set the correction type to RangePoint RTX:

1. In the *Settings* screen, tap **GPS**. The *GPS* screen appears.
2. Tap **GPS Setup** and then tap **RTK**. The *GPS Correction Source* screen appears:



3. In the *Frequency* tab, the frequency and baud rate are pre-selected for the US Central beam. If necessary, these values can be changed manually to track a specific Lband satellite.

4. Tap **RangePoint RTX**. The *RangePoint RTX Setup* wizard appears. Read all cautions and warnings carefully. Select the appropriate settings:

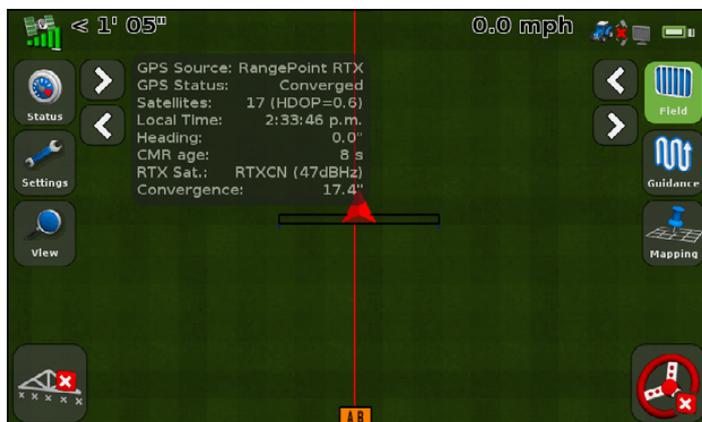
Option	Description
Position Quality	<p>This screen provides options that enable you to operate when the quality of GPS position information is comprised.</p> <ul style="list-style-type: none"> • Favor Accuracy - Provides the highest level of accuracy. This is the recommended setting. • Balanced Quality - Trades potential accuracy for a slight increase in production time. • Favor Availability - Extends production time further, with more potential for reduced accuracy.

5. After the wizard has been completed, return to the Run screen.

Notes:

- *GPS Source is RangePoint RTX.*
- *Convergence is a high value.*
- *The satellite icon is yellow, indicating the system is not ready to operate.*

The status values will change while the receiver converges to its final accuracy:



Notes:

- *Convergence takes place in less than five minutes.*
- *The satellite icon is now green, indicating that the system is now ready to operate.*

Status

Use the *Status* screen to view the current status of the system. The items that appear in the *Status* screen vary according to the features that you use.

Select this item ...	To view ..
Region protect	The GPS signal region you are currently in and whether it is locked or unlocked. If your region is locked, contact your Trimble reseller.
Language Pack status	The language packs that have been installed on the display.
LB25 remote lightbar status	The following information for the lightbar: <ul style="list-style-type: none"> • Status: <i>Connected</i> or <i>Disconnected</i> • Serial number • Firmware version
EZ-Remote status	The following information for the EZ-Remote: <ul style="list-style-type: none"> • Status: <i>Connected</i> or <i>Disconnected</i> • Serial number • Firmware version
System status	The current time and date ID: CFX-750 The following data about your CFX-750 display: <ul style="list-style-type: none"> • Version and Version date • Serial number • Part number • Hardware Revision System voltage Temperature Storage: This is the number of hours of coverage logging remaining before the internal memory is full. Operational hours: This is the number of hours that the CFX-750 has been operating.
Upgrade options	The status of optional features and extensions
Fault history	Those faults that have occurred recently (they may not be currently active).

CFX-750 screen

The *CFX-750* screen has two options:

- **About the Display:** Shows information about your CFX-750 display, including the current version and the serial number.
- **Restore Defaults:** Restores the display defaults to clear all of your current settings. If you choose to restore the default settings, the display and lightbar will restart.

Recalibrate touchscreen

The first time you power on the display, you must calibrate the touchscreen. See [Power up, page 25](#).

If the current calibration does not read your selections accurately, use the *Recalibrate Touchscreen* option to adjust the responsiveness of the touchscreen.

Alternatively, do the following:

1. Power off the display and then power it on.
2. Wait until the status bar at the bottom of the second startup screen is more than half full:



3. Press **both** brightness control buttons at the same time:



4. Hold the two buttons down until the display beeps.